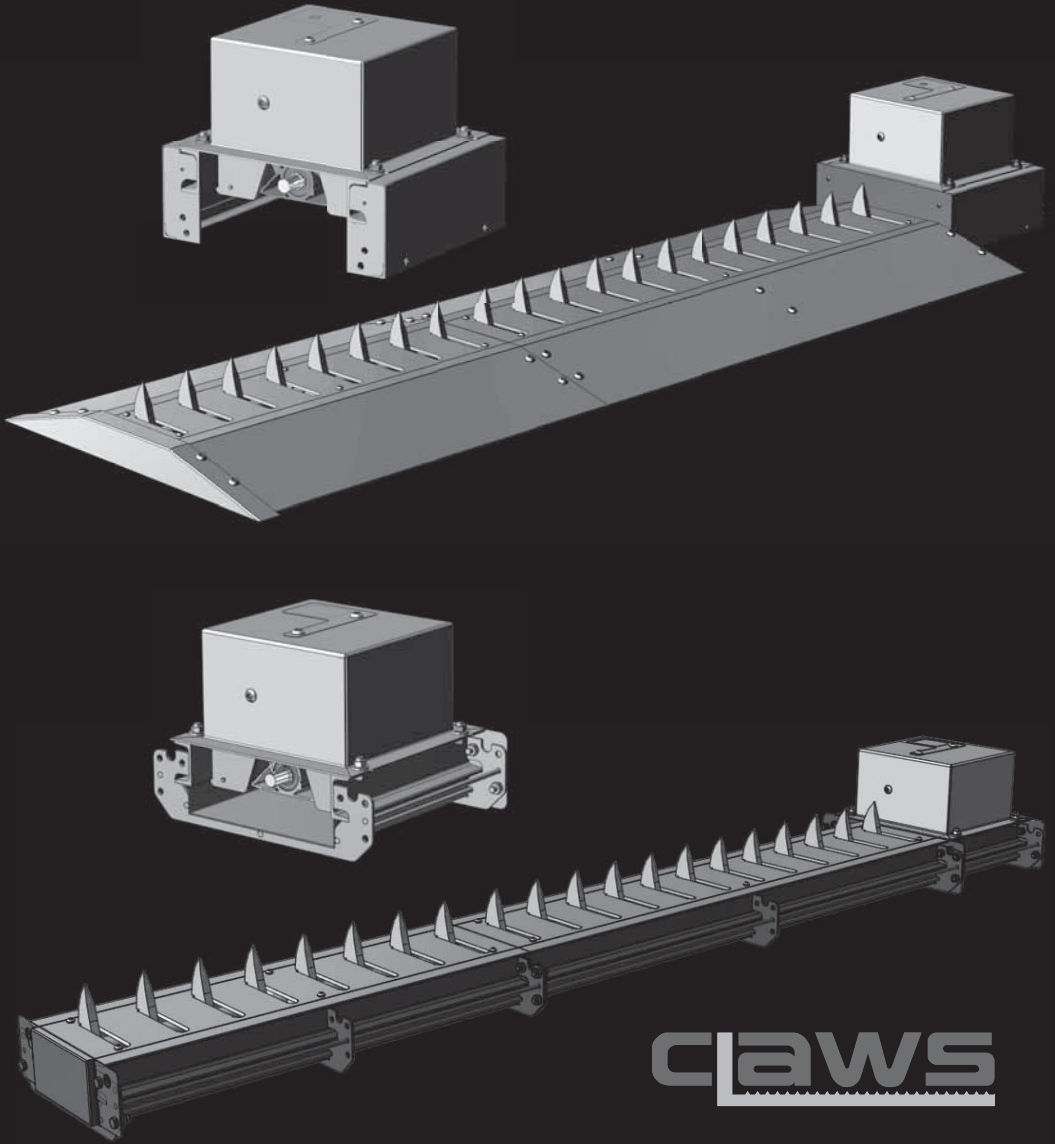


CLAWS - Independent Drive Installation manual



claws



Company profile



1986

1990

1995

1999

Today

In-house R&D development team

Manufactures to international quality standard ISO 9001:2008



After-sales multi-language Technical Support

**Monday to Friday from 07h00 to 18h00 GMT+2
Saturdays 08h00 to 16h30 GMT +2**

100% testing of products



Sales and technical support to Africa, Europe, Asia, the Americas, Australia and the Pacific

Centurion Systems (Pty) Ltd reserves the right to make changes to the products described in this manual without notice and without obligation to notify any persons of any such revisions or changes. Additionally, **Centurion Systems (Pty) Ltd** makes no representations or warranties with respect to this manual. No part of this document may be copied, stored in a retrieval system or transmitted in any form or by any means electronic, mechanical, optical or photographic, without the express prior written consent of **Centurion Systems (Pty) Ltd**.



Contents

**SAFETY
FIRST**
IMPORTANT SAFETY INSTRUCTIONS

page 6

1. General Description	page 8
Surface Mount Installations	page 9
2. Product Identification	page 10
3. Tools Required	page 11
4. Introduction	page 12
4.1. Installation Configurations	page 12
4.1.1. Orientation of Installation	page 12
4.1.2. Spike Impact Direction	page 13
5. RHS Surface Mount - Similar Direction of Travel	page 15
5.1. Preparing the Drive Linkage Assembly	page 15
5.2. Spike Module Assembly	page 16
5.3. Re-assembling the Ramp Plates and Linkage Cover	page 25
5.4. Integrating the SECTOR II with the CLAWS	page 27
6. RHS Surface Mount - Opposing Direction of Travel	page 35
6.1. Preparing the Drive Linkage Assembly	page 35
6.2. Spike Module Assembly	page 36
6.3. Re-assembling the Ramp Plates and Linkage Cover	page 45
6.4. Integrating the SECTOR II with the CLAWS	page 47
7. LHS Surface Mount - Similar Direction of Travel	page 55
7.1. Preparing the Drive Linkage Assembly	page 55
7.2. Spike Module Assembly	page 56
7.3. Re-assembling the Ramp Plates and Linkage Cover	page 65
7.4. Integrating the SECTOR II with the CLAWS	page 67

8.	LHS Surface Mount - Opposing Direction of Travel	page 75
8.1.	Preparing the Drive Linkage Assembly	page 75
8.2.	Spike Module Assembly	page 76
8.3.	Re-assembling the Ramp Plates and Linkage Cover	page 85
8.4.	Integrating the SECTOR II with the CLAWS	page 87
	Flush Mount Installations	page 95
9.	Product Identification	page 96
10.	Tools Required	page 97
11.	Introduction	page 98
11.1.	Installation Configurations	page 98
11.1.1.	Orientation of Installation	page 98
11.1.2.	Spike Impact Direction	page 99
12.	RHS Flush Mount - Similar Direction of Travel	page 101
12.1.	Preparing the Drive Linkage Assembly	page 101
12.2.	Spike Module Assembly	page 102
12.3.	Preparing the Trench and Drainage System	page 111
12.4.	Re-assembling the Trench Plates	page 112
12.5.	Integrating the SECTOR II with the CLAWS	page 113
12.5.1.	Directly Mount the SECTOR II onto the Independent Drive	page 113
12.5.2.	Separately-placed CLAWS and SECTOR II	page 115
13.	RHS Flush Mount - Opposing Direction of Travel	page 123
13.1.	Preparing the Drive Linkage Assembly	page 123
13.2.	Spike Module Assembly	page 124
13.3.	Preparing the Trench and Drainage System	page 133
13.4.	Re-assembling the Trench Plates	page 134
13.5.	Integrating the SECTOR II with the CLAWS	page 135
13.5.1.	Directly Mount the SECTOR II onto the Independent Drive	page 135
13.5.2.	Separately-placed CLAWS and SECTOR II	page 137

14. LHS Flush Mount - Similar Direction of Travel	page 145
14.1. Preparing the Drive Linkage Assembly	page 145
14.2. Spike Module Assembly	page 146
14.3. Preparing the Trench and Drainage System	page 155
14.4. Re-assembling the Trench Plates	page 156
14.5. Integrating the SECTOR II with the CLAWS	page 157
14.5.1. Directly Mount the SECTOR II onto the Independent Drive	page 157
14.5.2. Separately-placed CLAWS and SECTOR II	page 159
15. LHS Flush mount - Similar Direction of Travel	page 167
15.1. Preparing the Drive Linkage Assembly	page 167
15.2. Spike Module Assembly	page 168
15.3. Preparing the Trench and Drainage System	page 177
15.4. Re-assembling the Trench Plates	page 178
15.5. Integrating the SECTOR II with the CLAWS	page 179
15.5.1. Directly Mount the SECTOR II onto the Independent Drive	page 179
15.5.2. Separately-placed CLAWS and SECTOR II	page 181
16. Wiring Diagram	page 188
17. SECTOR II & CLAWS Controller Settings	page 189
18. Installation Handover	page 190

Icons used in this manual



This icon indicates tips and other information that could be useful during the installation.



This icon denotes variations and other aspects that should be considered during installation.



This icon indicates warning, caution or attention! Please take special note of critical aspects that MUST be adhered to in order to prevent injury.



This icon indicates areas where mechanical crushing may occur.

IMPORTANT SAFETY INSTRUCTIONS

ATTENTION

To ensure the safety of people and possessions, it is important that you read all the following instructions.

Incorrect installation or incorrect use of the product may cause serious harm to people and / or property.



The installer, being either professional or DIY, is the last person on the site who can ensure that the operator is safely installed, and that the whole system can be operated safely.

Warnings for the installer

CAREFULLY READ AND FOLLOW ALL INSTRUCTIONS before beginning to install the product.

- All installation, repair, and service work to this product must be done by a suitably qualified person
- Do not activate the **CLAWS** unless you can see them and can determine that the **CLAWS** are clear of people, pets, vehicles or any obstructions
- Nothing must be placed, and nobody must be near the trench covers at any time. Always keep people and objects away from the spikes' area of travel
- Children should be supervised to ensure that they do not play with or around the spikes and trench cover
- This device is not intended for use by persons (including children) with reduced physical, sensory or mental capabilities, or lack of experience and knowledge, unless they have been given supervision or instruction concerning use of the appliance by a person responsible for their safety
- Secure all easily-accessed **CLAWS** controls in order to prevent unauthorised use
- Do not in any way modify the components of the automated system
- Do not install the equipment in an explosive atmosphere. The presence of flammable gas or fumes is a serious danger to safety
- Before attempting any work on the system, cut electrical power and disconnect the batteries
- The mains power supply of the automated system must be fitted with an all-pole switch with contact opening distance of 3mm or greater. Use of a 5A thermal breaker with all-pole circuit break is recommended
- Make sure that an earth leakage circuit breaker with a threshold of 30mA is fitted upstream of the system
- Never short-circuit the battery and do not try to recharge the batteries with power supply units other than that supplied with the product, or manufactured by Centurion Systems (Pty) Ltd

- Make sure that the earthing system is correctly constructed, and that all metal parts of the system are suitably earthed
- Safety devices must be fitted to the installation to guard against mechanical movement risks such as crushing, dragging and shearing
- It is recommended that at least one warning indicator light be fitted to every system
- Always fit a warning sign visibly to the inside and outside of the entrance and exit
- The installer must explain and demonstrate the manual operation of the system in case of an emergency, and must hand the User Guide and Safety Instructions over to the end-user
- Explain these safety instructions to all persons authorised to use the system, and be sure that they understand the hazards associated with the system
- Do not leave packing materials (plastic, polystyrene, etc.) within reach of children as such materials are potential sources of danger
- Dispose of all waste products like packaging materials, worn-out batteries, etc. according to local regulations
- Always check the obstruction detection system and safety devices for correct operation
- Neither Centurion Systems (Pty) Ltd, nor its subsidiaries, accepts any liability caused by improper use of the product, or for use other than that for which the automated system was intended
- This product was designed and built strictly for the use indicated in this documentation. Any other use, not expressly indicated here, could compromise the service life/operation of the product and/or be a source of danger
- Everything not expressly specified in these instructions is not permitted



1. General Description

CLAWS barrier spikes are designed to enhance the security at the entrance to high-volume application. They provide a formidable deterrent to would-be criminals and due to their robust construction they are very difficult to defeat.

Clever modular design allows the **CLAWS** to be ordered ex-stock and can be configured into a variety of different lengths. The orientation of the spikes can also be easily changed depending on the direction of the traffic flow. Their external limit switches allow for safe operation of the system.

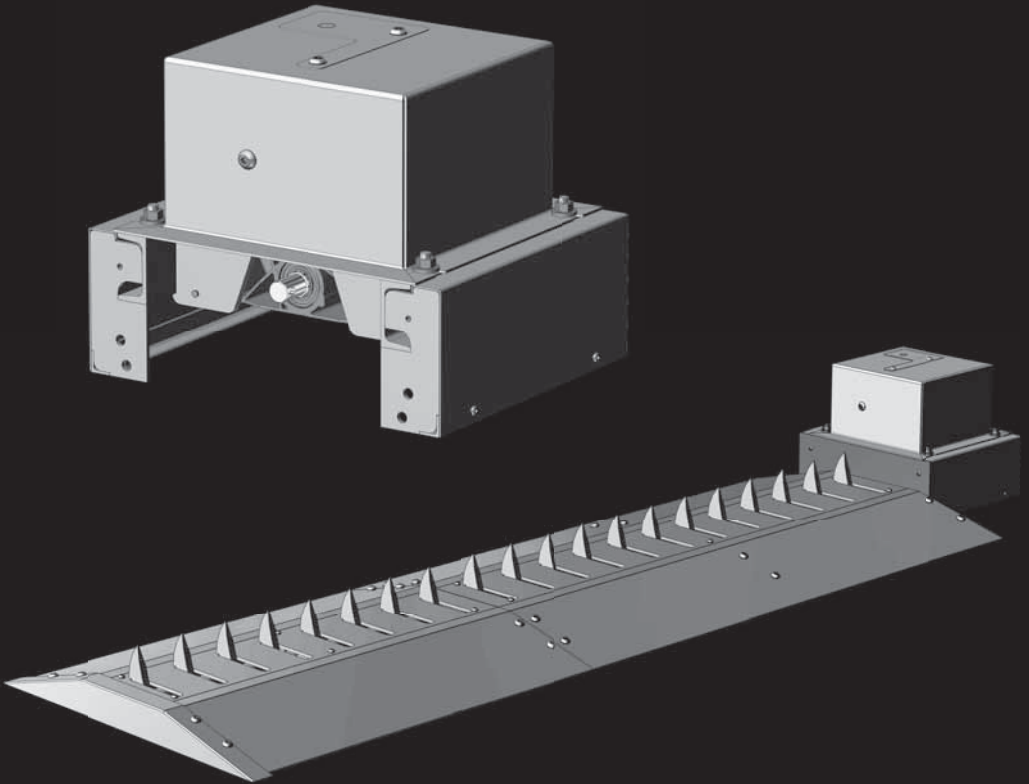
CLAWS are easy to install and use a standard SECTOR controller and a standard SECTOR gearbox, saving you time and reducing your spares inventory. They boast all-weather construction and have been designed to allow for all moving parts to be removed easily for quick and easy maintenance.

CLAWS also provide onboard support for a traffic light interface, and the Independent Drive **CLAWS** models have variable speed control and multiple Modes of Operation. The **CLAWS** Independent Drive system has its own drive mechanism and controller, and can work independently of traffic barriers, etc. It is available in both Flush Mount and Surface Mount variants.

The Flush Mount models are ideal for installations that require seamless access control for smooth-flowing traffic, whereas the Surface Mount models are mounted above the general surface of the roadway and create a traffic-calming bump for a safer access control point.

Independent Drive Surface Mount Installations

claws



2. Product Identification

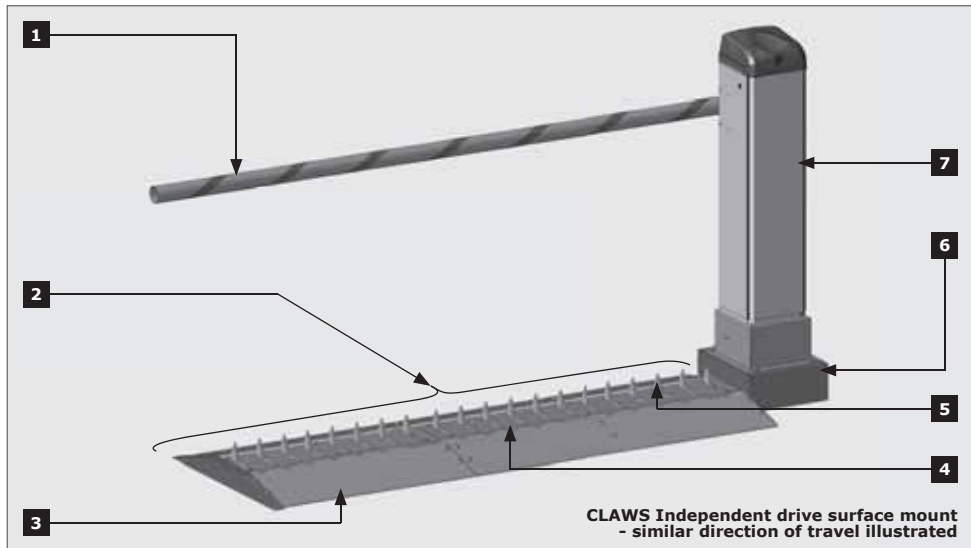










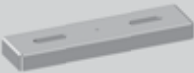






FIGURE 1. PRODUCT IDENTIFICATION

- | | |
|--|--|
| <ul style="list-style-type: none"> 1. Boom pole 2. Spikes module assembly 3. Ramp plates 4. Trench cover plate | <ul style="list-style-type: none"> 5. Spikes 6. Drive linkage assembly 7. SECTOR II |
|--|--|

	Module Frame
	Linkage Frame
	Sandwich Plate
	Top Coupler
	Bottom Coupler
	8x20 Dowel Pin

	Drive Linkage Arm
	Driven Linkage Arm
	Drive Link Pin
	Bearing Housing
	Hold Down Bracket
	Linkage End Cover
	Blanking Plate
	Gearbox Cover
	Module End Cover

3. Tools Required

- 13mm,17mm, and 19mm Spanners
- Ratchet
- 19mm, and 24mm Sockets
- Allen Key Set
- Mallet
- Tape Measure
- Spirit Level
- Torque Wrench

4. Introduction

This document describes the basic steps to follow when installing the surface-mountable **CLAWS** Spikes driven by an independently-powered gearbox. The installation described in this document is a 2.5 meter installation. For other installations, modules of 1.5 or 1.0 meters can be combined to achieve different widths.



The installation of the **CLAWS** Spikes requires a minimum of two persons.

4.1. Installation Configurations

The surface-mountable **CLAWS** Spikes can be installed in four different configurations. The configuration is dependent on two factors:

- Orientation of installation
- Direction of spike impact

4.1.1. Orientation of Installation

The orientation of installation is described as the side at which the drive linkage is installed when approaching the **CLAWS** Spikes. In other words, when driving up to the **CLAWS** Spikes, in the correct direction for traffic flow, and the drive is installed on the right-hand side of the vehicle, it's deemed a right-hand installation. And when driving up to the **CLAWS** Spikes, in the correct direction for traffic flow, and the drive is installed on the left-hand side of the vehicle, it's deemed a left-hand installation.



FIGURE 2. RHS CONFIGURATION



FIGURE 3. LHS CONFIGURATION

4.1.2. Spike Impact Direction

The **CLAWS** Spikes are designed to take a much larger impact in one direction. Thus, the **CLAWS** Spikes can be installed to take larger or more frequent impact in one direction. In other words, the spikes can be installed to face either towards oncoming traffic (similar) or face towards traffic (opposing) trying to enter from the wrong direction or lane (Section 2, Figure 1).

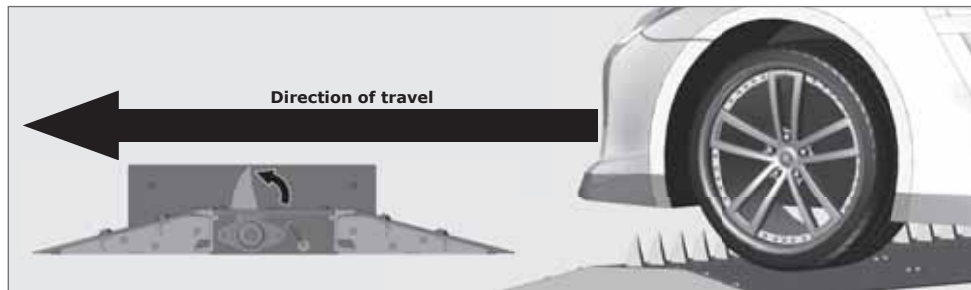


FIGURE 4. SPIKE IMPACT DIRECTION - SIMILAR



FIGURE 5. SPIKE IMPACT DIRECTION - OPPOSING

There are four types of typical installations. Refer to Section 4, Figures 2 and 3 to determine if the installation is left- or right-hand orientated.

Secondly; pay attention to the spike impact direction:

- **Similar direction of travel** prevents vehicles from exiting whilst the boom pole is still down (Normal direction of traffic)
- **Opposing direction of travel** prevents vehicles entering against the flow of traffic whilst the boom pole is down

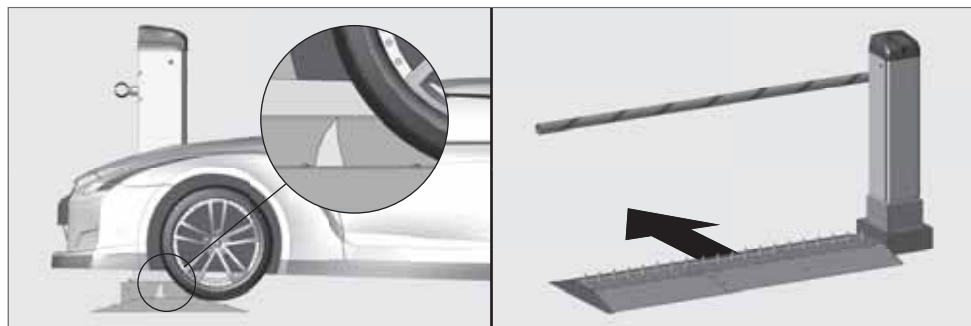


FIGURE 6. RHS SIMILAR DIRECTION OF TRAVEL

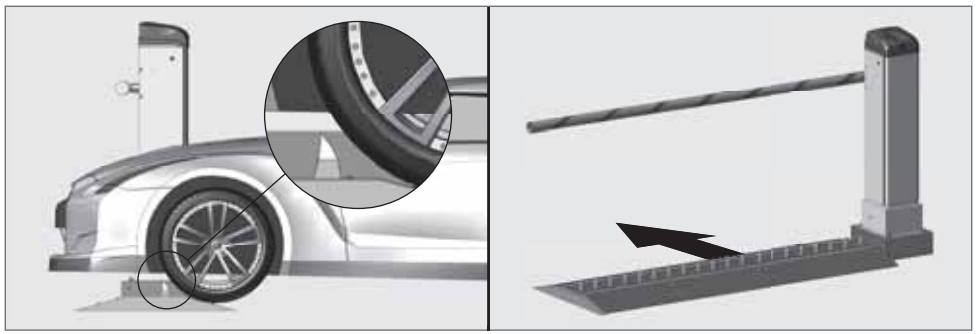


FIGURE 7. RHS OPPOSED DIRECTION OF TRAVEL

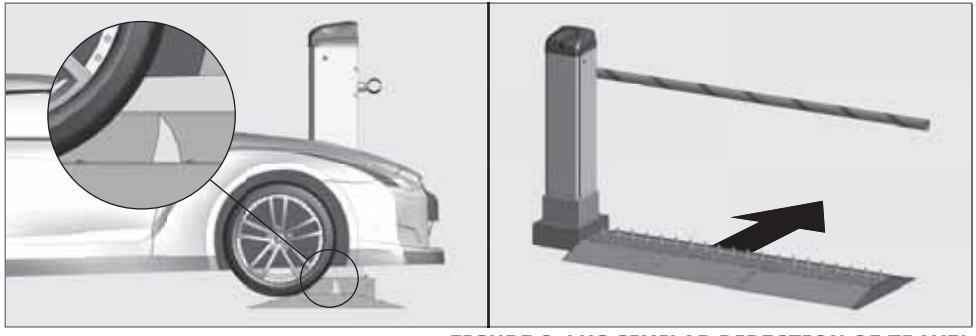


FIGURE 8. LHS SIMILAR DIRECTION OF TRAVEL

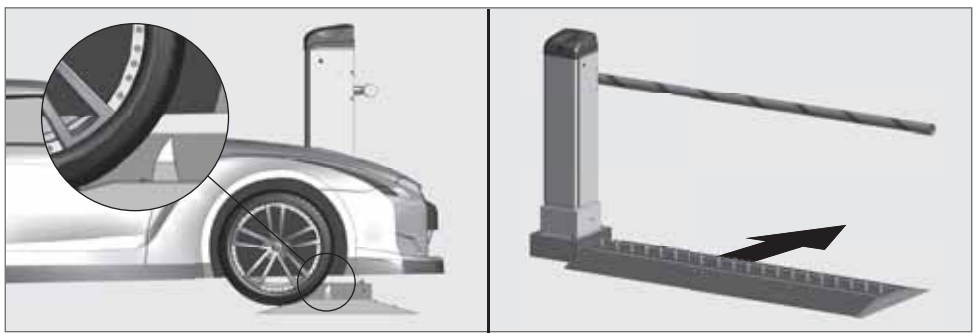
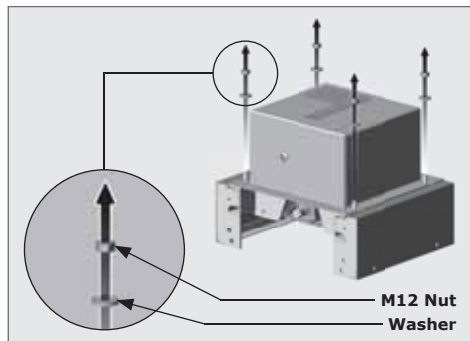


FIGURE 9. LHS OPPOSED DIRECTION OF TRAVEL

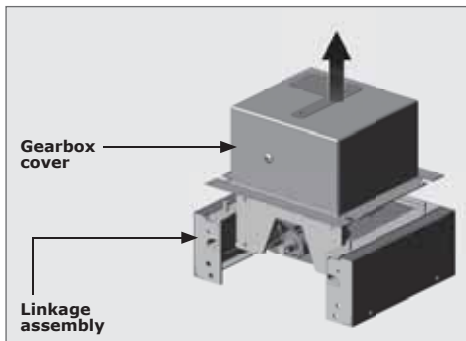
5. RHS Independent Drive Surface Mount - Similar Direction of Travel

5.1. Preparing the Drive Linkage Assembly



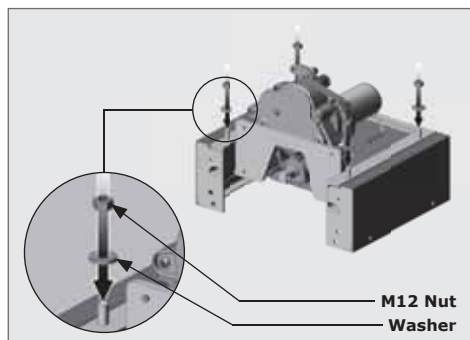
STEP 1

FIGURE 10



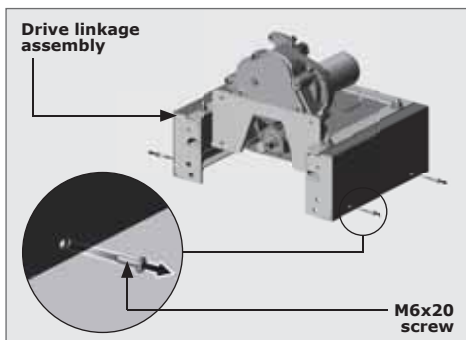
STEP 2

FIGURE 11



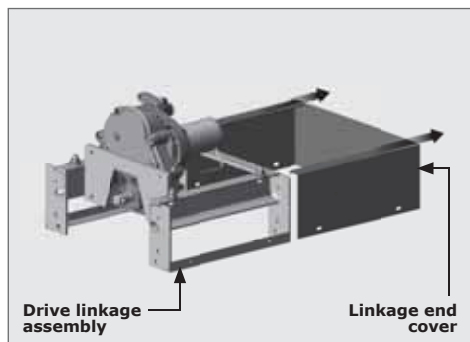
STEP 3

FIGURE 12



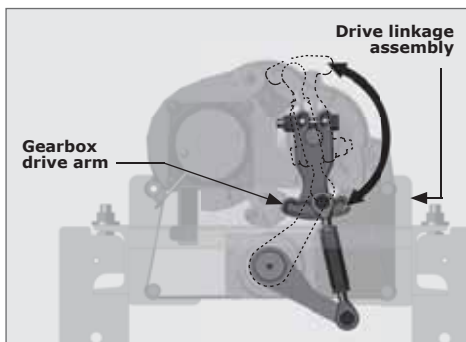
STEP 4

FIGURE 13



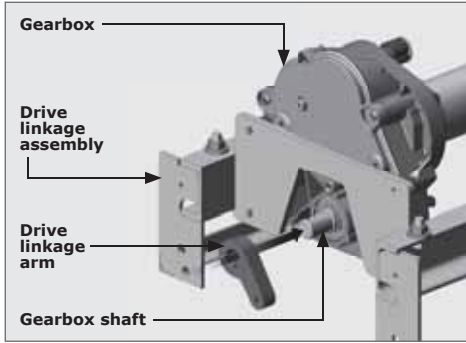
STEP 5

FIGURE 14



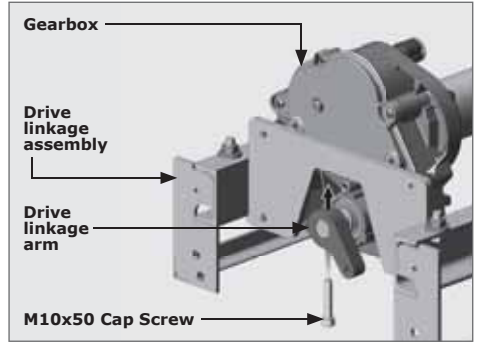
STEP 6

FIGURE 15



STEP 7

FIGURE 16

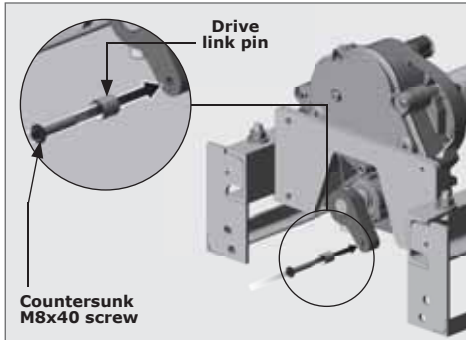


STEP 8

FIGURE 17



The drive linkage arm should point to a 5 o'clock position and the holes of the gearbox shaft and the linkage arm must line up as shown above.



STEP 9

FIGURE 18

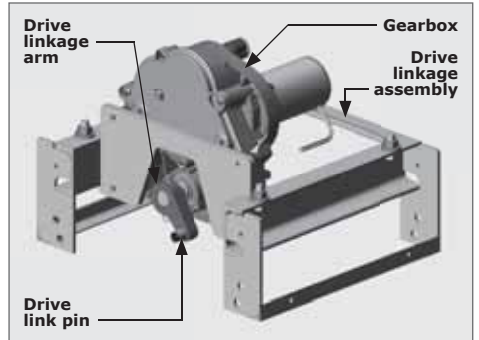


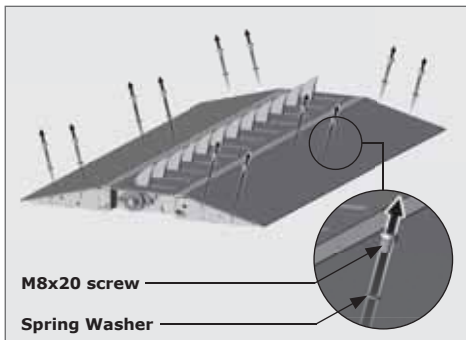
FIGURE 19



Tighten the Countersunk M8x40 screw to 20Nm (Section 5, Figure 18).

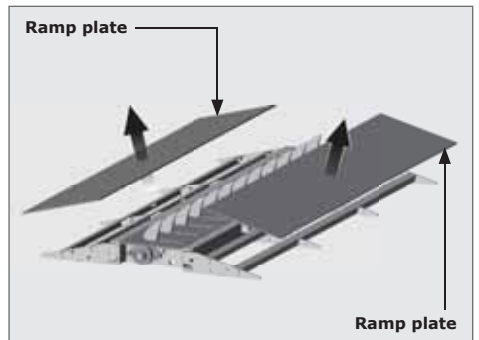
5.2. Spike Module Assembly

5.2.1. Preparing the Spike Model assembly(ies) for installation



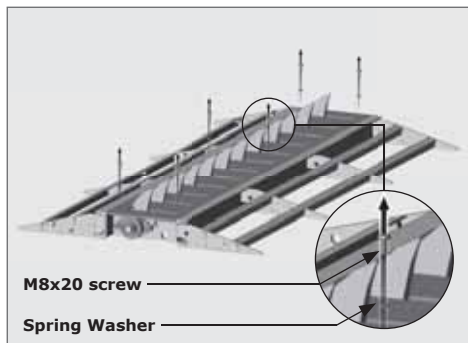
STEP 1

FIGURE 20



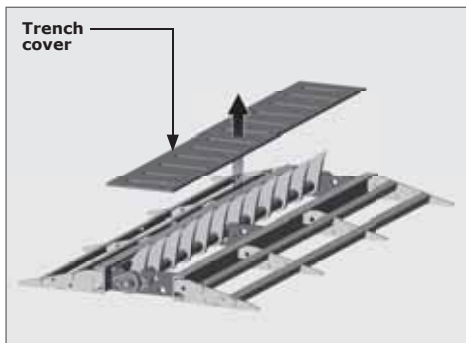
STEP 2

FIGURE 21



STEP 3

FIGURE 22



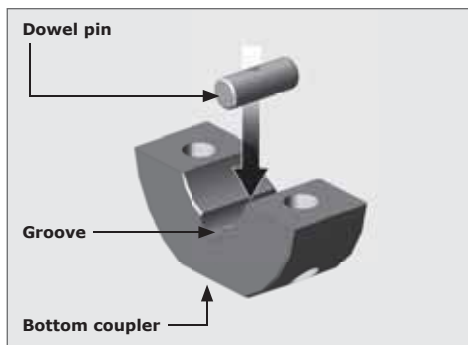
STEP 4

FIGURE 23

5.2.2. Attaching the Driven Link to the first spike module

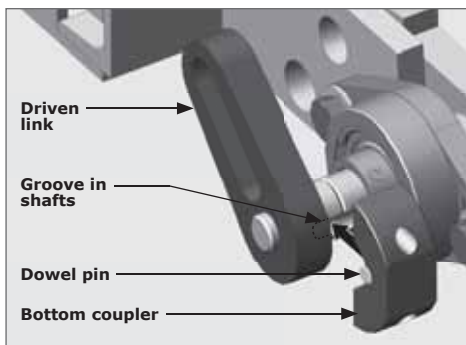


Place the spikes into the down position to aid in the fitment of all the shaft couplings.



STEP 1

FIGURE 24

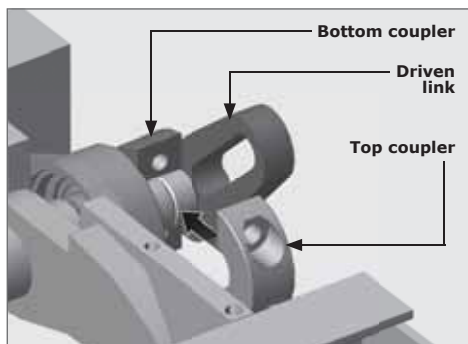


STEP 2

FIGURE 25

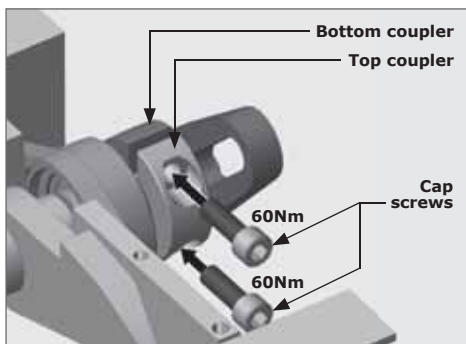


Ensure the Driven Link and the spikes are pointing in the same direction. (Section 5, Figures 25 to 28).



STEP 3

FIGURE 26



STEP 4

FIGURE 27

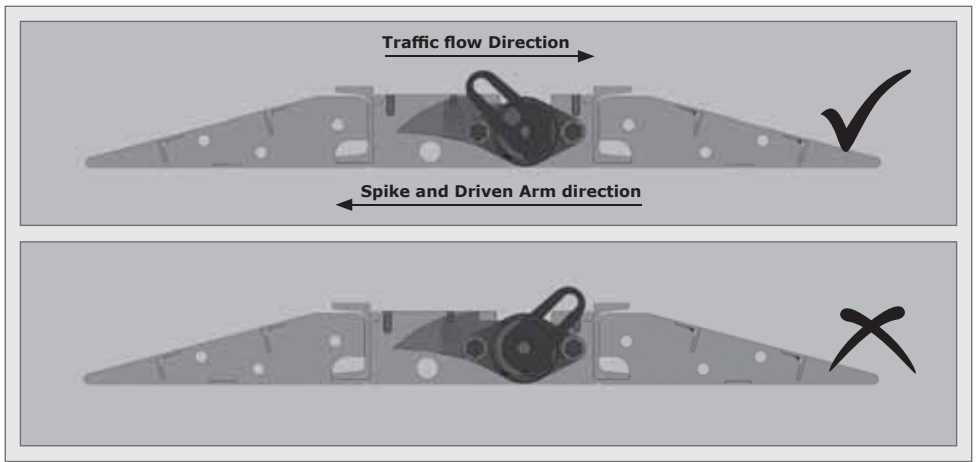


FIGURE 28

5.2.3. Aligning the Driven Linkage Arm to the Drive Linkage Arm.

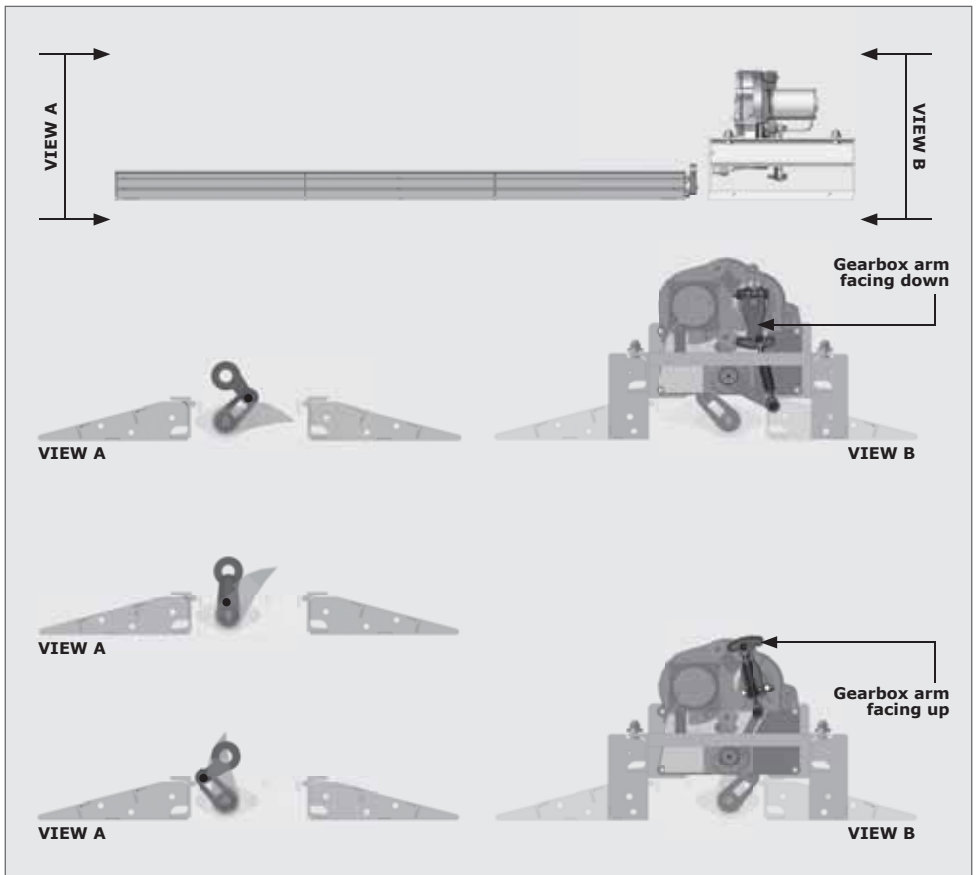
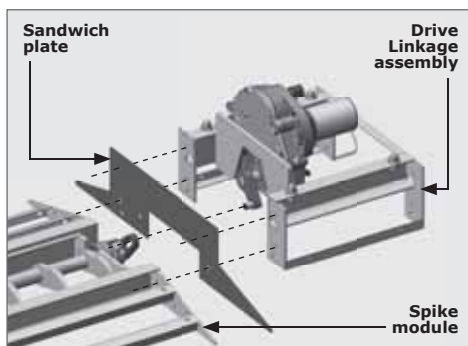


FIGURE 29

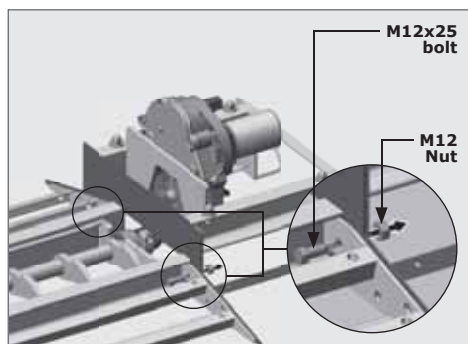
5.2.4. Attaching the drive linkage assembly to the spike module

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly. Ensure that the Sandwich Plate is lifted over the Driven Linkage Arm, so that the Driven Linkage Arm sits flush with the Drive Linkage Arm (Section 5, Figure 30).



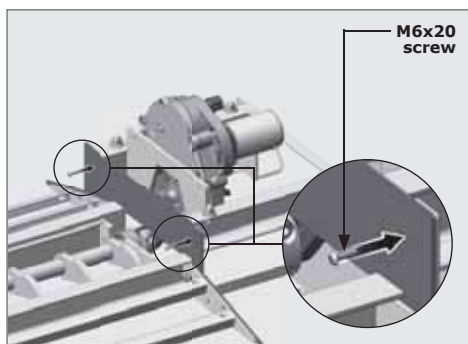
STEP 1

FIGURE 30



STEP 2

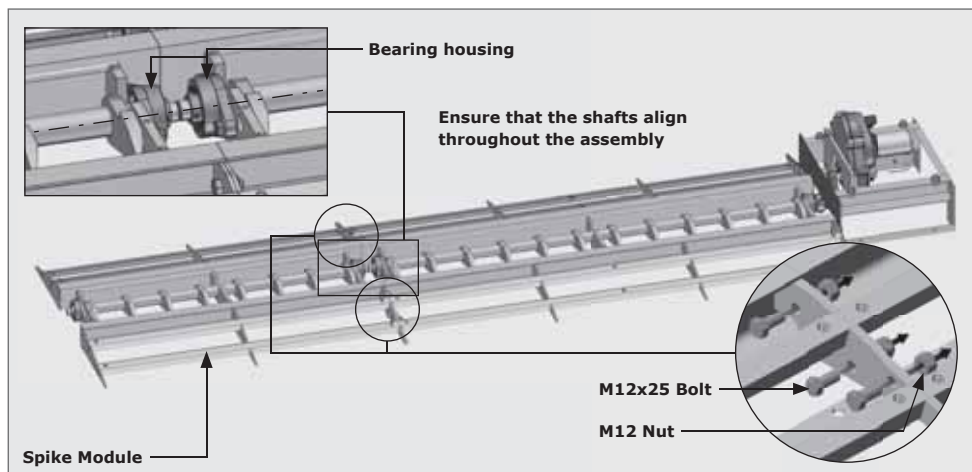
FIGURE 31



STEP 3

FIGURE 32

Using six M12x25 bolts, fix one spike module to another (Section 5, Figure 33).



STEP 4

FIGURE 33



To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

5.2.5. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.



It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.

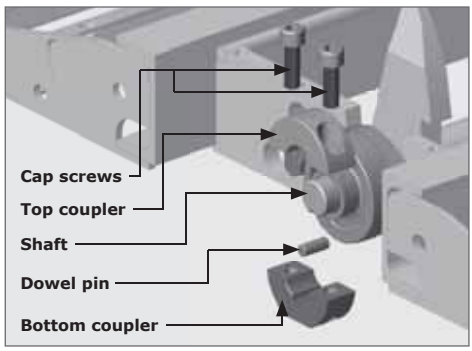


FIGURE 34. SHAFT COUPLER

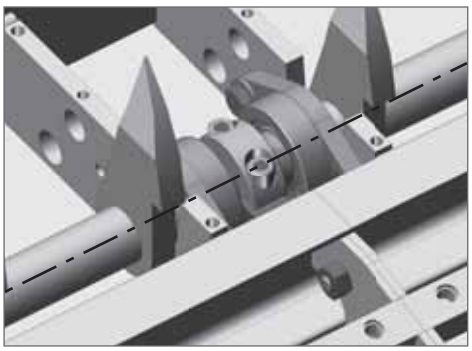
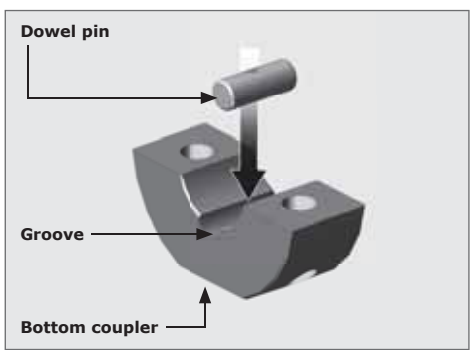


FIGURE 35

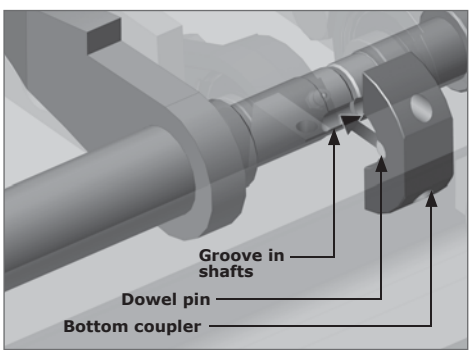


Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.



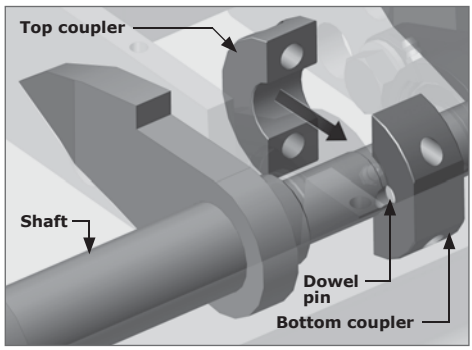
STEP 1

FIGURE 36



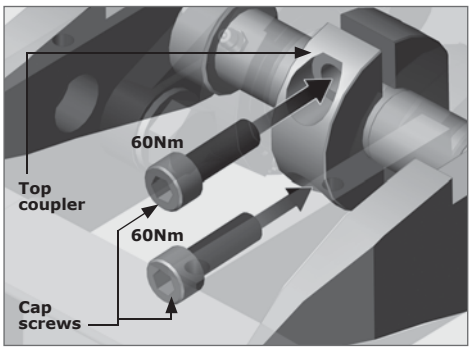
STEP 2

FIGURE 37



STEP 3

FIGURE 38



STEP 4

FIGURE 39

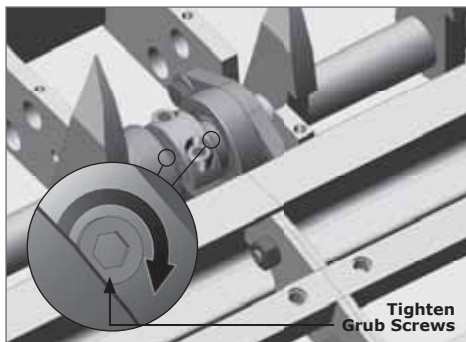
STEP 5

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they rotate freely.



STEP 6

FIGURE 40



STEP 7

Tighten
Grub Screws

FIGURE 41

5.2.6. Bolting down the assembly to the ground

If the SECTOR II and **CLAWS** are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. (Section 5.4.2.) These must be done before bolting the assembly to the ground. Once this preparation work has been completed, proceed with the installation below.

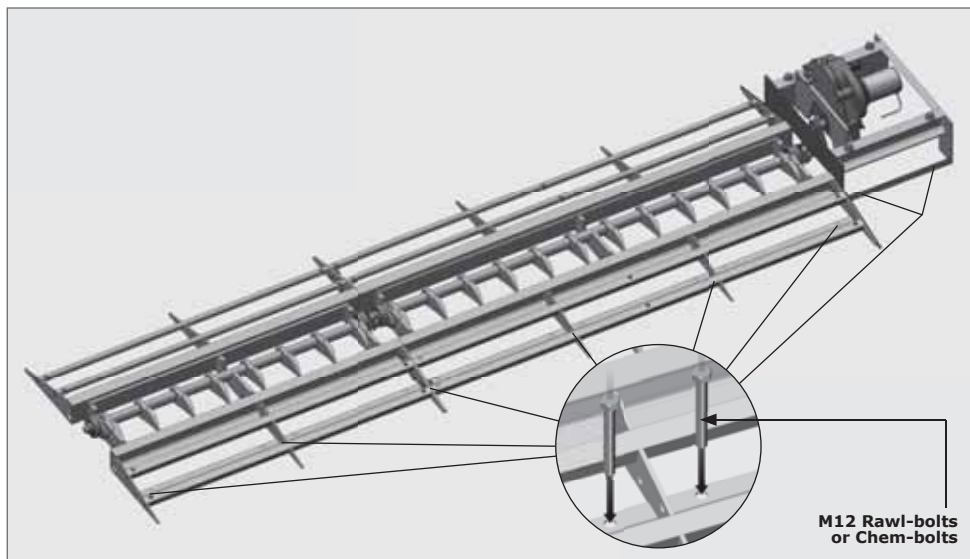
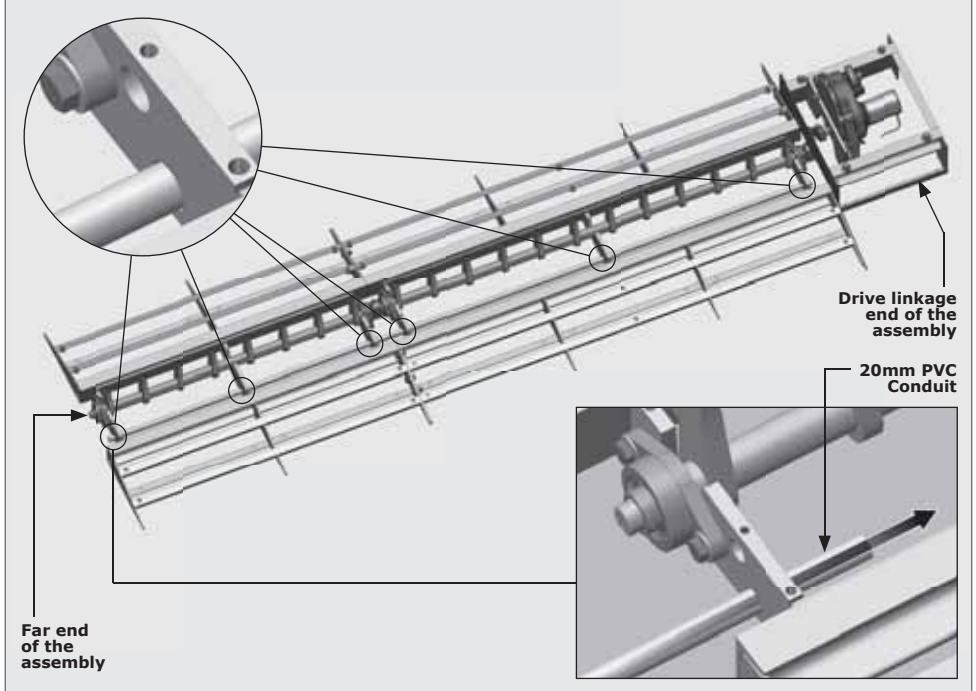
M12 Rawl-bolts
or Chem-bolts

FIGURE 42



It is crucial that the surface it's mounted on is a reasonably even surface as an uneven surface could result in an uneven binding of the spike shafts. This will result in premature failure.

5.2.7. Proximity sensor installation



STEP 1

FIGURE 43



The length of the PVC conduit will be relative to the length of the spike modules and drive linkage unit combined. Ensure that a further 38mm is added to this to account for the modules and coupling (Refer to Section 5, Figure 44).

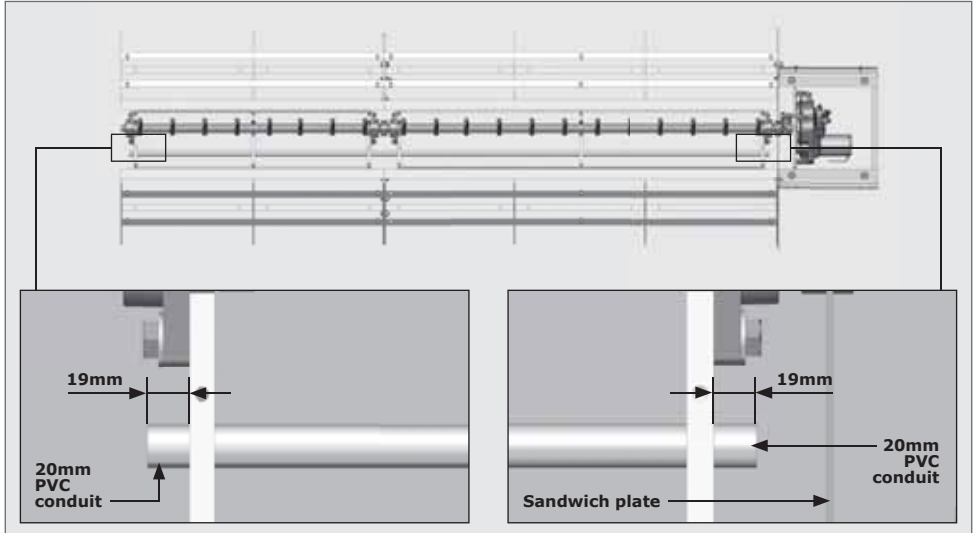
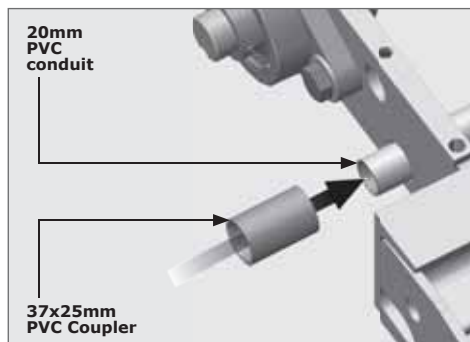


FIGURE 44

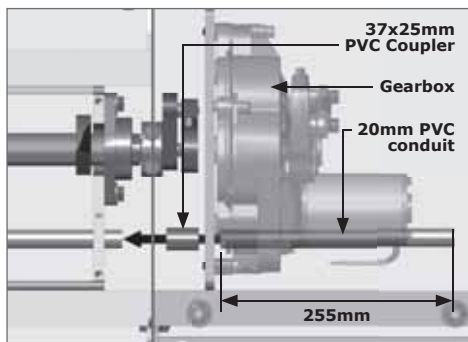


Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.



STEP 2

FIGURE 45

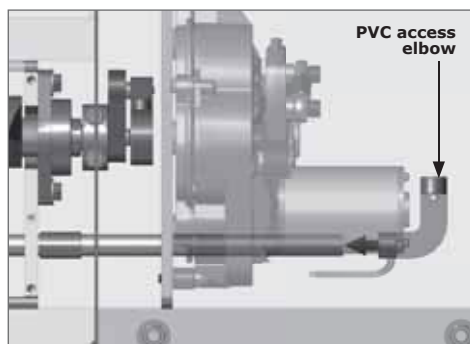


STEP 3

FIGURE 46

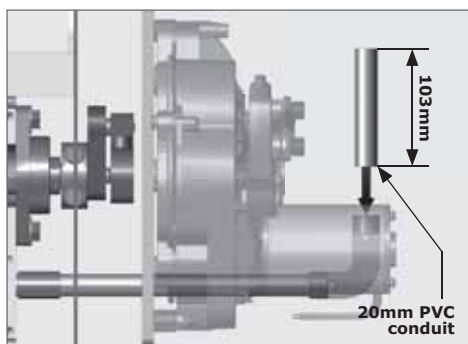


Steps 4-7 is only applicable if the SECTOR II will be mounted directly onto the **CLAWS** Gearbox. If they are going to be mounted separately, a trench for the conduit and proximity sensor cable will need to be dug (Section 5.4.2.).



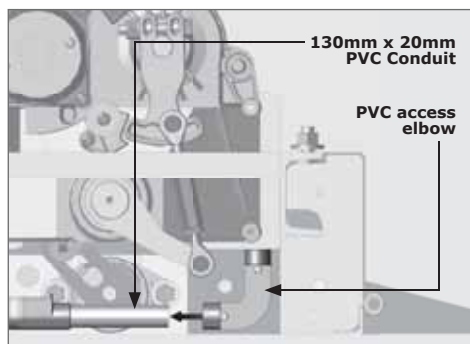
STEP 4

FIGURE 47



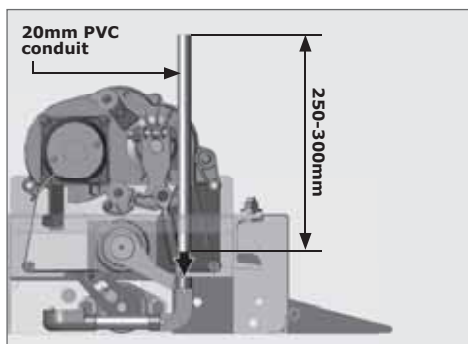
STEP 5

FIGURE 48



STEP 6

FIGURE 49



STEP 7

FIGURE 50



Please ensure that the moving mechanical parts do not rub against the conduit or cables.

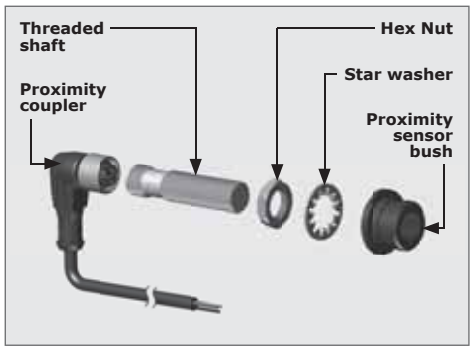


FIGURE 51. PROXIMITY SENSOR

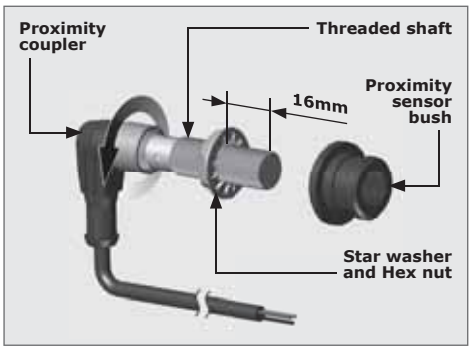


FIGURE 52. PROXIMITY SENSOR

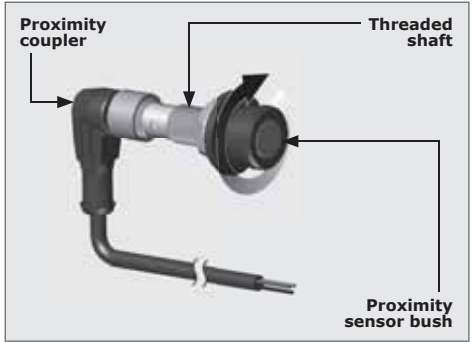
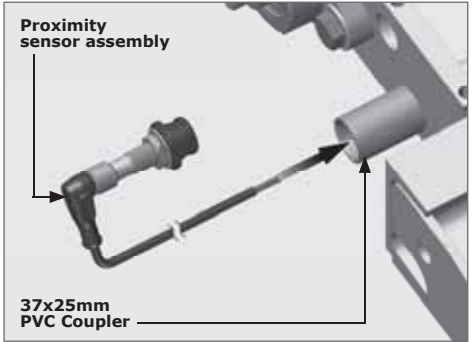


FIGURE 53. PROXIMITY SENSOR



STEP 8 FIGURE 54

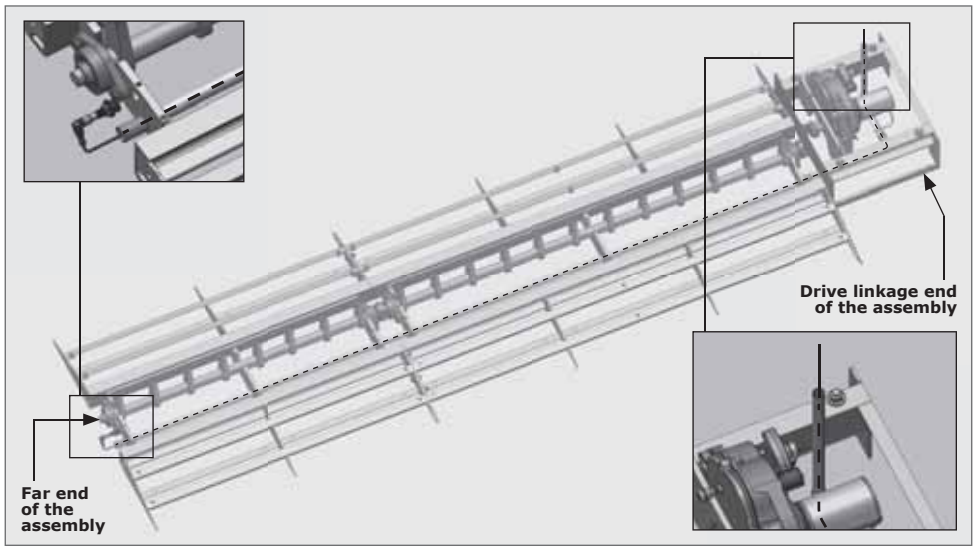
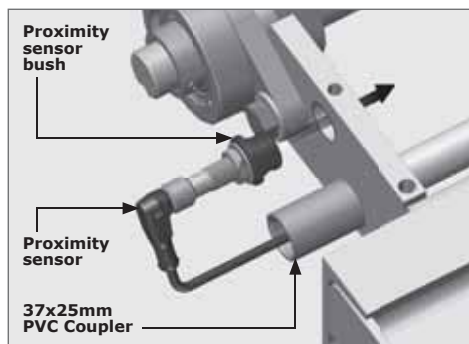


FIGURE 55

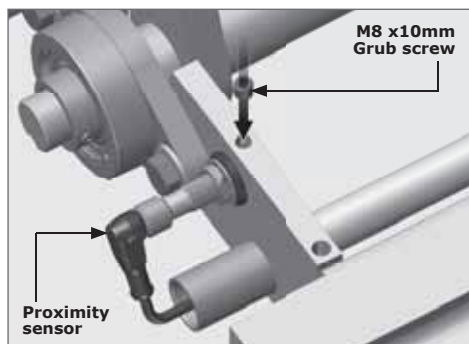


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed to the SECTOR II at a later stage.



STEP 9

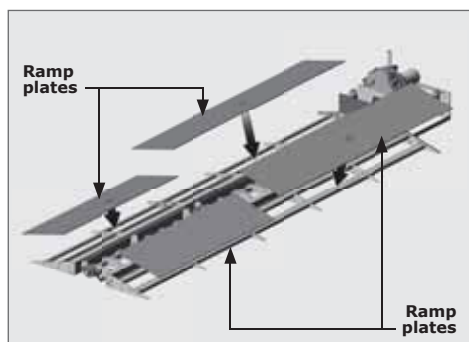
FIGURE 56



STEP 10

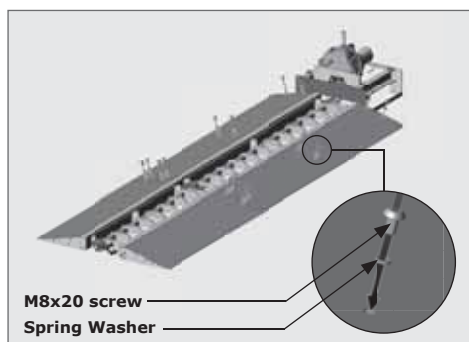
FIGURE 57

5.3. Re-assembling the ramp plates and linkage cover



STEP 1

FIGURE 58

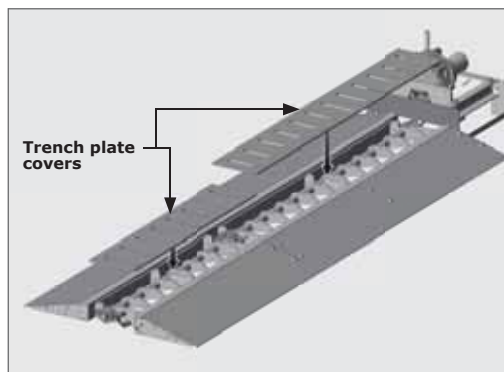


STEP 2

FIGURE 59

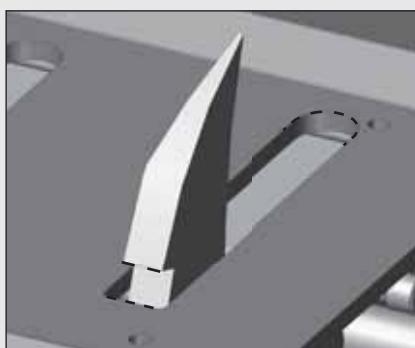


Leave out the four M8 screws and Spring Washers on the far end of the assembly as the module end cover will be assembled later.

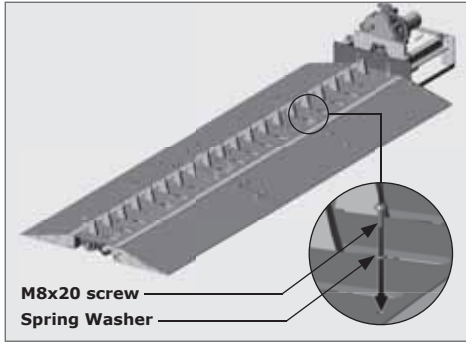


STEP 3

FIGURE 60

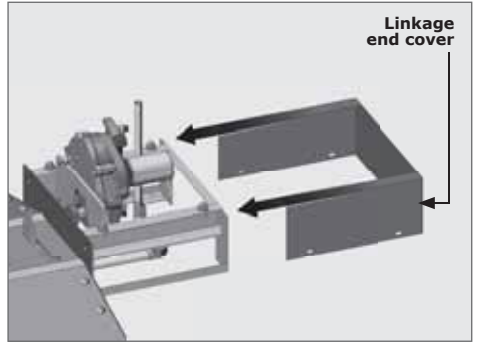


Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.



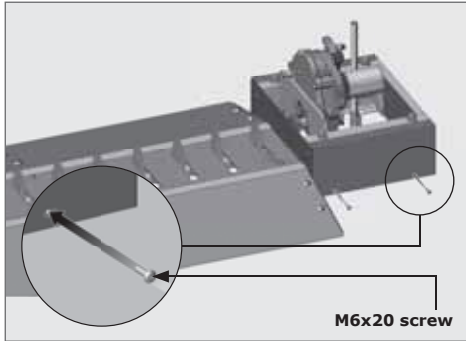
STEP 4

FIGURE 61



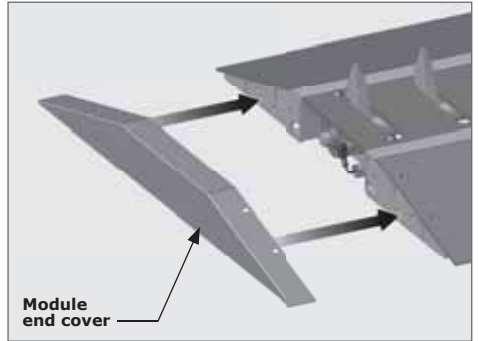
STEP 5

FIGURE 62



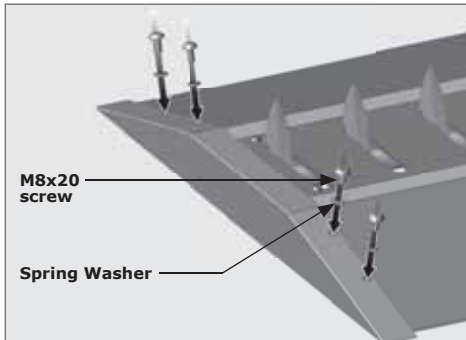
STEP 6

FIGURE 63



STEP 7

FIGURE 64



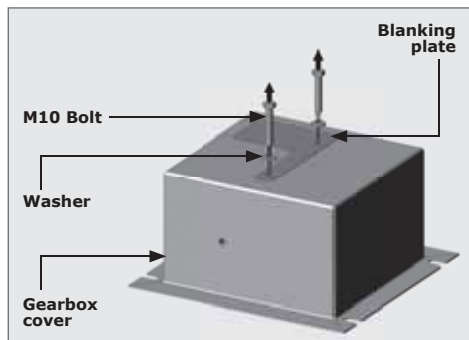
STEP 8

FIGURE 65

5.4. Integrating the SECTOR II with the CLAWS

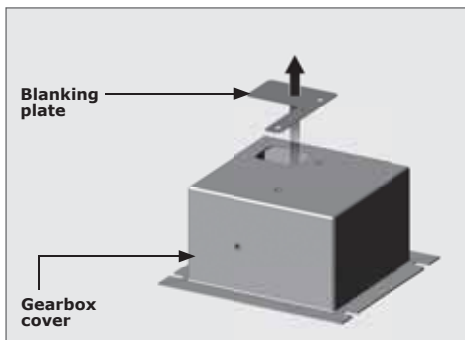
5.4.1. Directly mount THE SECTOR II onto the Independent Drive

5.4.1.1. Placing the gearbox cover into position



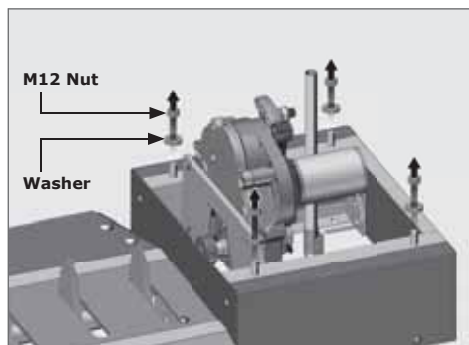
STEP 1

FIGURE 66



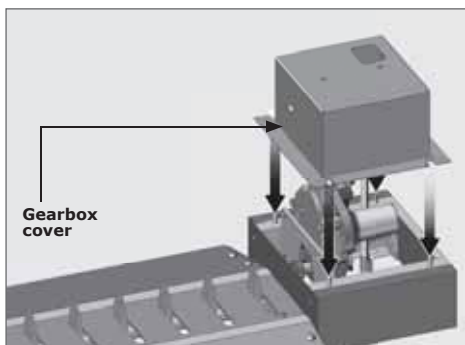
STEP 2

FIGURE 67



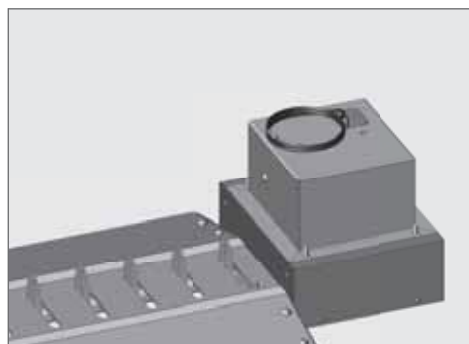
STEP 3

FIGURE 68



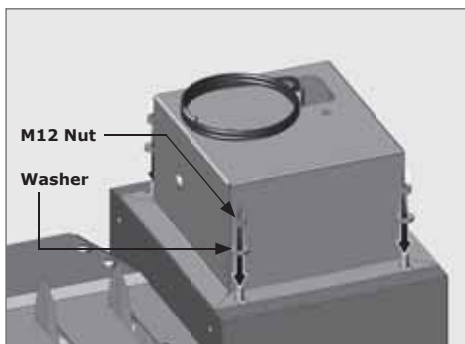
STEP 4

FIGURE 69



STEP 5

FIGURE 70



STEP 6

FIGURE 71

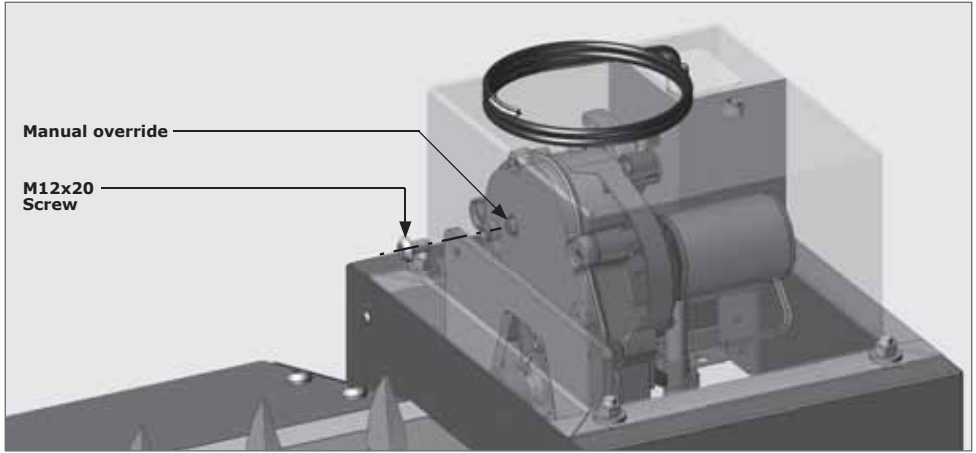
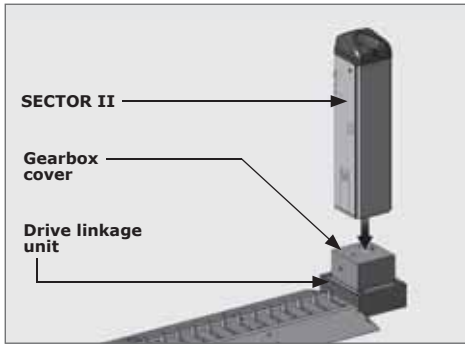
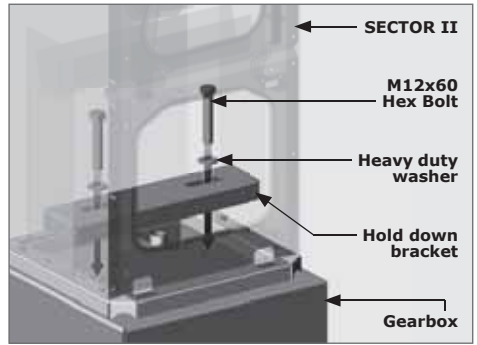


FIGURE 72. MANUAL OVERRIDE

5.4.1.2. Placing the SECTOR II into position



STEP 1 FIGURE 73



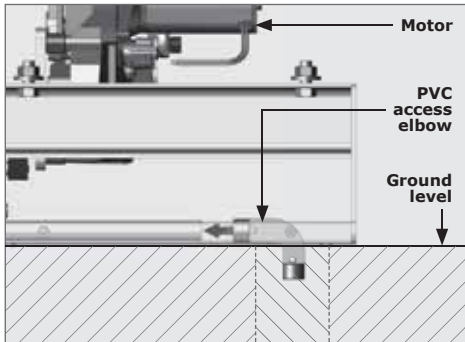
STEP 2 FIGURE 74

5.4.2. Separately-placed CLAWS and SECTOR II

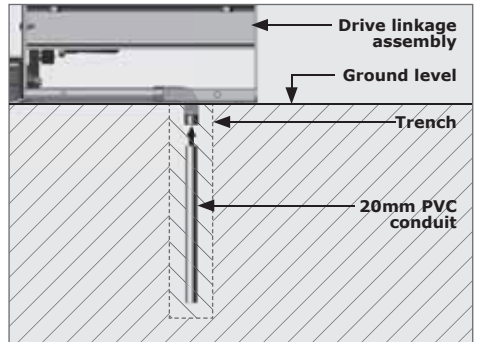
5.4.2.1. Running the conduit from the gearbox to the SECTOR II

STEP 1

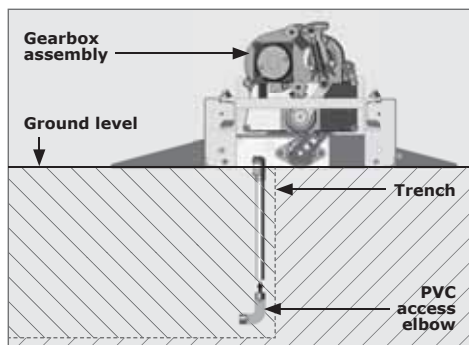
Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.



STEP 2 FIGURE 75

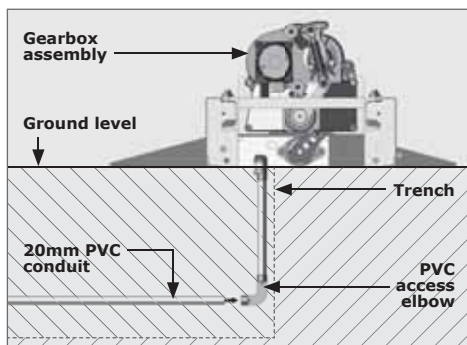


STEP 3 FIGURE 76



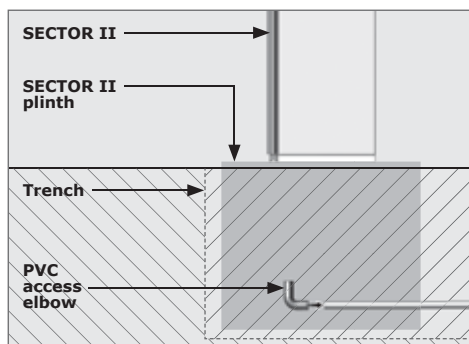
STEP 4

FIGURE 77



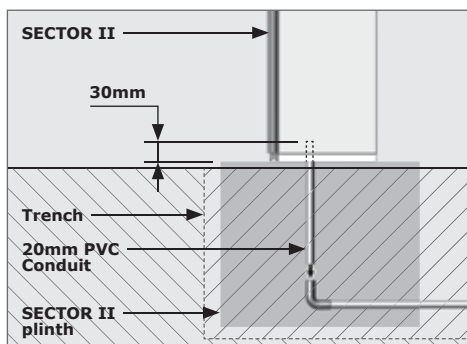
STEP 5

FIGURE 78



STEP 6

FIGURE 79



STEP 7

FIGURE 80

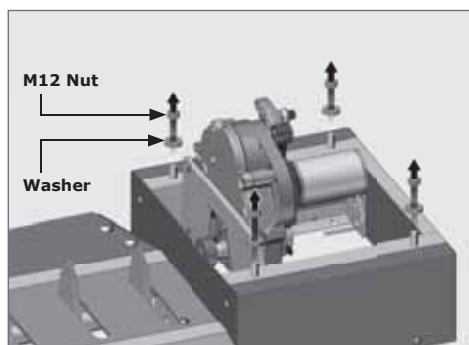
STEP 8

Route the **CLAWS** and Proximity sensor cables in the conduit to the SECTOR II.

STEP 9

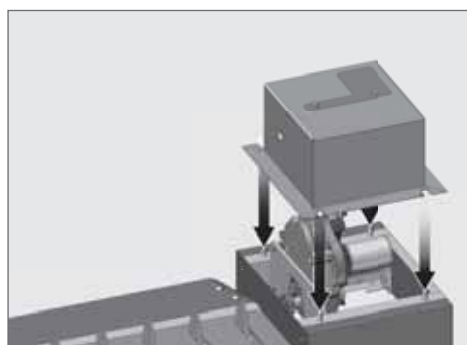
Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

5.4.2.2. Placing the gearbox cover into position



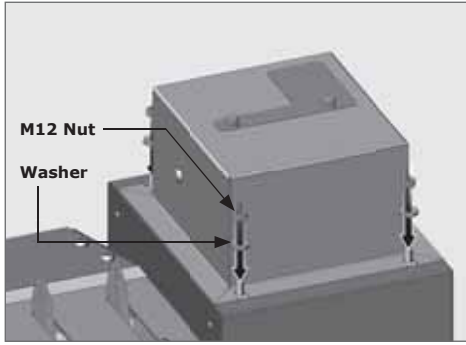
STEP 1

FIGURE 81



STEP 2

FIGURE 82



STEP 3

FIGURE 83

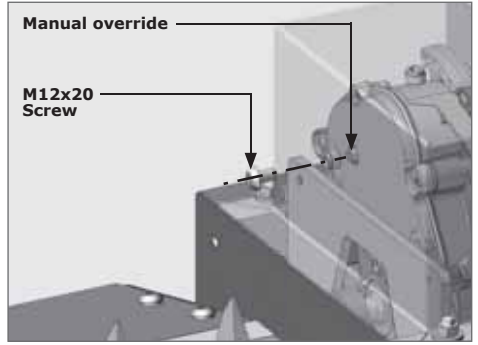
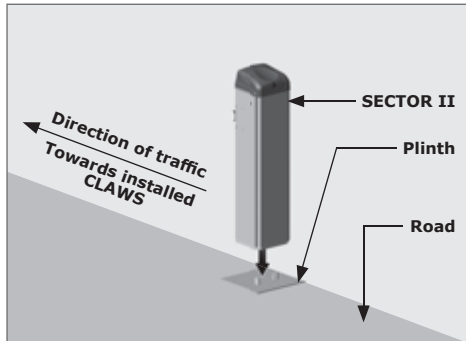


FIGURE 84. MANUAL OVERRIDE



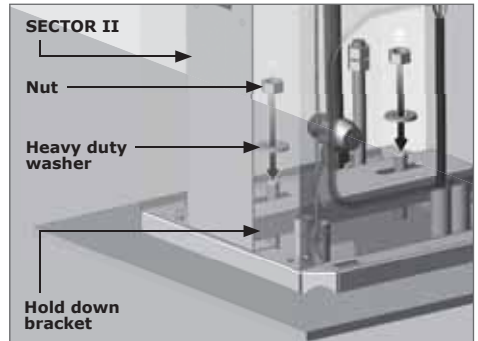
By removing the M12x20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.

5.4.2.3. Placing the SECTOR II into position



STEP 1

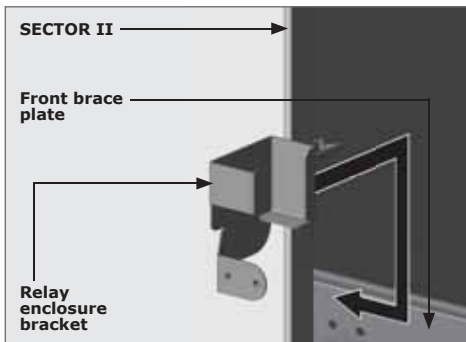
FIGURE 85



STEP 2

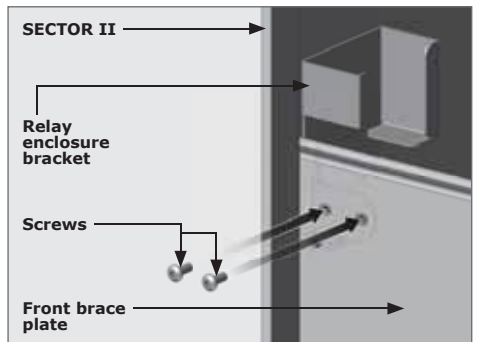
FIGURE 86

5.4.3. Fitting the relay enclosure and its bracket



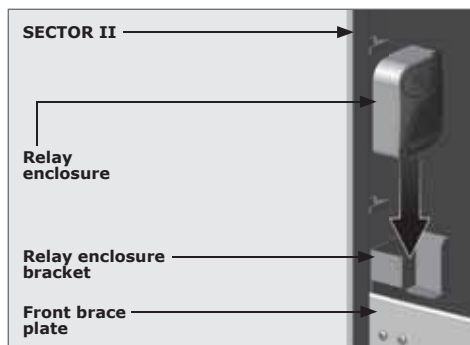
STEP 1

FIGURE 87



STEP 2

FIGURE 88



STEP 1

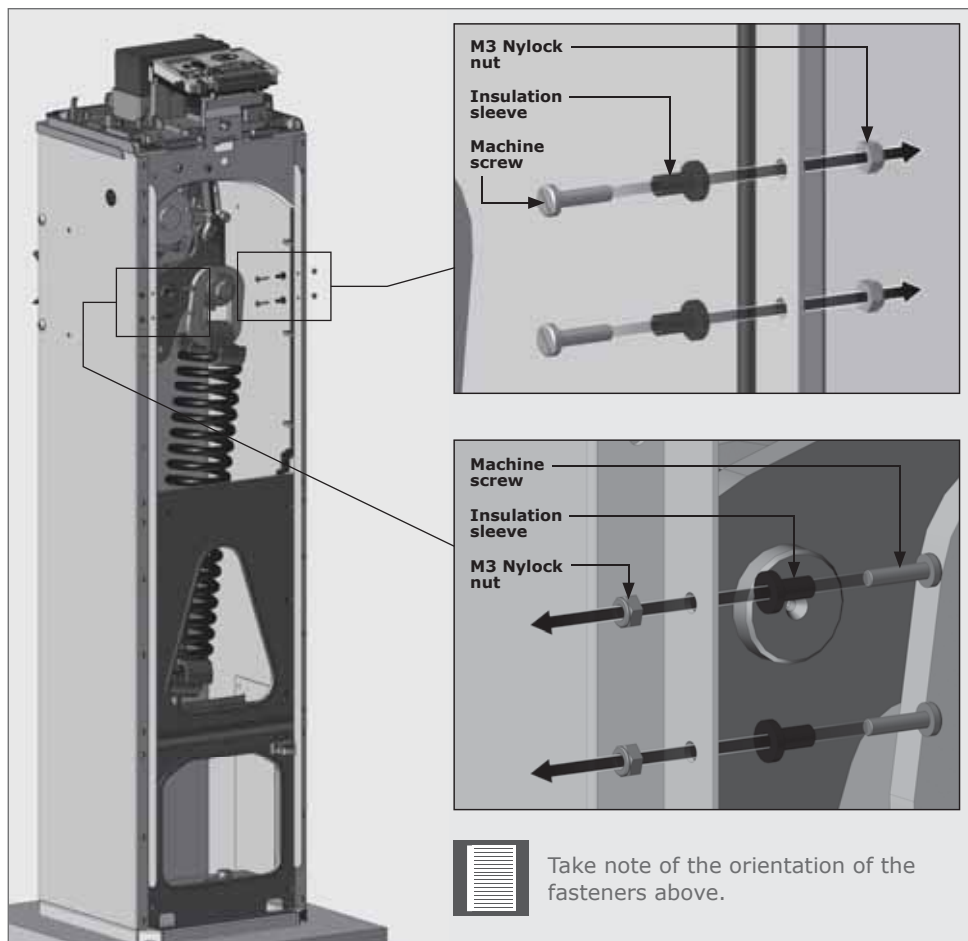
FIGURE 89

Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 16).



Complete the installation of the SECTOR II as per its full installation manual.

5.4.5. Fitting the CLAWS controller to the SECTOR II

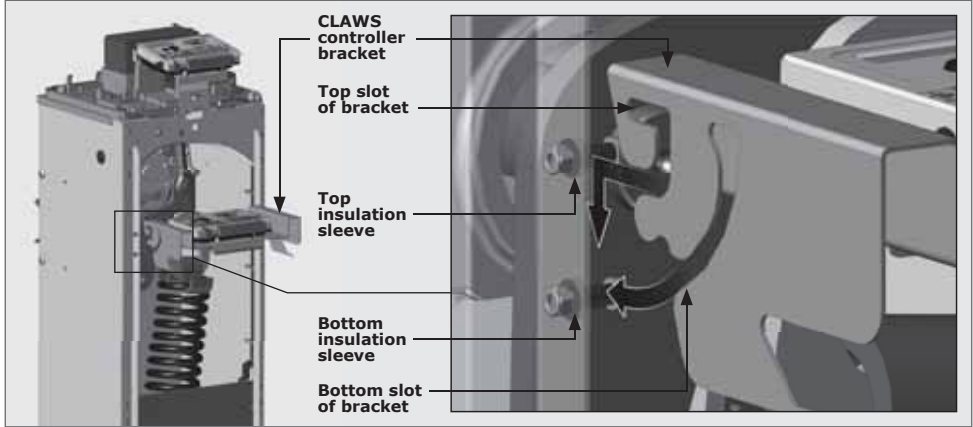
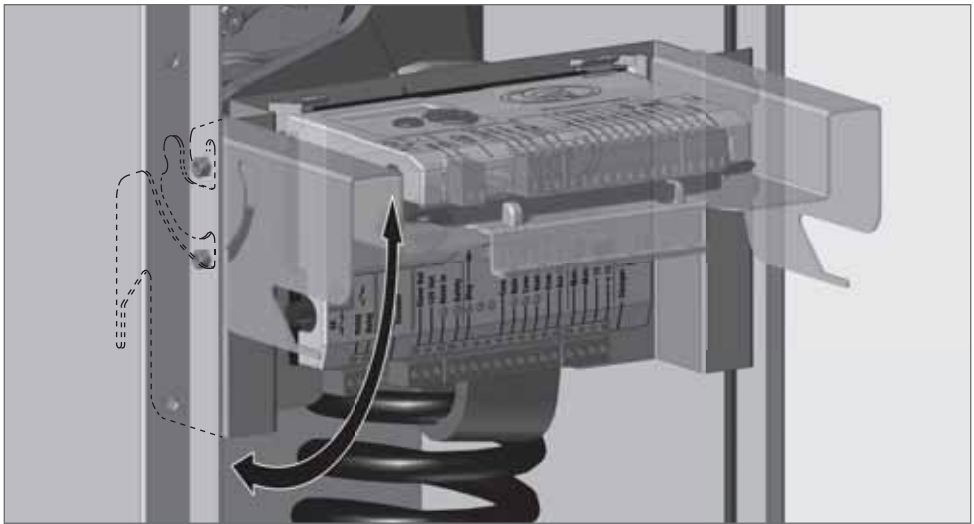


STEP 1

FIGURE 90

STEP 2

Keeping the **CLAWS** Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.

**FIGURE 91****FIGURE 92**

The bracket can be moved into a set angle of 70° by pivoting it upward from the bottom for better viewing of the LCD screen (Section 5, Figure 93).

It can also be moved lower down for optimum space when working on the gearbox (Section 5, Figure 94).



Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 5, Figure 91).

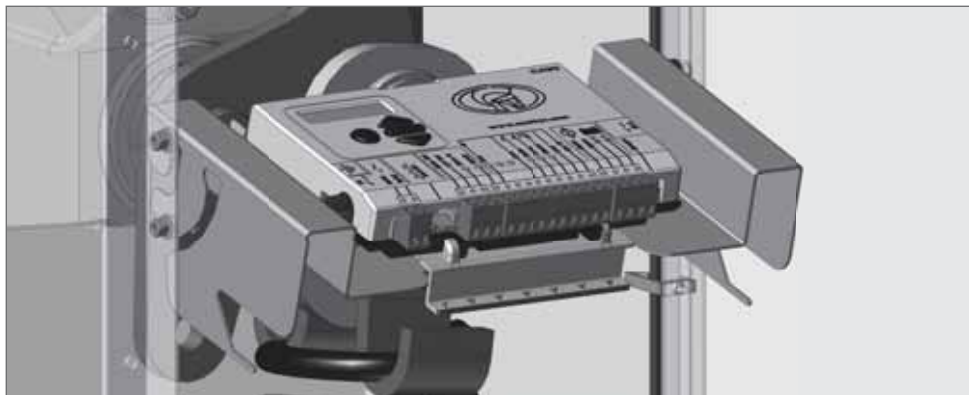


FIGURE 93. CLAWS CONTROLLER AND BRACKET AT FIXED 70° POSITION

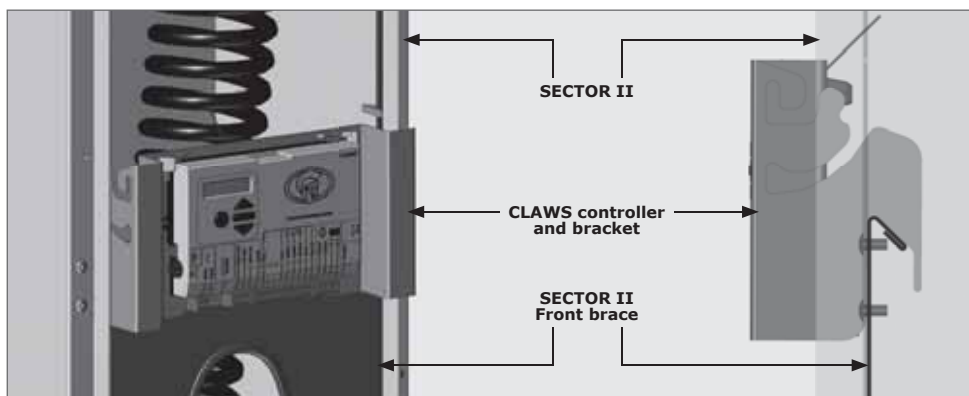


FIGURE 94. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION

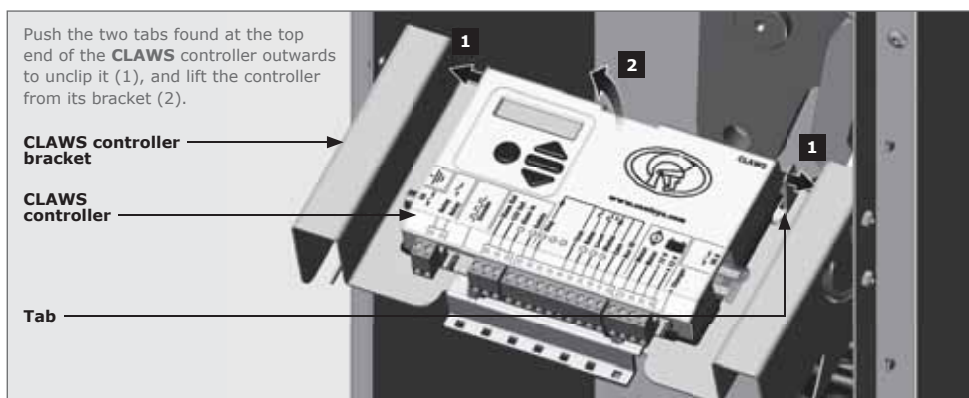


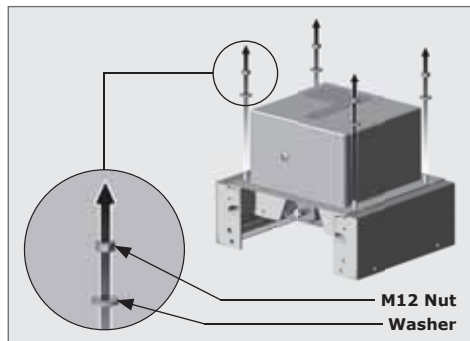
FIGURE 95. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET

STEP 3

Connect harness and power supply. Refer to the wiring diagrams and controller settings.

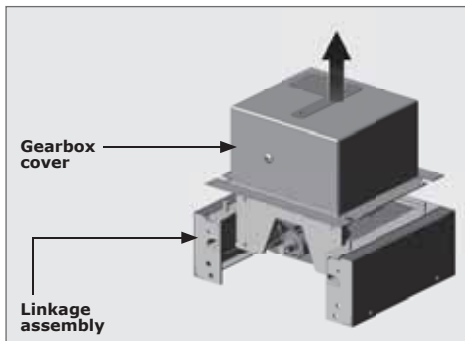
6. RHS Independent Drive Surface Mount - Opposing Direction of Travel

6.1. Preparing the Drive Linkage Assembly



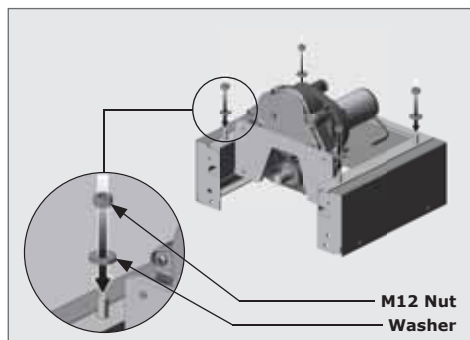
STEP 1

FIGURE 1



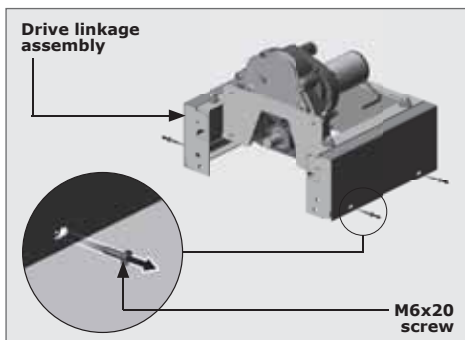
STEP 2

FIGURE 2



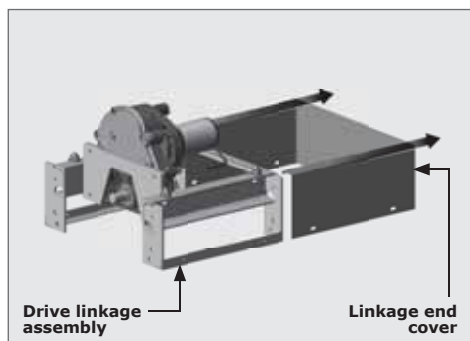
STEP 3

FIGURE 3



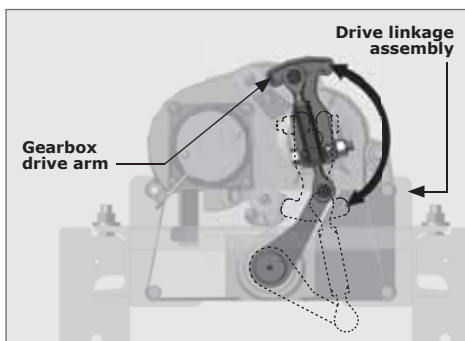
STEP 4

FIGURE 4



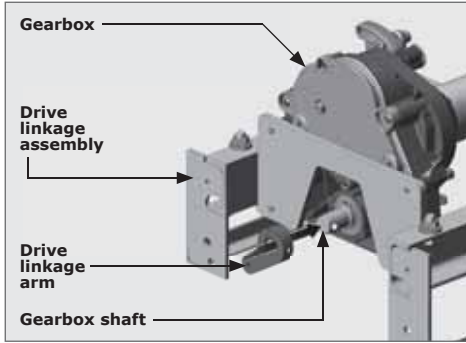
STEP 5

FIGURE 5



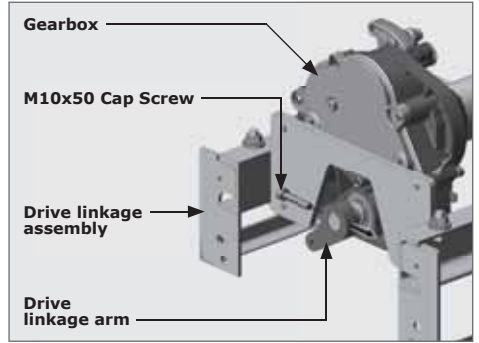
STEP 6

FIGURE 6



STEP 7

FIGURE 7

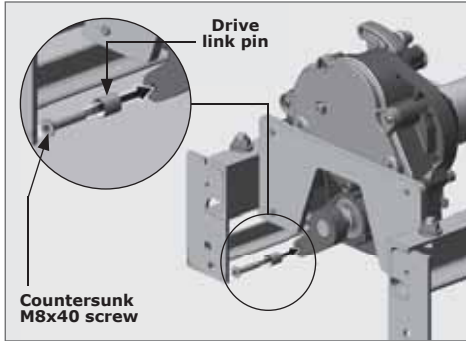


STEP 8

FIGURE 8



The drive linkage arm should point to a 7 o'clock position and the holes of the gearbox shaft and the linkage arm must line up as shown above.



STEP 9

FIGURE 9

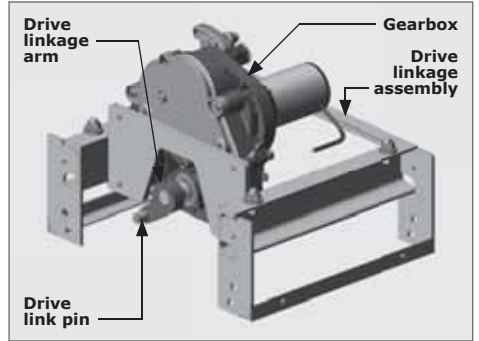


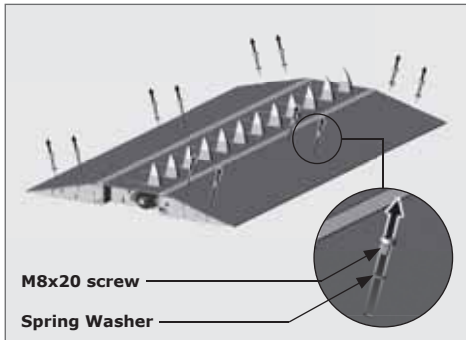
FIGURE 10



Tighten the Countersunk M8x40 screw to 20Nm (Section 6, Figure 9).

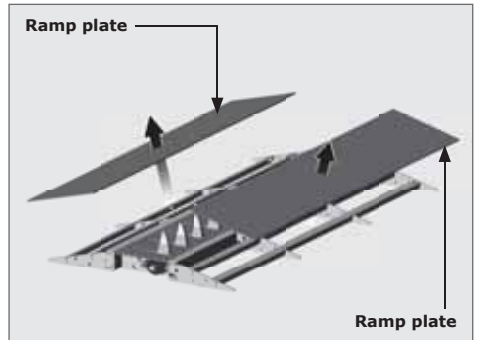
6.2. Spike Module Assembly

6.2.1. Preparing the Spike Model assembly(ies) for installation



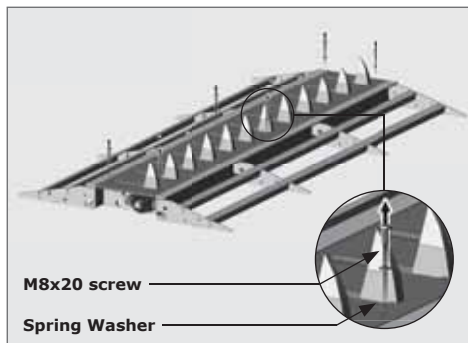
STEP 1

FIGURE 11



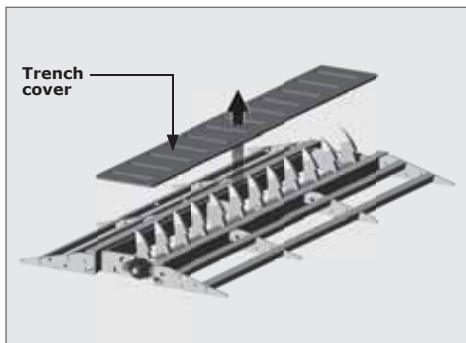
STEP 2

FIGURE 12



STEP 3

FIGURE 13



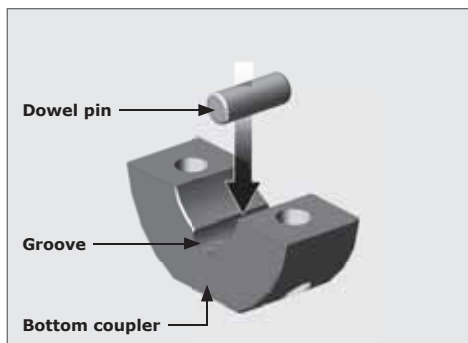
STEP 4

FIGURE 14

6.2.2. Attaching the Driven Link to the first spike module

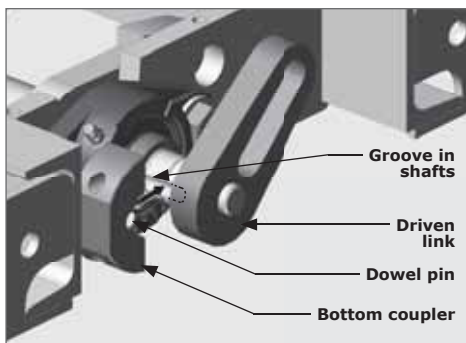


Place the spikes into the down position to aid in the fitment of all the shaft couplings.



STEP 1

FIGURE 15

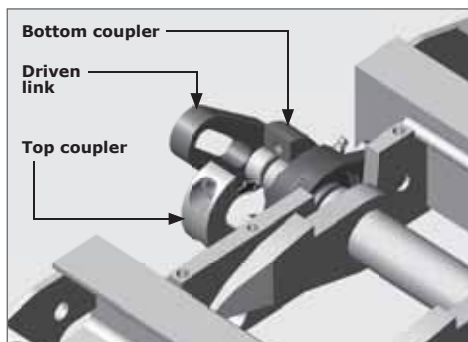


STEP 2

FIGURE 16

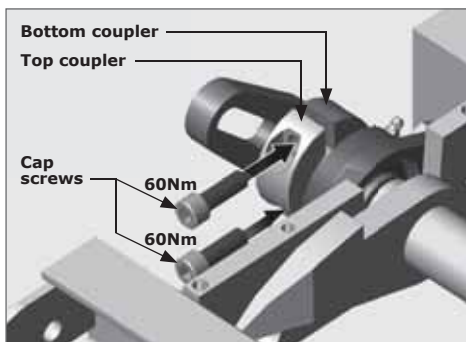


Ensure the Driven Link and the spikes are pointing in the same direction. (Section 6, Figures 16 to 19).



STEP 3

FIGURE 17



STEP 4

FIGURE 18

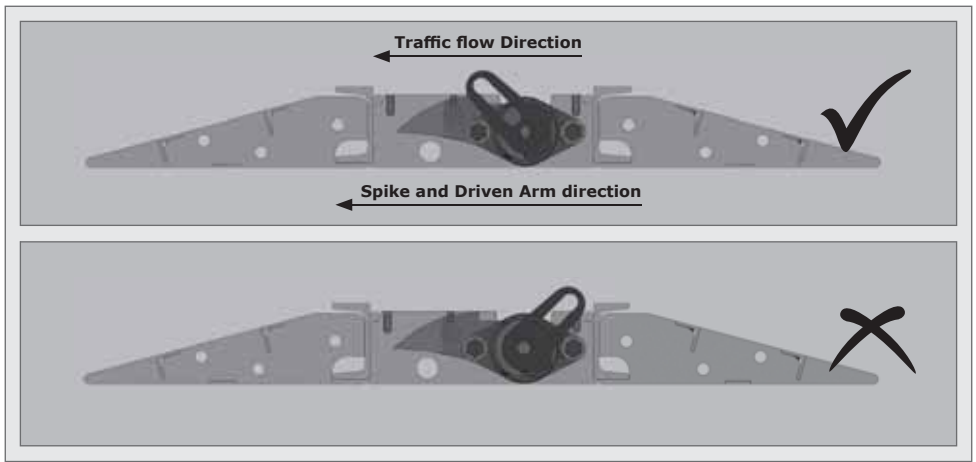


FIGURE 19

6.2.3. Aligning the Driven Linkage Arm to the Drive Linkage Arm.

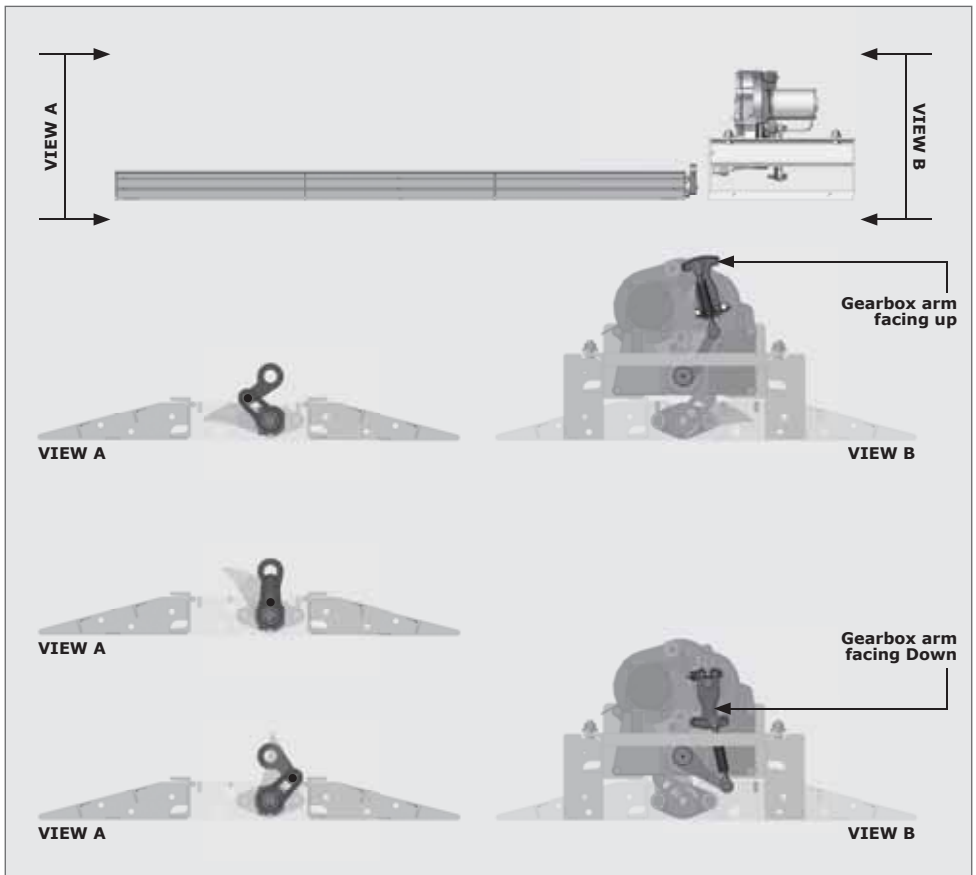
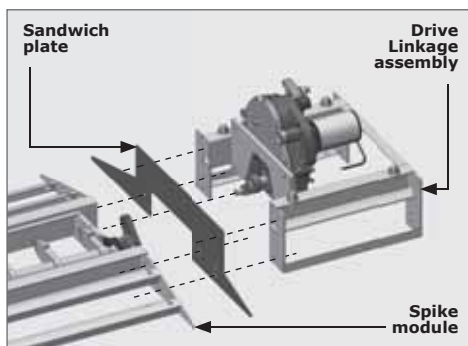


FIGURE 20

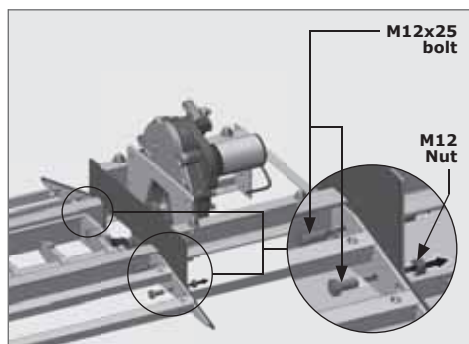
6.2.4. Attaching the drive linkage assembly to the spike module

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly. Ensure that the Sandwich Plate is lifted over the Driven Linkage Arm, so that the Driven Linkage Arm sits flush with the Drive Linkage Arm (Section 6, Figure 21).



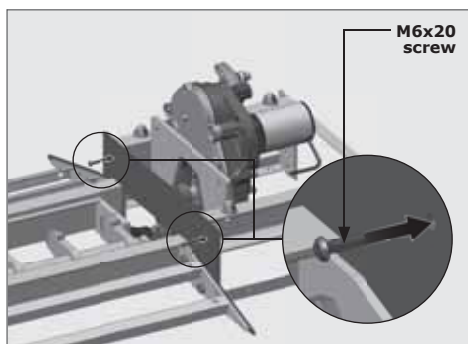
STEP 1

FIGURE 21



STEP 2

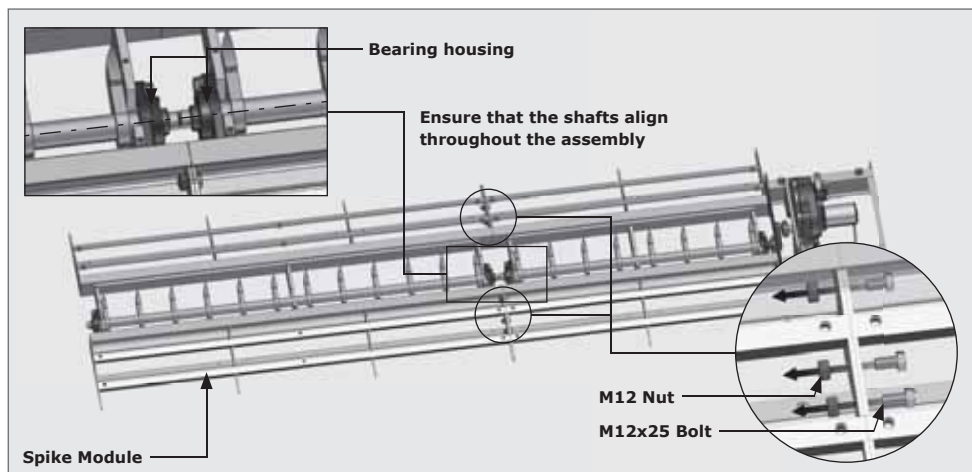
FIGURE 22



STEP 3

FIGURE 23

Using six M12x25 bolts, fix one spike module to another (Section 6, Figure 24).



STEP 4

FIGURE 24



To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

6.2.5. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.



It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.

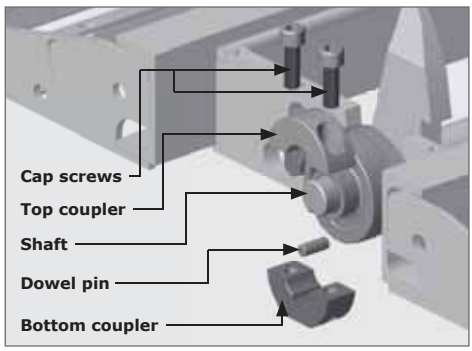


FIGURE 25. SHAFT COUPLER

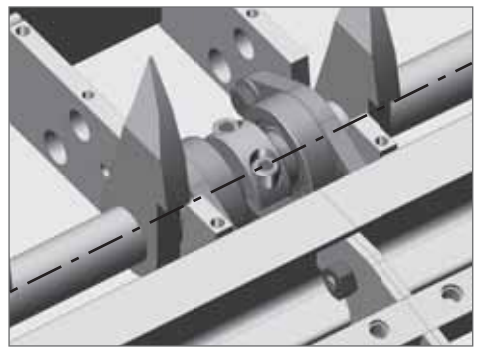
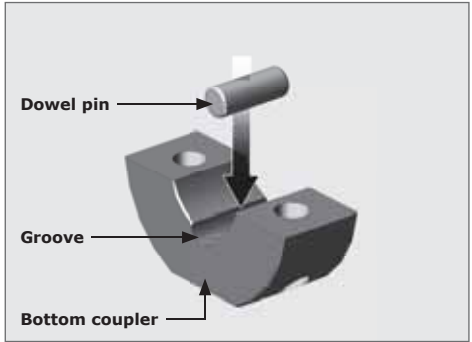


FIGURE 26

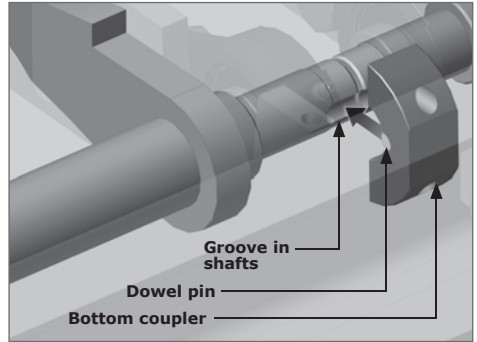


Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.



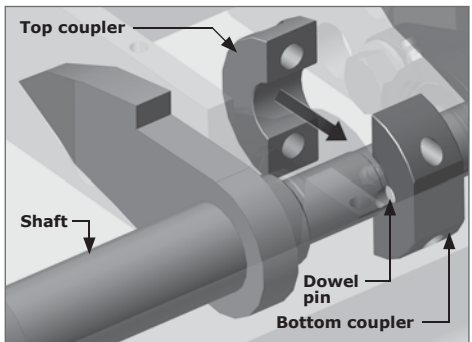
STEP 1

FIGURE 27



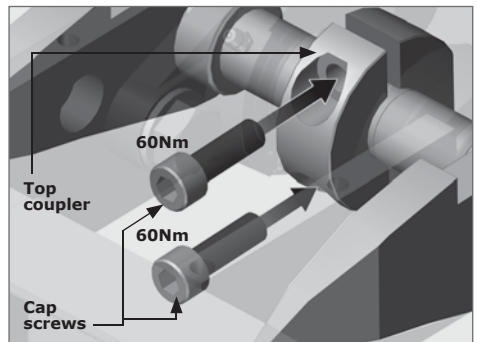
STEP 2

FIGURE 28



STEP 3

FIGURE 29



STEP 4

FIGURE 30

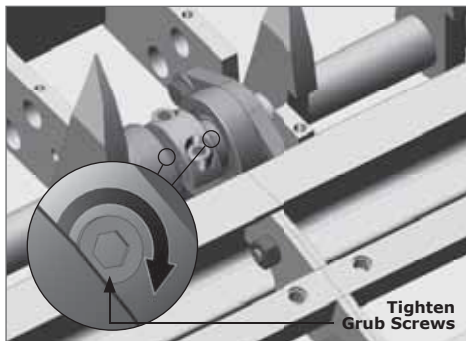
STEP 5

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.



STEP 6

FIGURE 31



STEP 7

FIGURE 32

6.2.6. Bolting down the assembly to the ground

If the **SECTOR II** and **CLAWS** are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and **SECTOR II**. (Section 6.4.2.)

These must be done before bolting the assembly to the ground. Once this preparation work has been completed, proceed with the installation below.

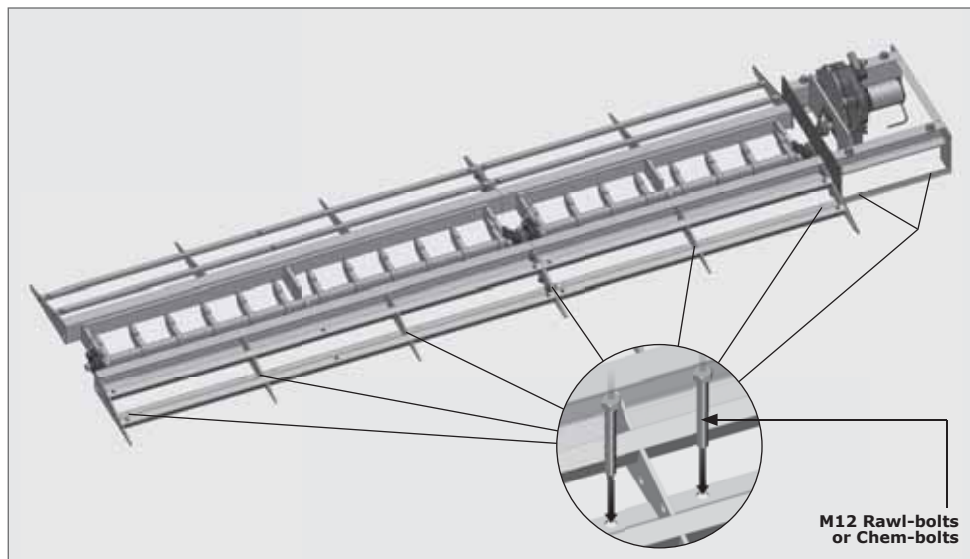
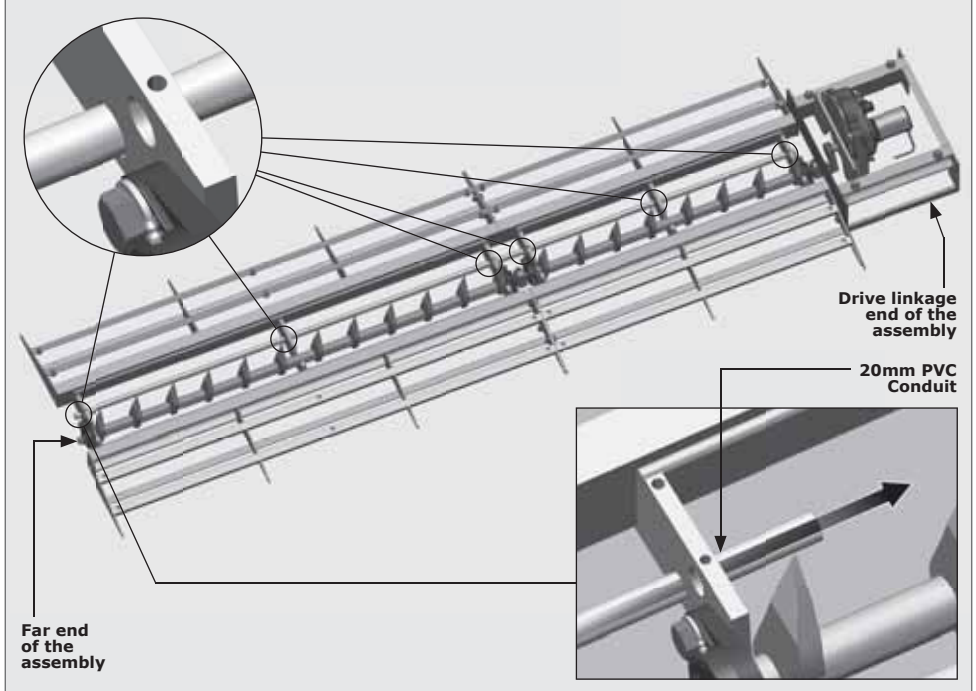


FIGURE 33



It is crucial that the surface it's mounted on is a reasonably even surface as an uneven surface could result in an uneven binding of the spike shafts. This will result in premature failure.

6.2.7. Proximity sensor installation



STEP 1

FIGURE 34



The length of the PVC conduit will be relative to the length of the spike modules and drive linkage unit combined. Ensure that a further 38mm is added to this to account for the modules and coupling (Refer to Section 6, Figure 35).

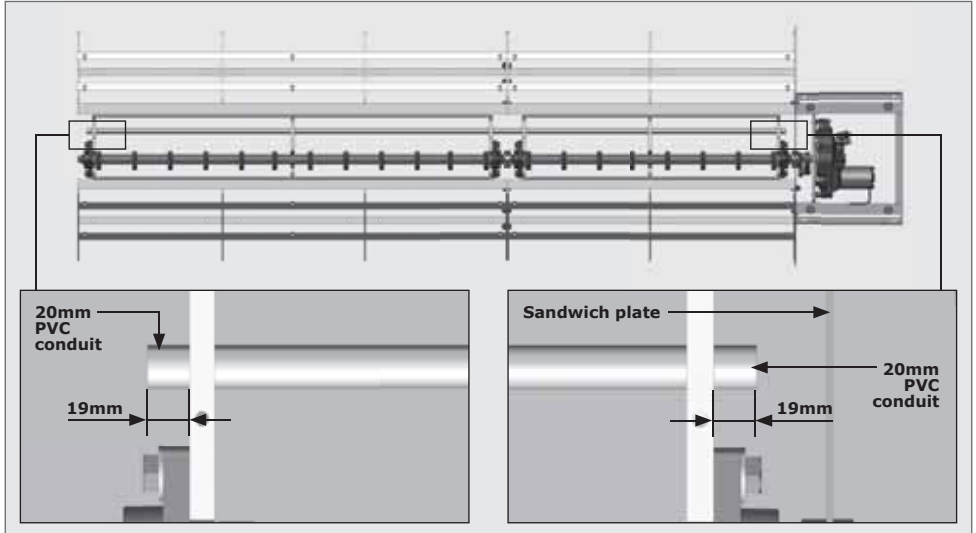
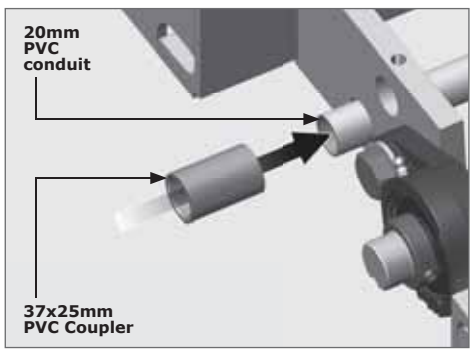


FIGURE 35

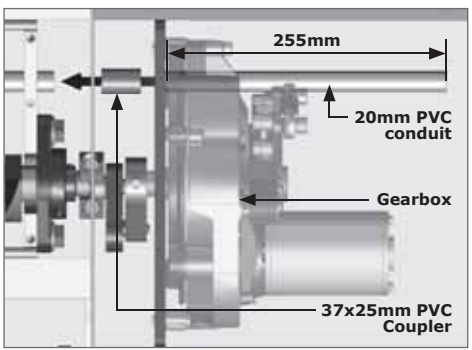


Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.



STEP 2

FIGURE 36

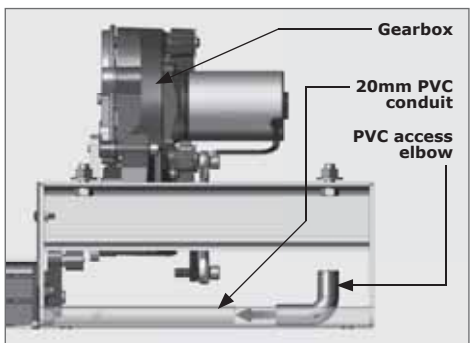


STEP 3

FIGURE 37

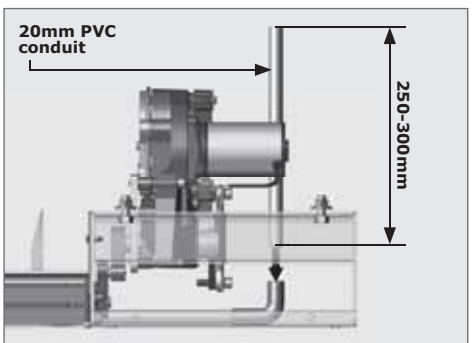


Steps 4-5 is only applicable if the SECTOR II will be mounted directly onto the **CLAWS** Gearbox. If they are going to be mounted separately, a trench for the conduit and proximity sensor cable will need to be dug (Section 6.4.2.).



STEP 4

FIGURE 38



STEP 5

FIGURE 39



Please ensure that the moving mechanical parts do not rub against the conduit or cables.

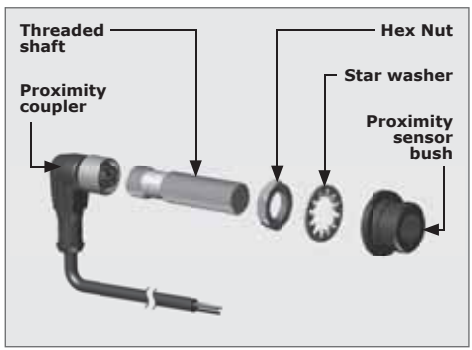


FIGURE 40. PROXIMITY SENSOR

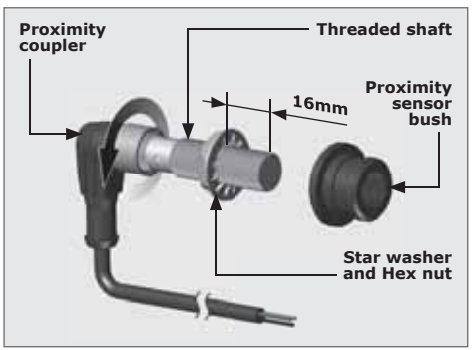


FIGURE 41. PROXIMITY SENSOR

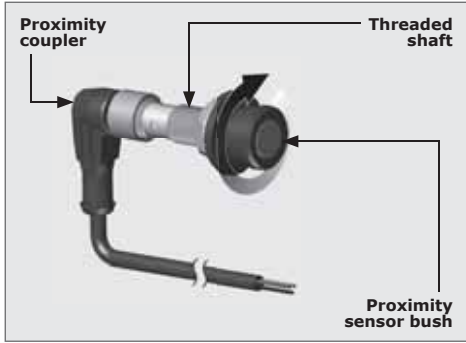
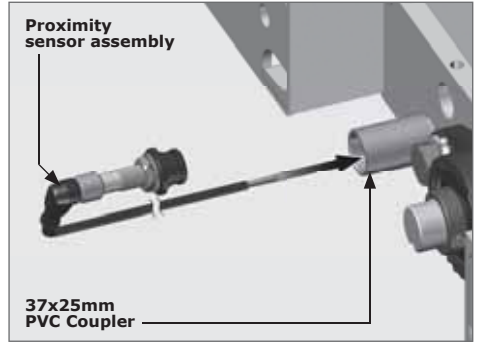


FIGURE 42. PROXIMITY SENSOR



STEP 8

FIGURE 43

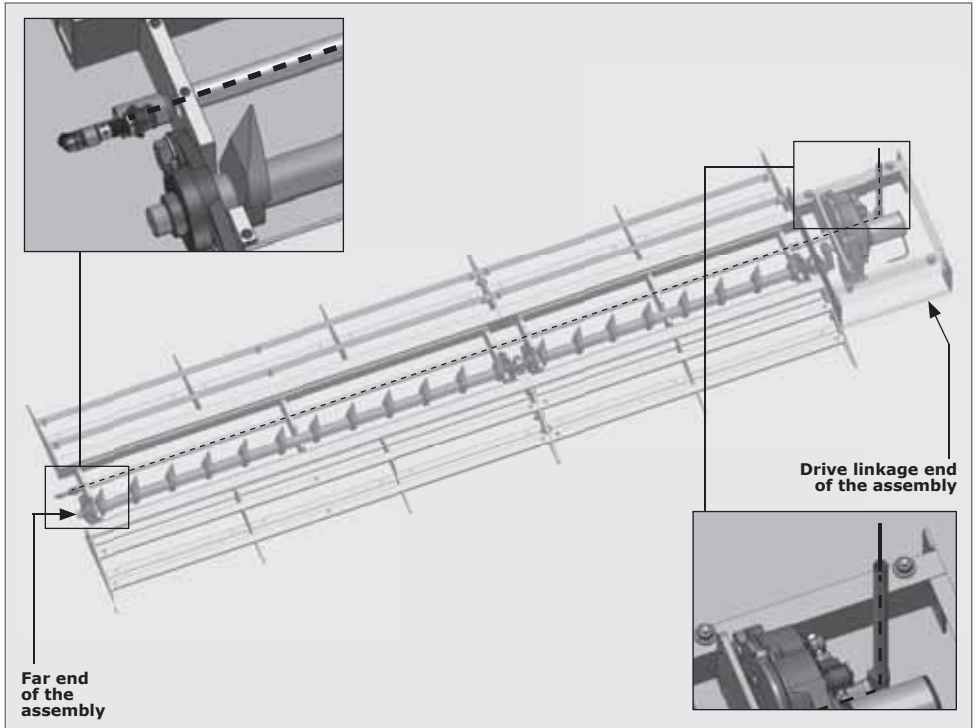
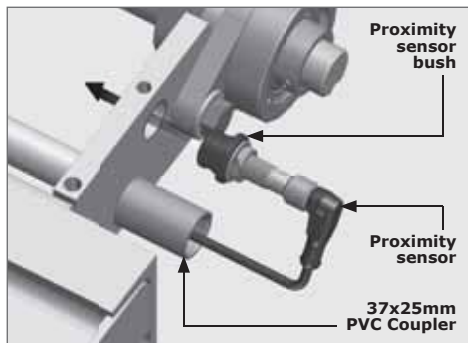


FIGURE 44

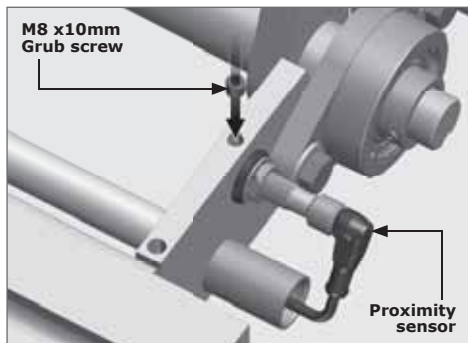


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed to the SECTOR II at a later stage.



STEP 9

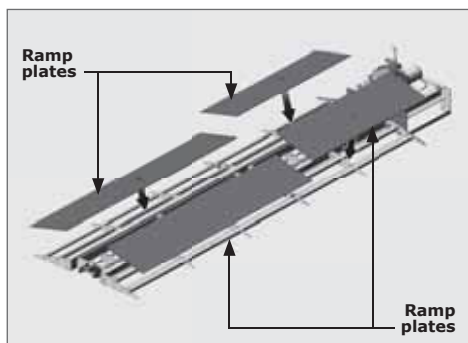
FIGURE 45



STEP 10

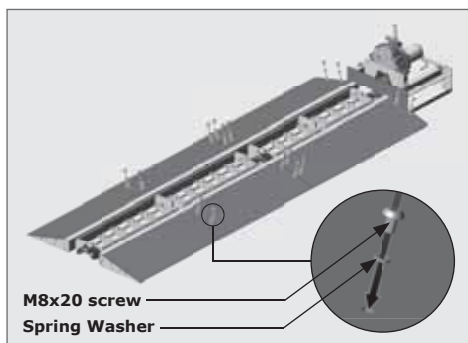
FIGURE 46

6.3. Re-assembling the ramp plates and linkage cover



STEP 1

FIGURE 47

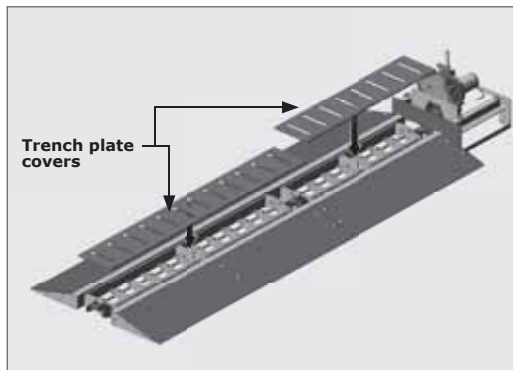


STEP 2

FIGURE 48

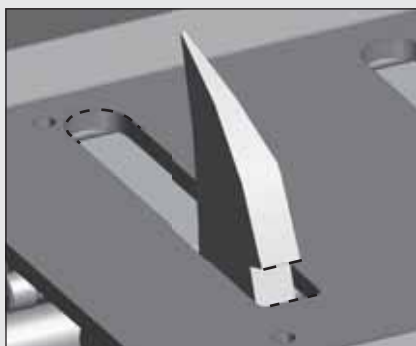


Leave out the four M8 screws and Spring Washers on the far end of the assembly as the module end cover will be assembled later.

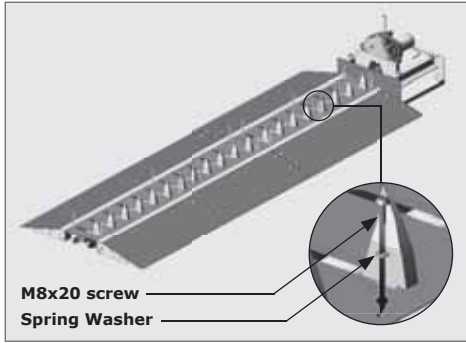


STEP 3

FIGURE 49

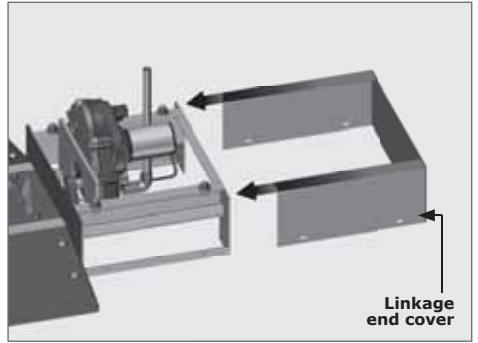


Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.



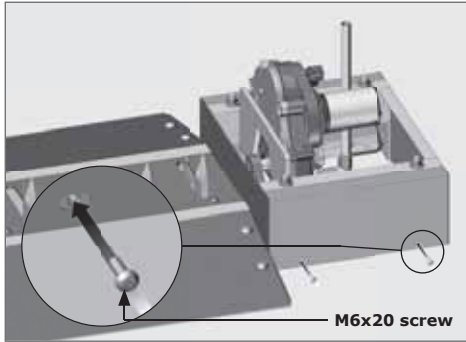
STEP 4

FIGURE 50



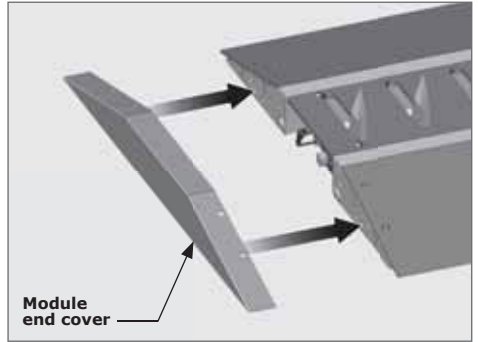
STEP 5

FIGURE 51



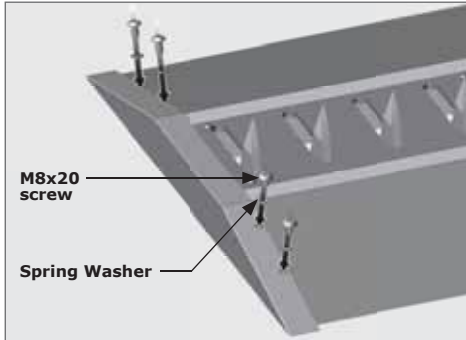
STEP 6

FIGURE 52



STEP 7

FIGURE 53



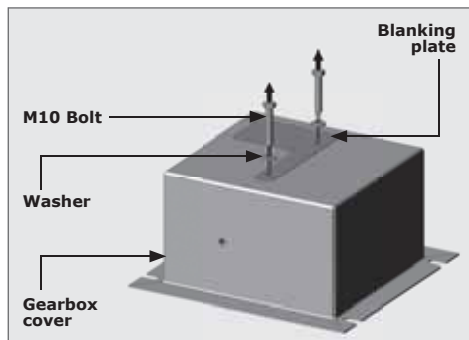
STEP 8

FIGURE 54

6.4. Integrating the SECTOR II with the CLAWS

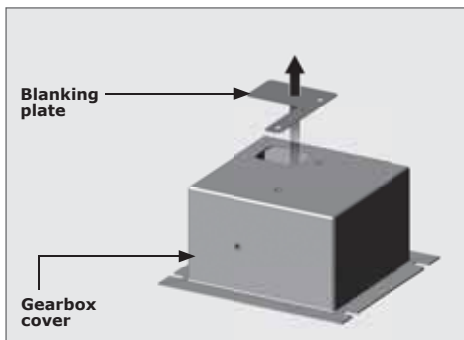
6.4.1. Directly mount the SECTOR II onto the Independent Drive

6.4.1.1. Placing the gearbox cover into position



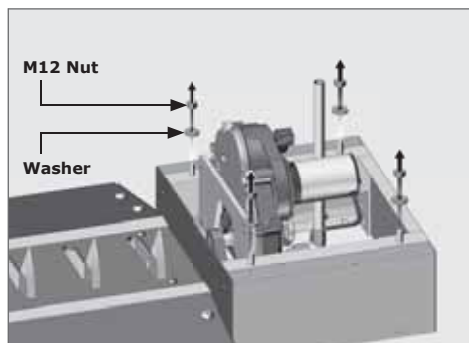
STEP 1

FIGURE 55



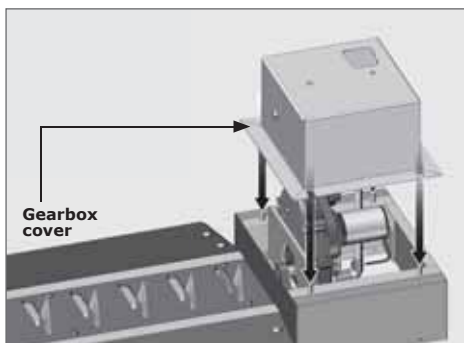
STEP 2

FIGURE 56



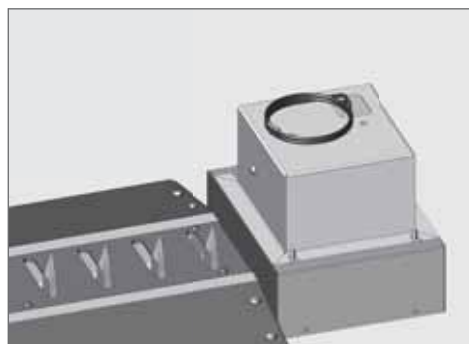
STEP 3

FIGURE 57



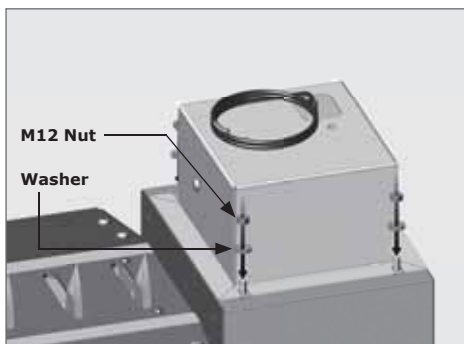
STEP 4

FIGURE 58



STEP 5

FIGURE 59



STEP 6

FIGURE 60

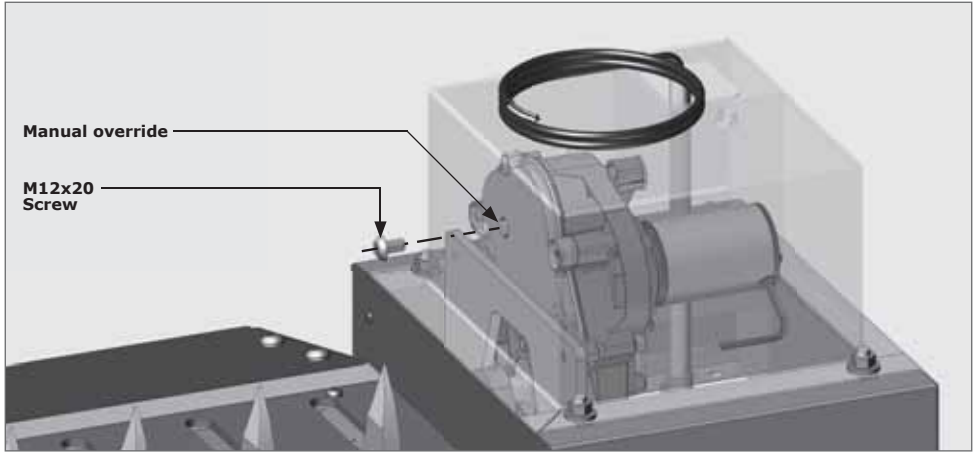
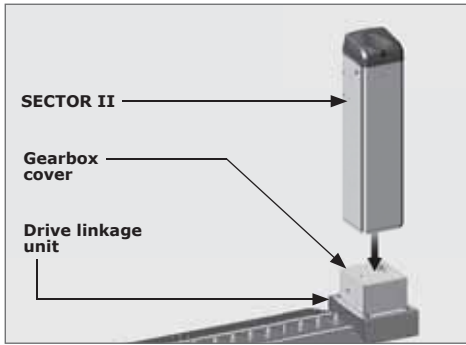
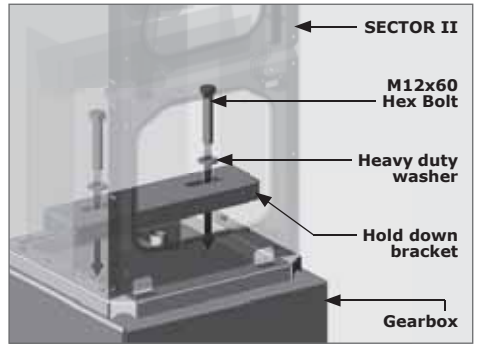


FIGURE 61. MANUAL OVERRIDE

6.4.1.2. Placing the SECTOR II into position



STEP 1 FIGURE 62



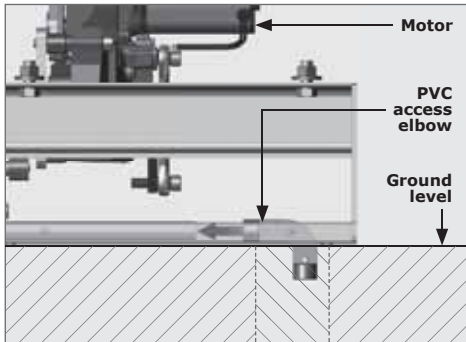
STEP 2 FIGURE 63

6.4.2. Separately-placed CLAWS and SECTOR II

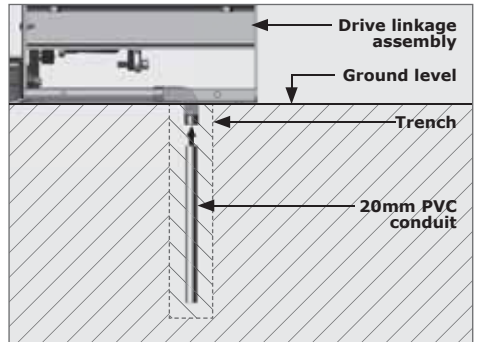
6.4.2.1. Running the conduit from the gearbox to the SECTOR II

STEP 1

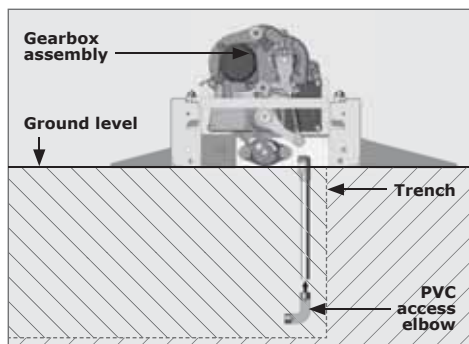
Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.



STEP 2 FIGURE 64

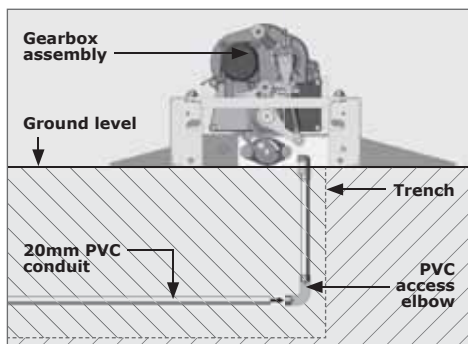


STEP 3 FIGURE 65



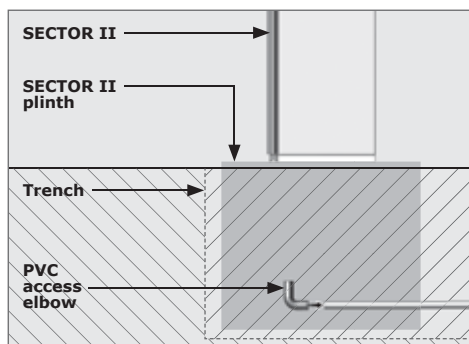
STEP 4

FIGURE 66



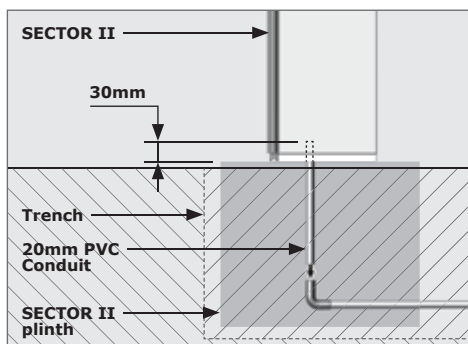
STEP 5

FIGURE 67



STEP 6

FIGURE 68



STEP 7

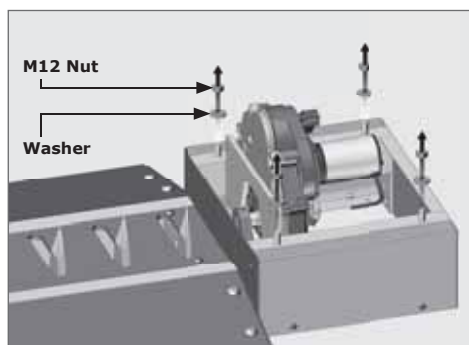
FIGURE 69

STEP 8

Route the **CLAWS** and Proximity sensor cables in the conduit to the SECTOR II.

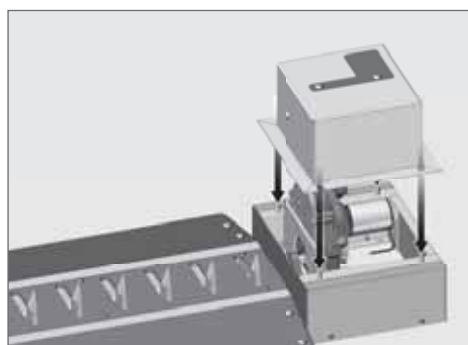
STEP 9

Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

6.4.2.2. Placing the gearbox cover into position

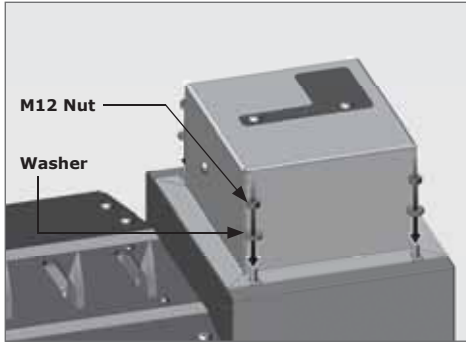
STEP 1

FIGURE 70



STEP 2

FIGURE 71



STEP 3

FIGURE 72

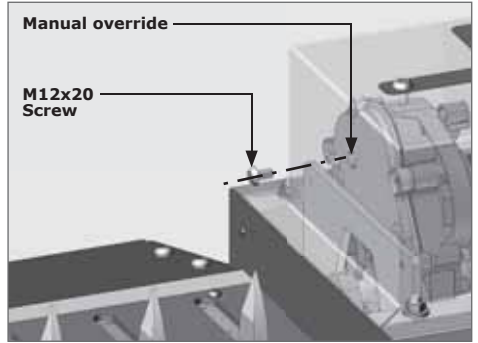
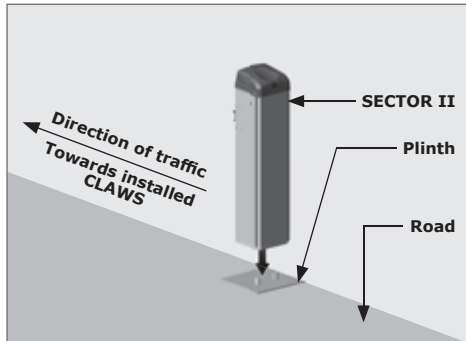


FIGURE 73. MANUAL OVERRIDE



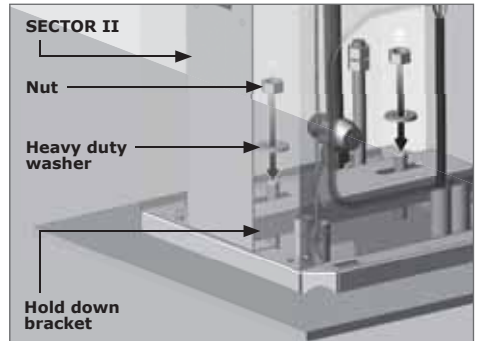
By removing the M12x20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.

6.4.2.3. Placing the SECTOR II into position



STEP 1

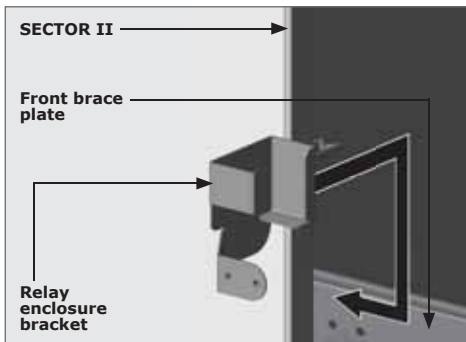
FIGURE 74



STEP 2

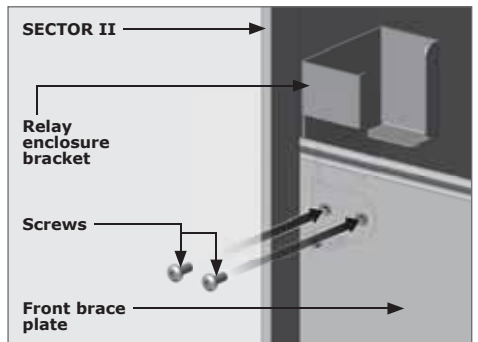
FIGURE 75

6.4.3. Fitting the relay enclosure and its bracket



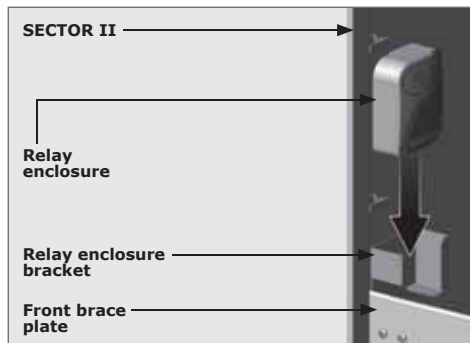
STEP 1

FIGURE 76



STEP 2

FIGURE 77



STEP 1

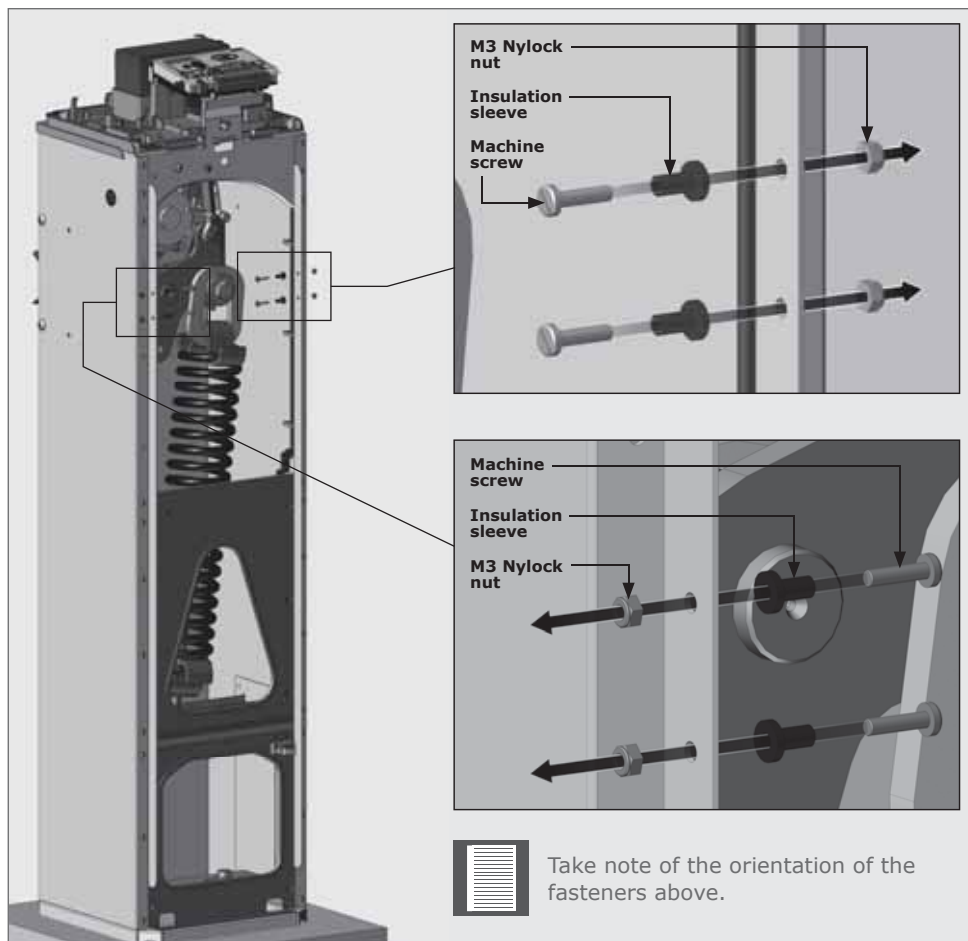
FIGURE 78

Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 16).



Complete the installation of the SECTOR II as per its full installation manual.

6.4.5. Fitting the CLAWS controller to the SECTOR II



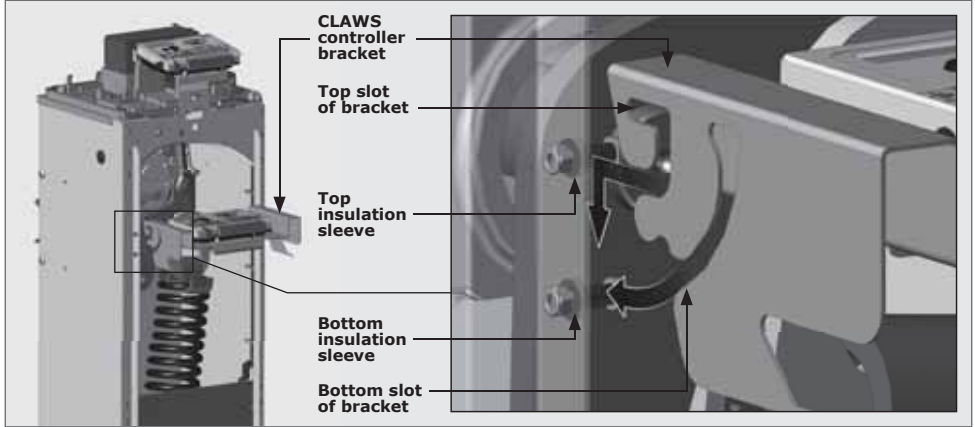
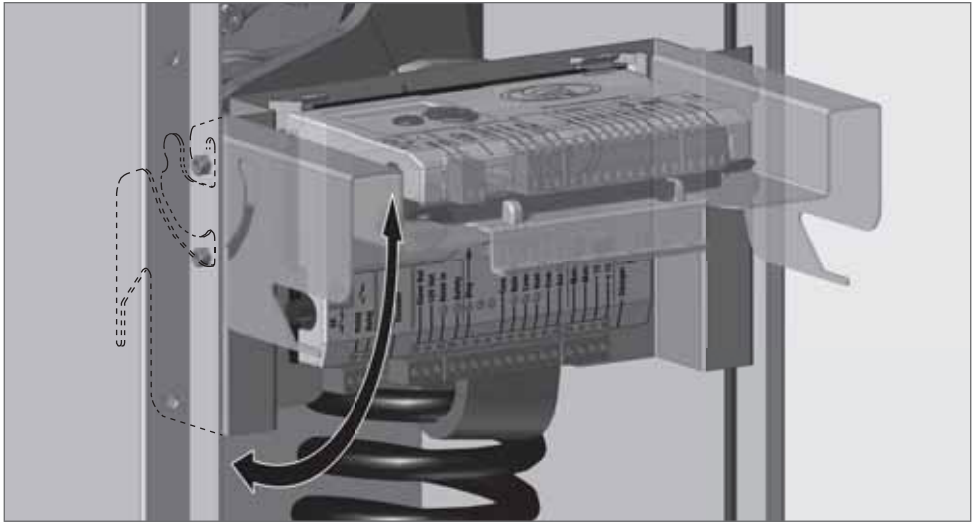
STEP 1

FIGURE 79

Take note of the orientation of the fasteners above.

STEP 2

Keeping the **CLAWS** Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.

**FIGURE 80****FIGURE 81**

The bracket can be moved into a set angle of 70° by pivoting it upward from the bottom for better viewing of the LCD screen (Section 6, Figure 82).

It can also be moved lower down for optimum space when working on the gearbox (Section 6, Figure 83).



Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 6, Figure 80).

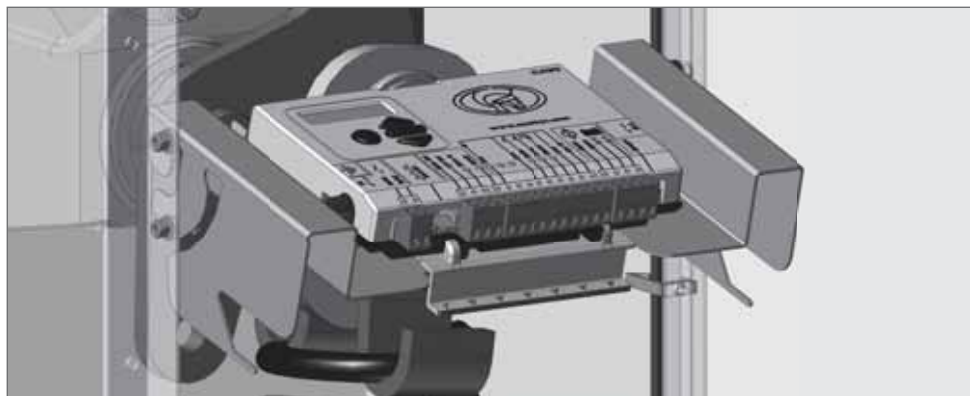


FIGURE 82. CLAWS CONTROLLER AND BRACKET AT FIXED 70° POSITION

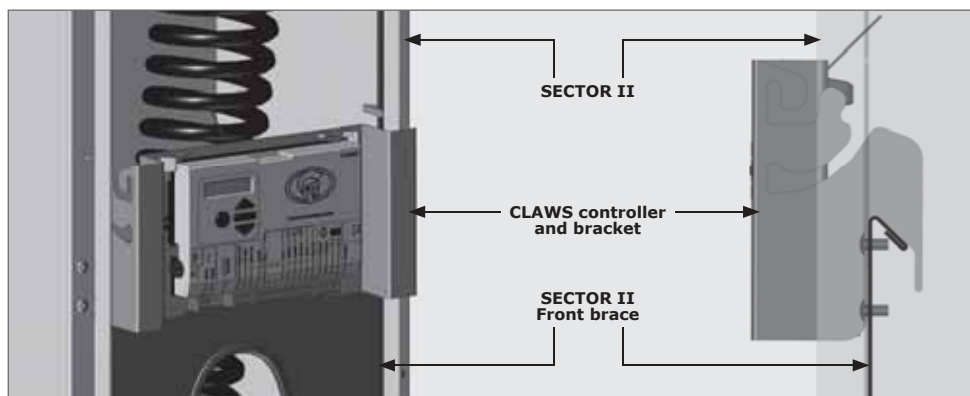


FIGURE 83. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION

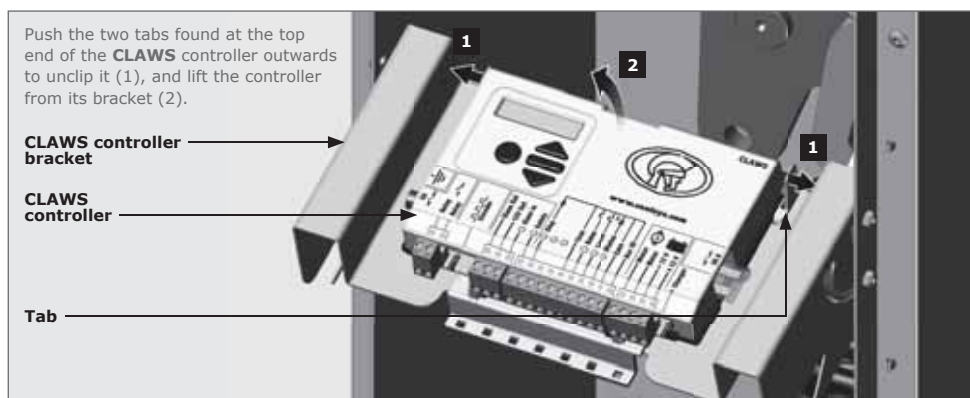


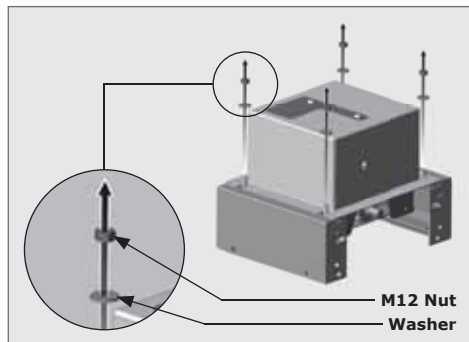
FIGURE 84. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET

STEP 3

Connect harness and power supply. Refer to the wiring diagrams and controller settings.

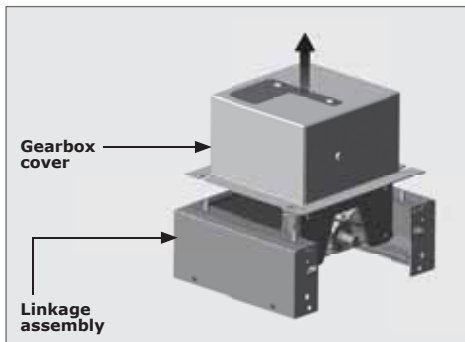
7. LHS Independent Drive Surface Mount - Similar Direction of Travel

7.1. Preparing the Drive Linkage Assembly



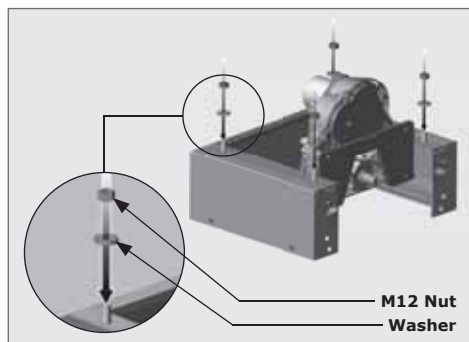
STEP 1

FIGURE 1



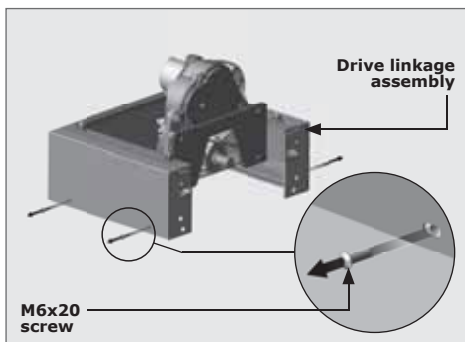
STEP 2

FIGURE 2



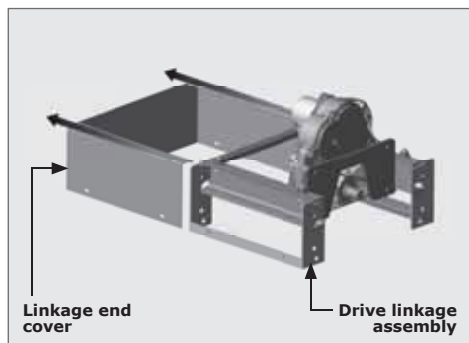
STEP 3

FIGURE 3



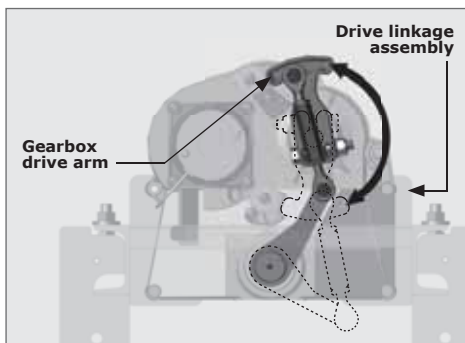
STEP 4

FIGURE 4



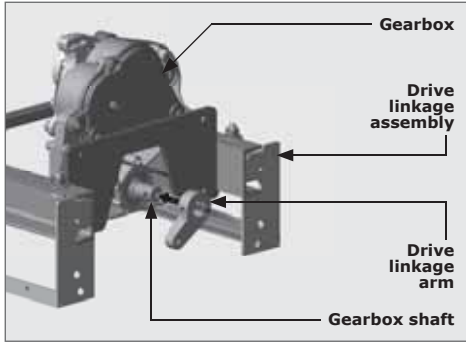
STEP 5

FIGURE 5



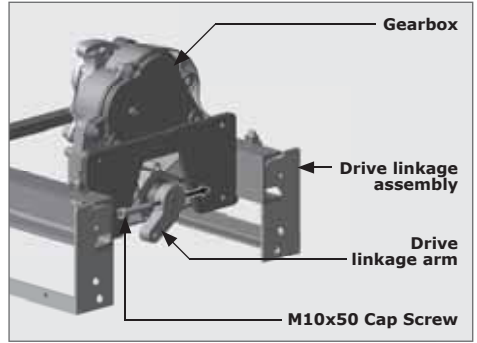
STEP 6

FIGURE 6



STEP 7

FIGURE 7

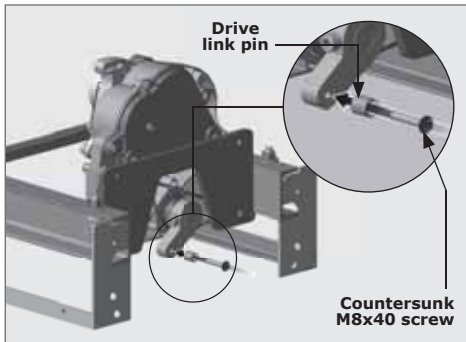


STEP 8

FIGURE 8



The drive linkage arm should point to a 7 o'clock position and the holes of the gearbox shaft and the linkage arm must line up as shown above.



STEP 9

FIGURE 9

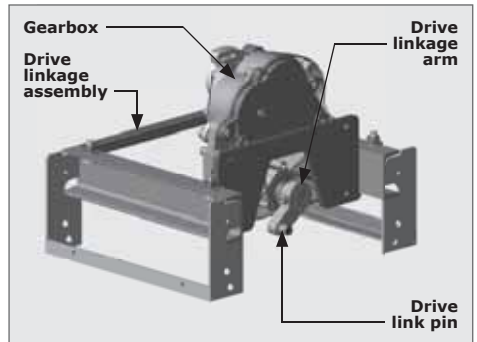


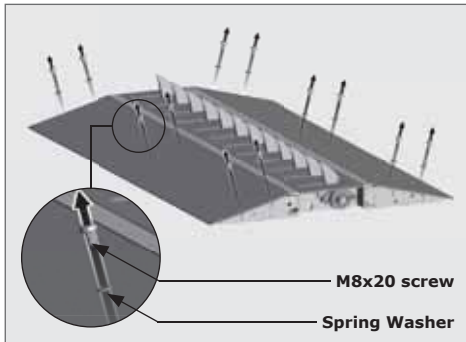
FIGURE 10



Tighten the Countersunk M8x40 screw to 20Nm (Section 7, Figure 9).

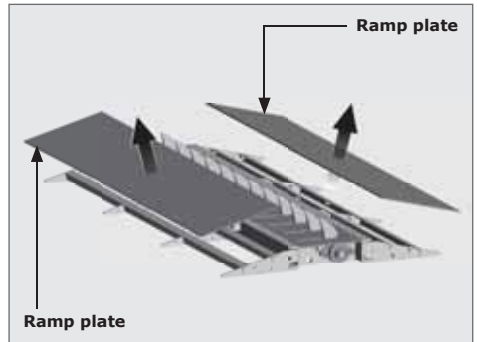
7.2. Spike Module Assembly

7.2.1. Preparing the Spike Model assembly(ies) for installation



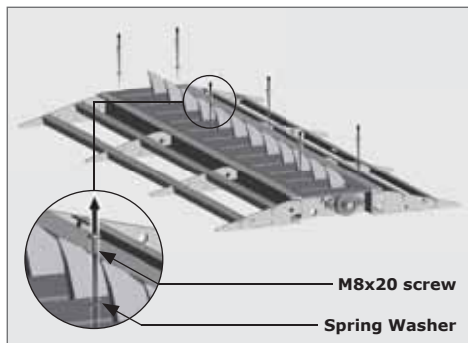
STEP 1

FIGURE 11

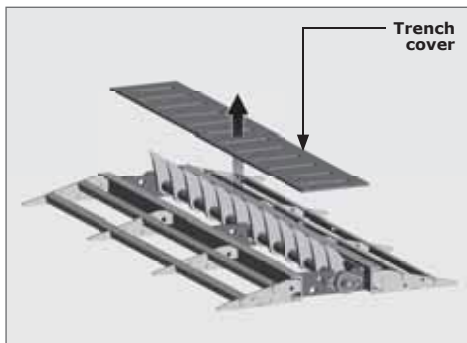


STEP 2

FIGURE 12



STEP 3 FIGURE 13

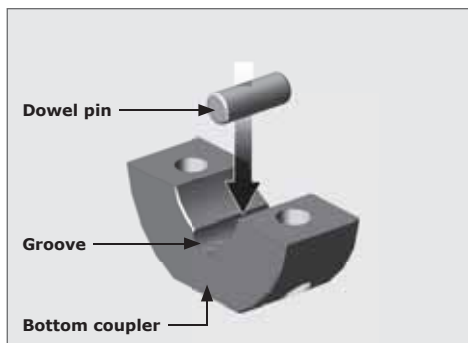


STEP 4 FIGURE 14

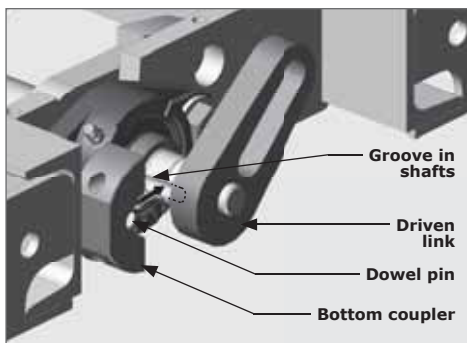
7.2.2. Attaching the Driven Link to the first spike module



Place the spikes into the down position to aid in the fitment of all the shaft couplings.



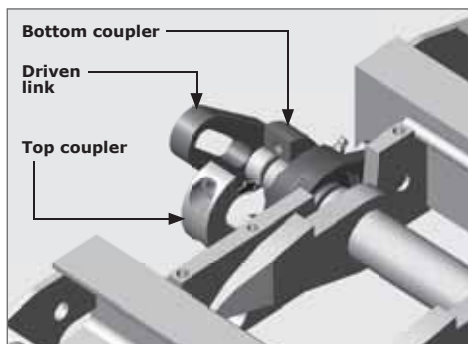
STEP 1 FIGURE 15



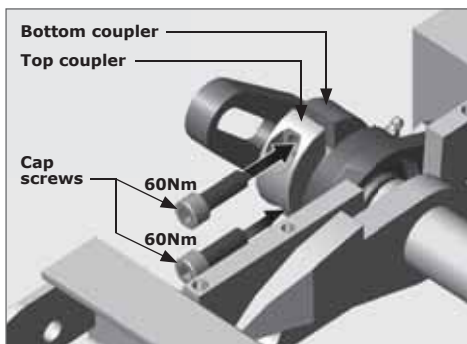
STEP 2 FIGURE 16



Ensure the Driven Link and the spikes are pointing in the same direction. (Section 7, Figures 16 to 19).



STEP 3 FIGURE 17



STEP 4 FIGURE 18

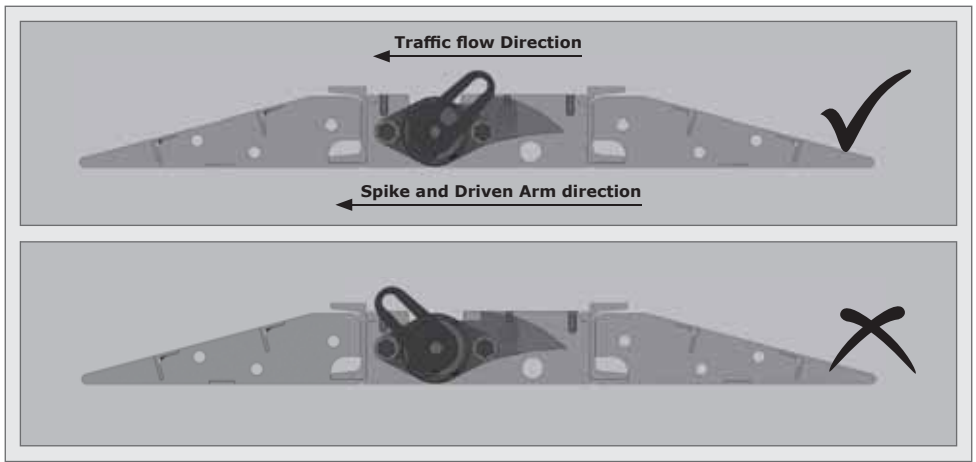


FIGURE 19

7.2.3. Aligning the Driven Linkage Arm to the Drive Linkage Arm.

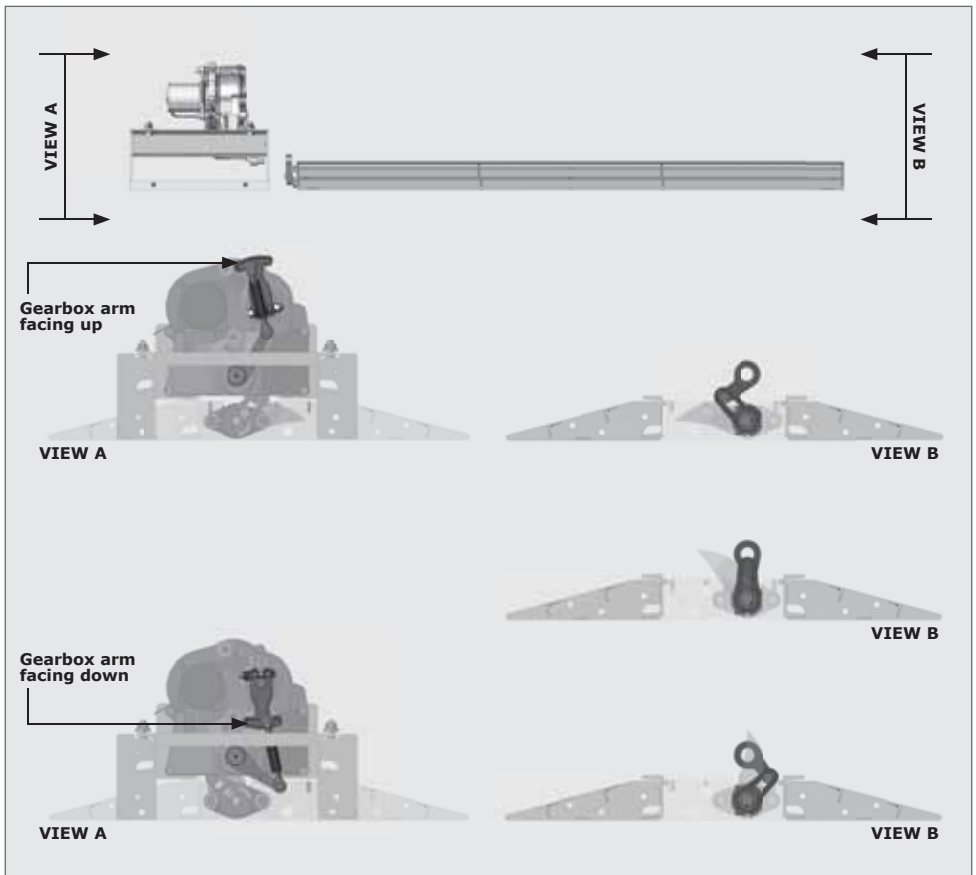
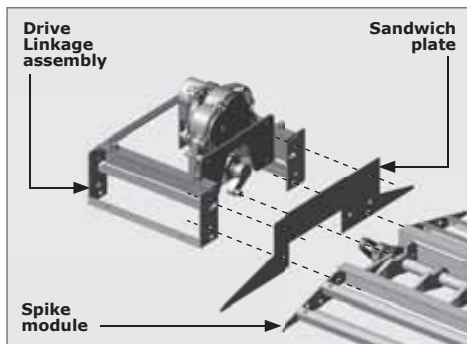


FIGURE 20

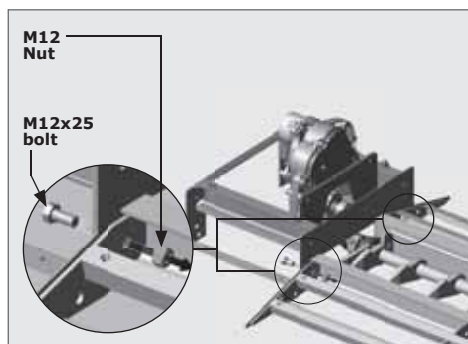
7.2.4. Attaching the drive linkage assembly to the spike module

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly. Ensure that the Sandwich Plate is lifted over the Driven Linkage Arm, so that the Driven Linkage Arm sits flush with the Drive Linkage Arm (Section 7, Figure 21).



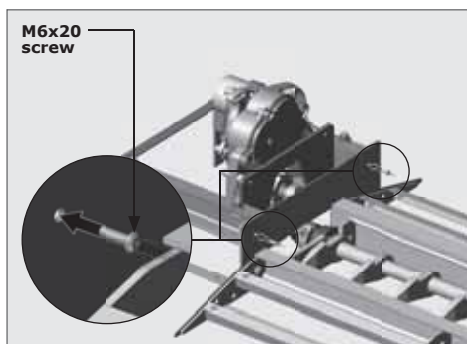
STEP 1

FIGURE 21



STEP 2

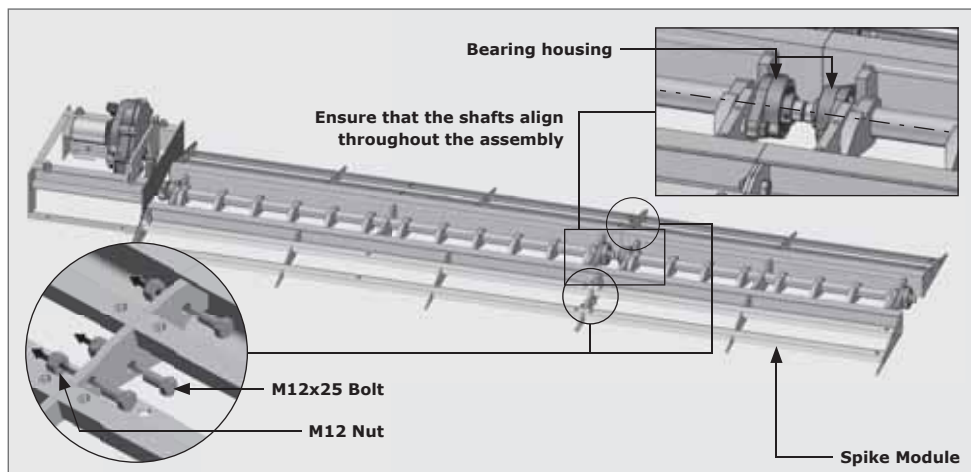
FIGURE 22



STEP 3

FIGURE 23

Using six M12x25 bolts, fix one spike module to another (Section 7, Figure 24).



STEP 4

FIGURE 24



To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

7.2.5. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.



It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.

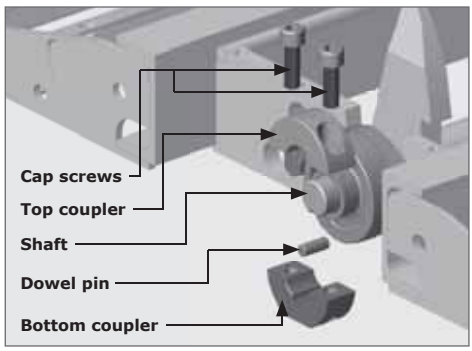


FIGURE 25. SHAFT COUPLER

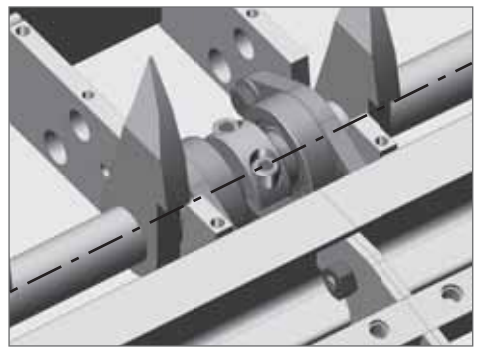
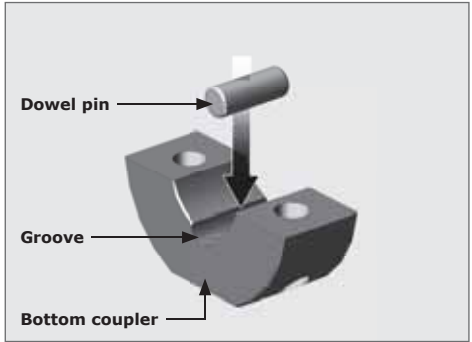


FIGURE 26

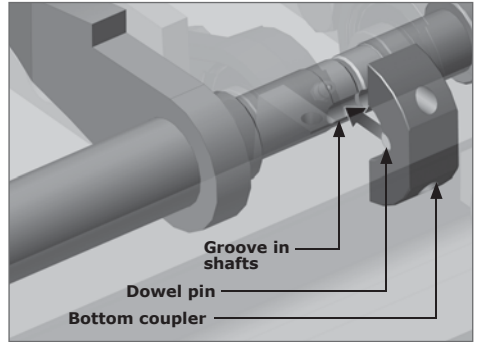


Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.



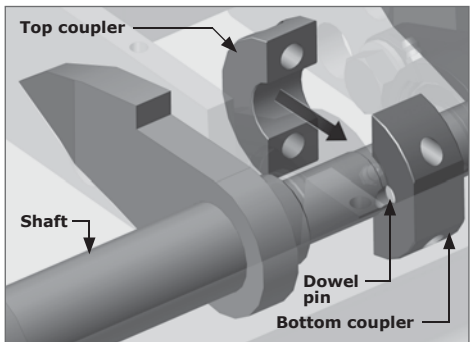
STEP 1

FIGURE 27



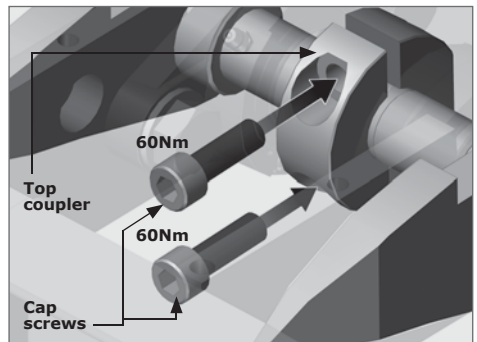
STEP 2

FIGURE 28



STEP 3

FIGURE 29



STEP 4

FIGURE 30

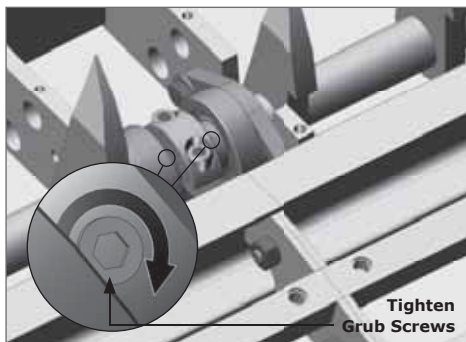
STEP 5

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.



STEP 6

FIGURE 31



STEP 7

FIGURE 32

7.2.6. Bolting down the assembly to the ground



If the SECTOR II and **CLAWS** are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. (Section 7.4.2.)

These must be done before bolting the assembly to the ground. Once this preparation work has been completed, proceed with the installation below.

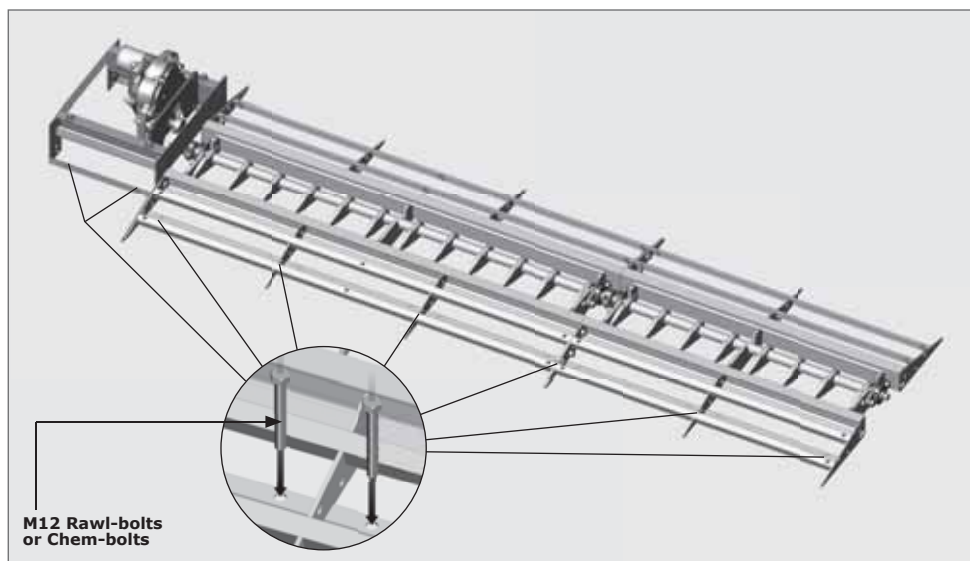
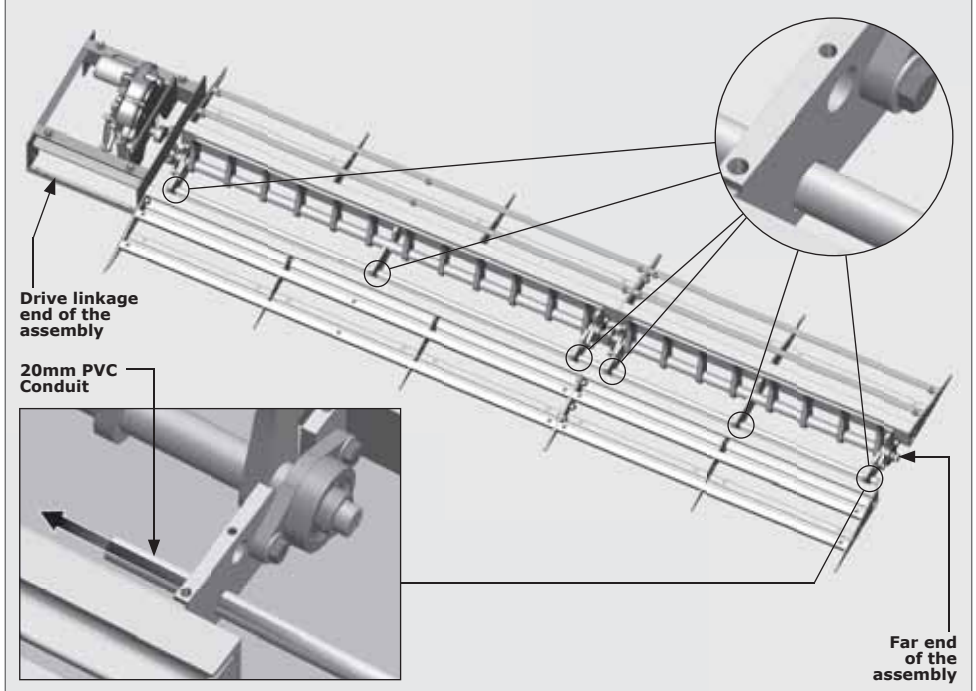


FIGURE 33



It is crucial that the surface it's mounted on is a reasonably even surface as an uneven surface could result in an uneven binding of the spike shafts. This will result in premature failure.

7.2.7. Proximity sensor installation



STEP 1

FIGURE 34



The length of the PVC conduit will be relative to the length of the spike modules and drive linkage unit combined. Ensure that a further 38mm is added to this to account for the modules and coupling (Refer to Section 7, Figure 35).

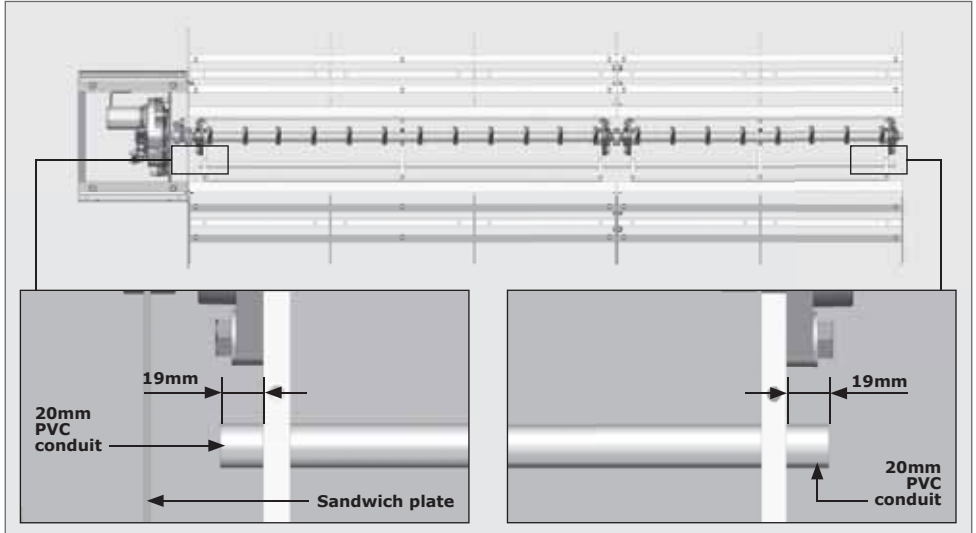
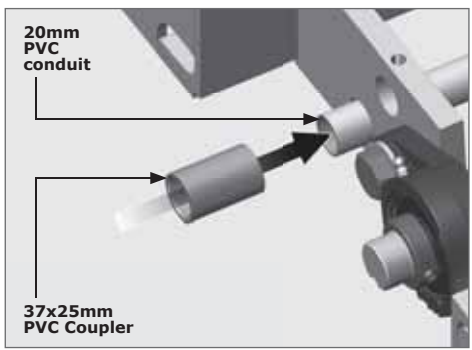


FIGURE 35

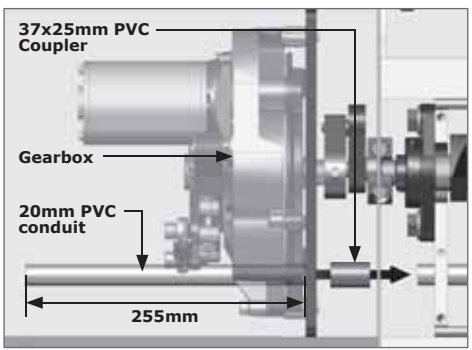


Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.



STEP 2

FIGURE 36

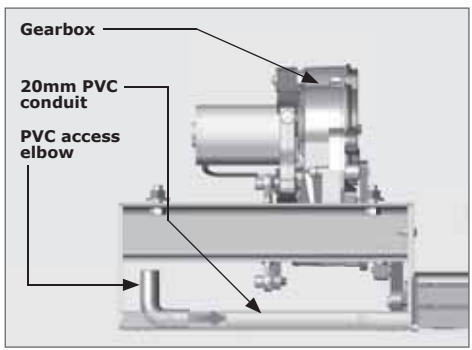


STEP 3

FIGURE 37

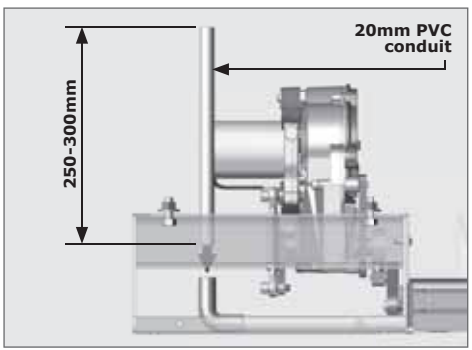


Steps 4-7 is only applicable if the SECTOR II will be mounted directly onto the **CLAWS** Gearbox. If they are going to be mounted separately, a trench for the conduit and proximity sensor cable will need to be dug (Section 7.4.2.).



STEP 4

FIGURE 38



STEP 5

FIGURE 39



Please ensure that the moving mechanical parts do not rub against the conduit or cables.

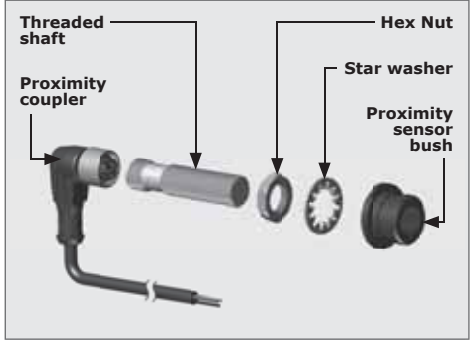


FIGURE 40. PROXIMITY SENSOR

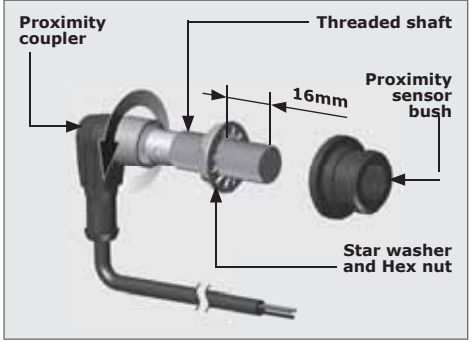
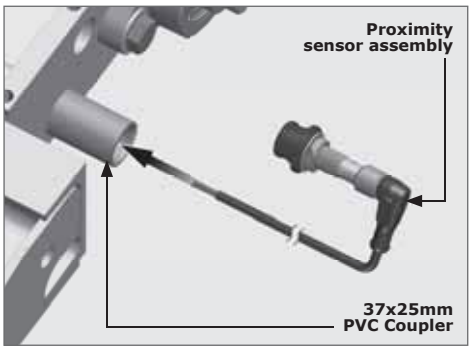


FIGURE 41. PROXIMITY SENSOR



FIGURE 42. PROXIMITY SENSOR



STEP 8

FIGURE 43

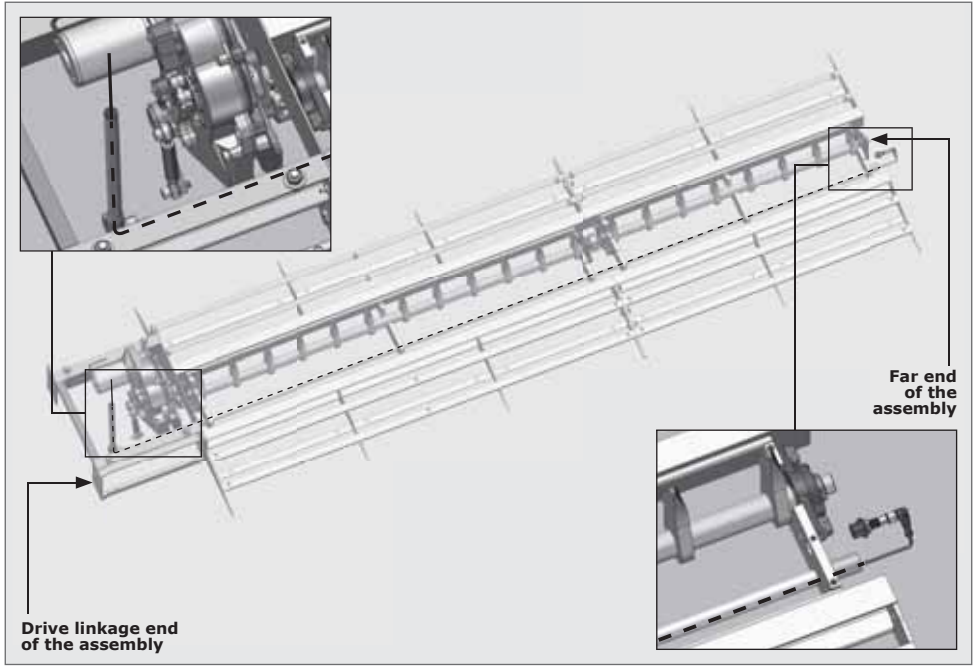
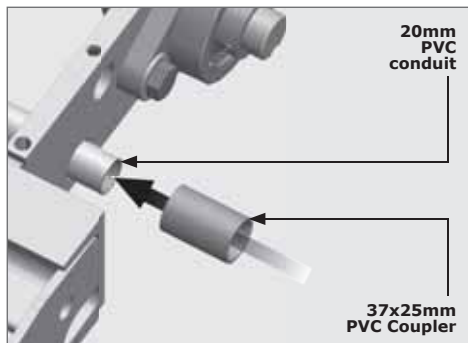


FIGURE 44

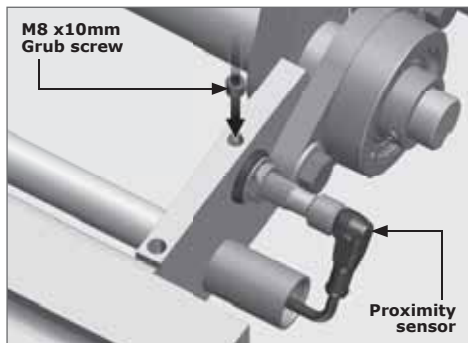


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed to the SECTOR II at a later stage.



STEP 9

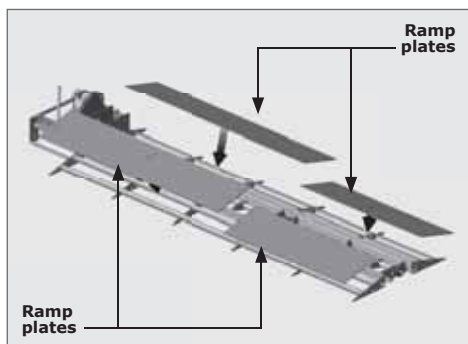
FIGURE 47



STEP 10

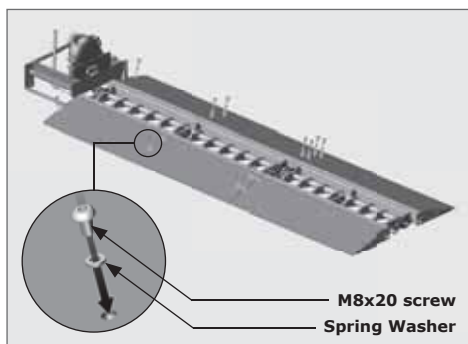
FIGURE 48

7.3. Re-assembling the ramp plates and linkage cover



STEP 1

FIGURE 49

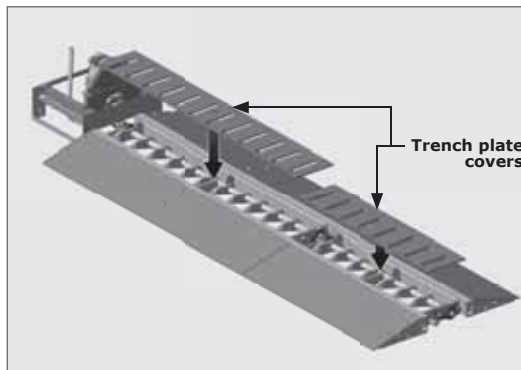


STEP 2

FIGURE 50



Leave out the four M8 screws and Spring Washers on the far end of the assembly as the module end cover will be assembled later.



STEP 3

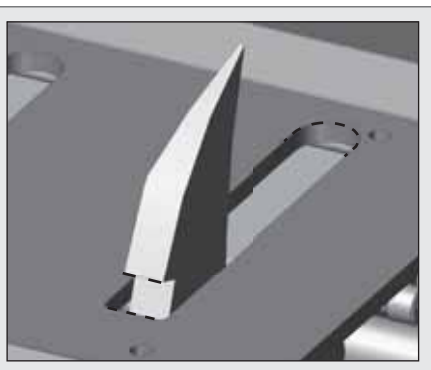
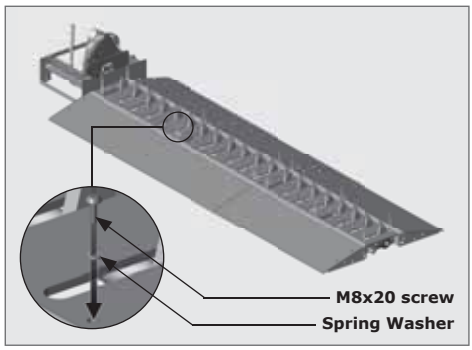


FIGURE 51

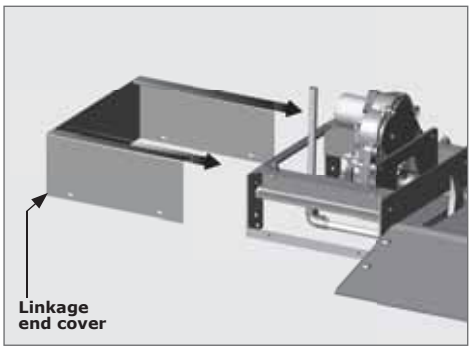


Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.



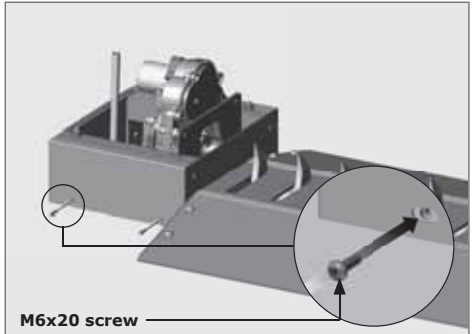
STEP 4

FIGURE 52



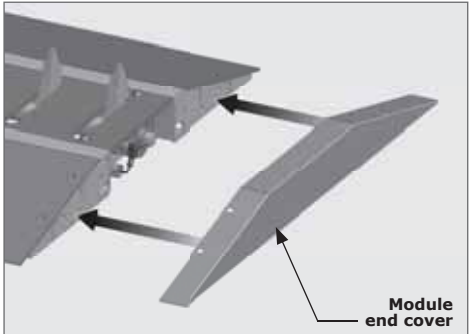
STEP 5

FIGURE 53



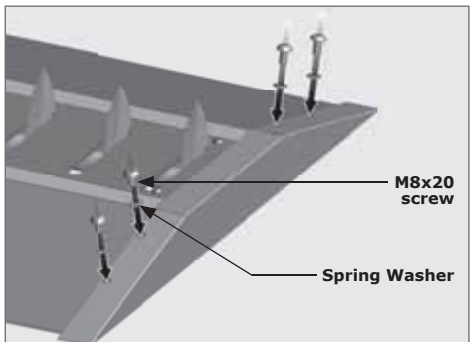
STEP 6

FIGURE 54



STEP 7

FIGURE 55



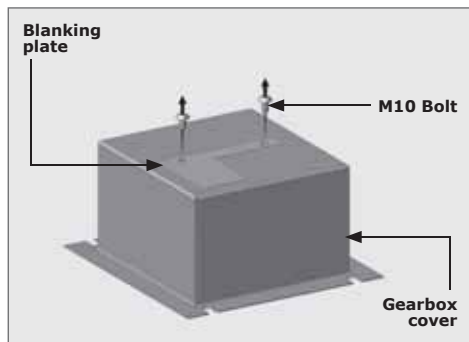
STEP 8

FIGURE 56

7.4. Integrating the SECTOR II with the CLAWS

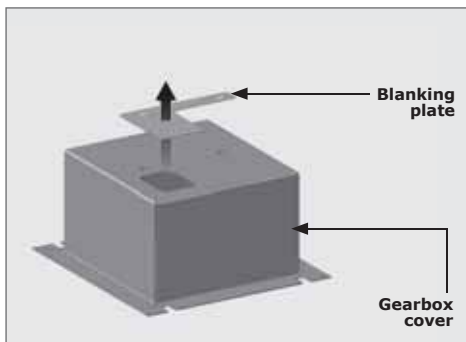
7.4.1. Directly mount THE SECTOR II onto the Independent Drive

7.4.1.1. Placing the gearbox cover into position



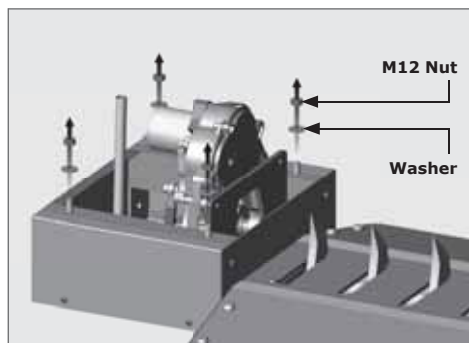
STEP 1

FIGURE 57



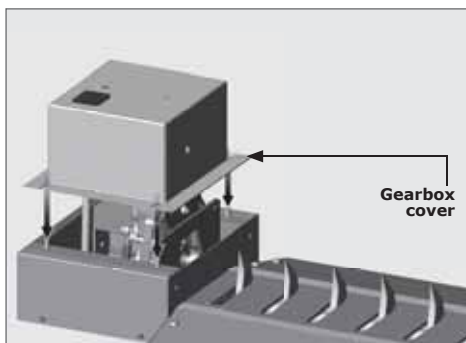
STEP 2

FIGURE 58



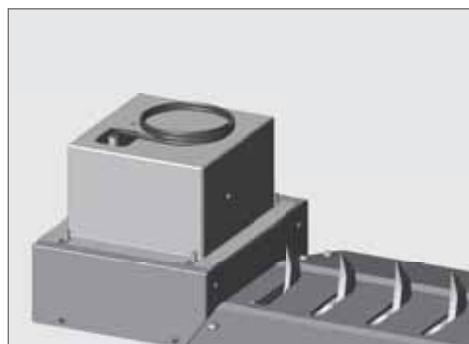
STEP 3

FIGURE 59



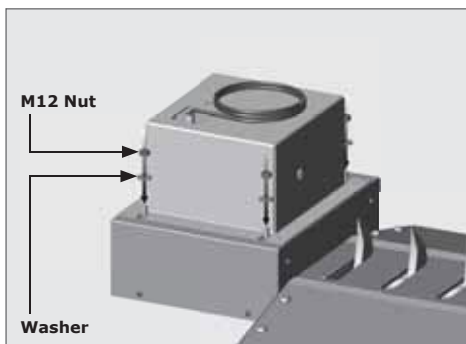
STEP 4

FIGURE 60



STEP 5

FIGURE 61



STEP 6

FIGURE 62

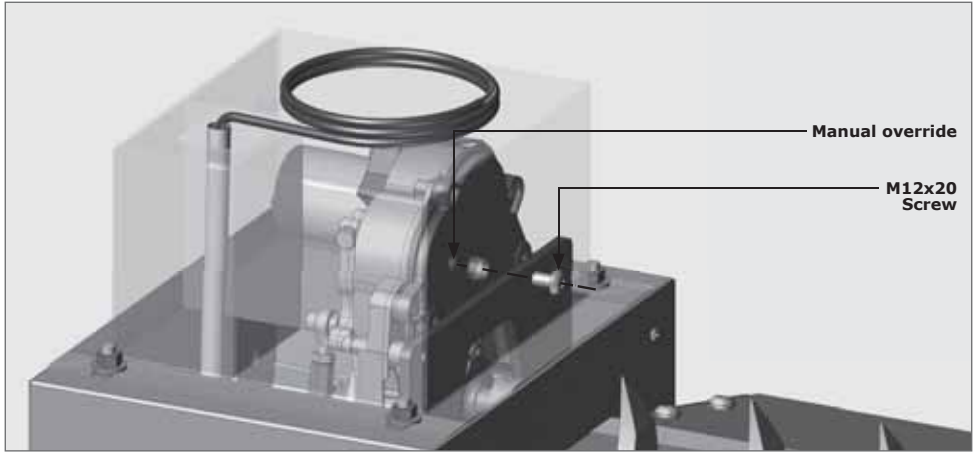
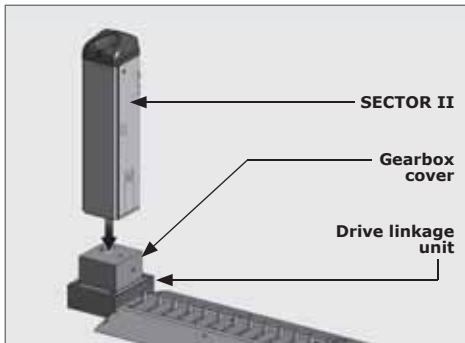
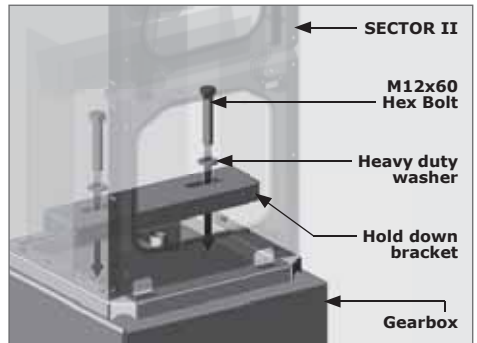


FIGURE 63. MANUAL OVERRIDE

7.4.1.2. Placing the SECTOR II into position



STEP 1 FIGURE 64



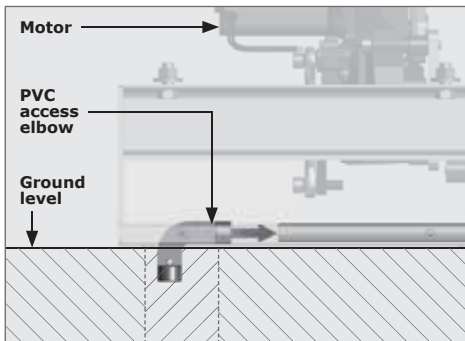
STEP 2 FIGURE 65

7.4.2. Separately-placed CLAWS and SECTOR II

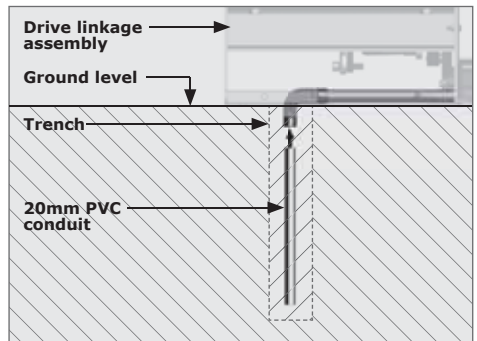
7.4.2.1. Running the conduit from the gearbox to the SECTOR II

STEP 1

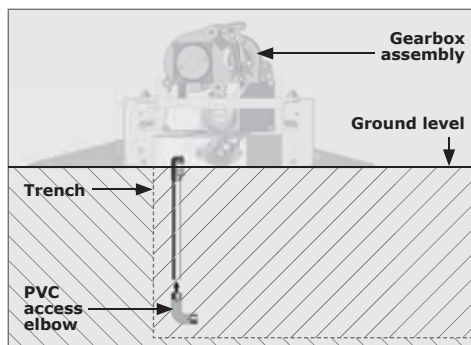
Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.



STEP 2 FIGURE 66

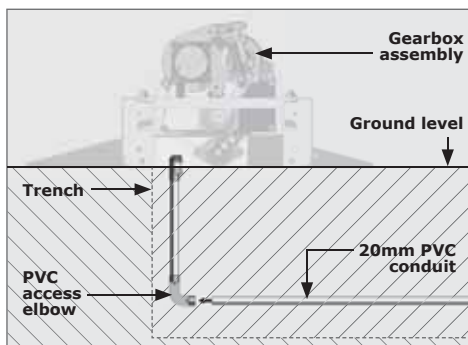


STEP 3 FIGURE 67



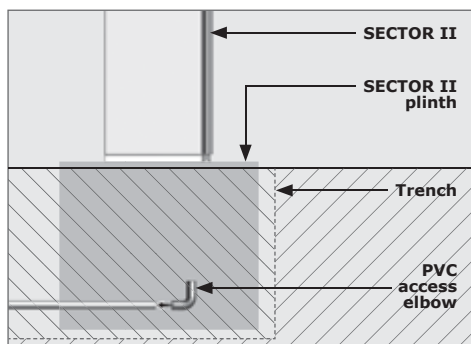
STEP 4

FIGURE 68



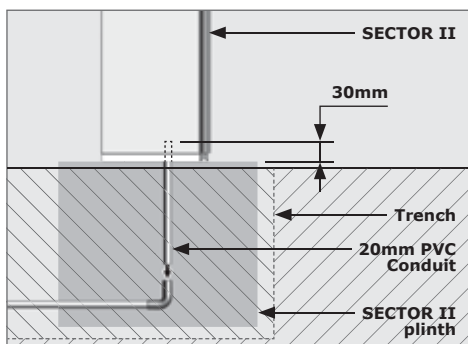
STEP 5

FIGURE 69



STEP 6

FIGURE 70



STEP 7

FIGURE 71

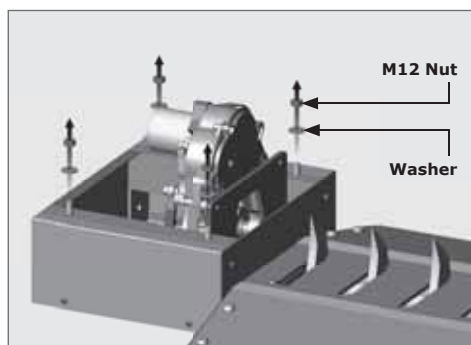
STEP 8

Route the **CLAWS** and Proximity sensor cables in the conduit to the SECTOR II.

STEP 9

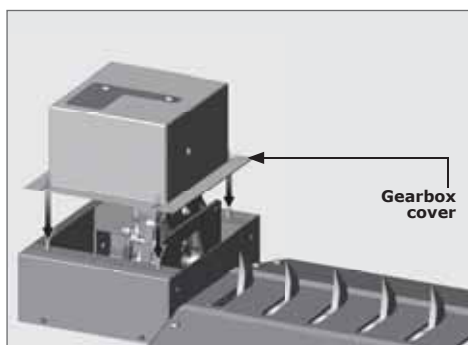
Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

7.4.2.2. Placing the gearbox cover into position



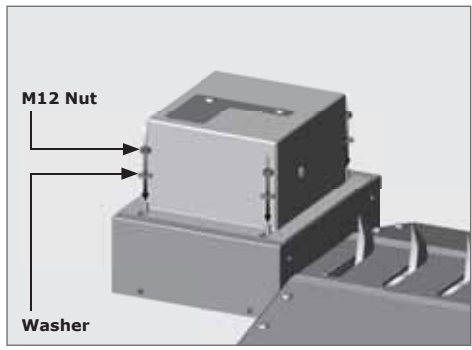
STEP 1

FIGURE 72



STEP 2

FIGURE 73



STEP 3

FIGURE 74

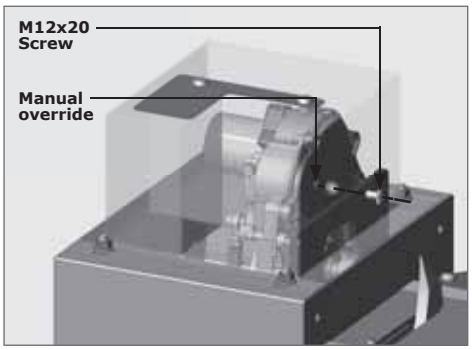
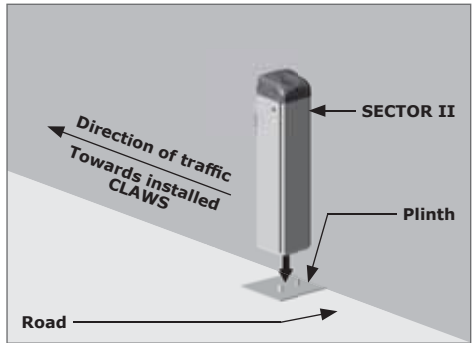


FIGURE 75. MANUAL OVERRIDE



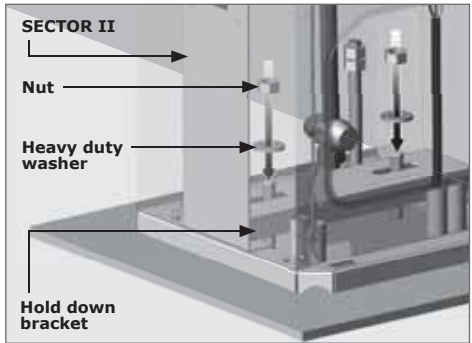
By removing the M12x20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.

7.4.2.3. Placing the SECTOR II into position



STEP 1

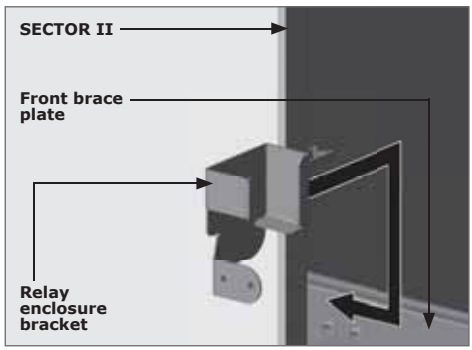
FIGURE 76



STEP 2

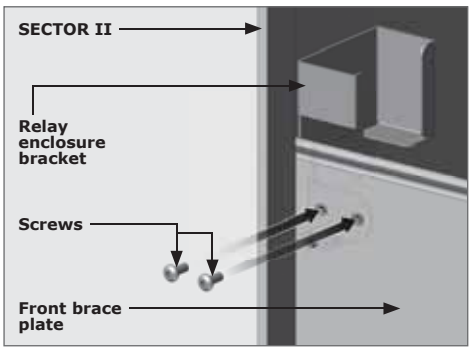
FIGURE 77

7.4.3. Fitting the relay enclosure and its bracket



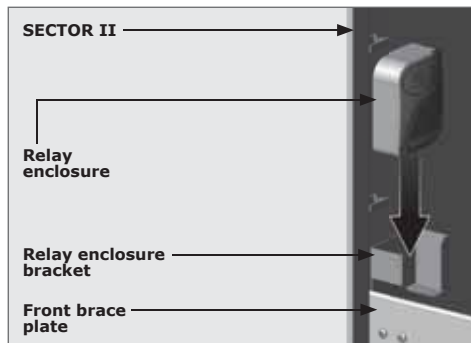
STEP 1

FIGURE 78



STEP 2

FIGURE 79



STEP 1

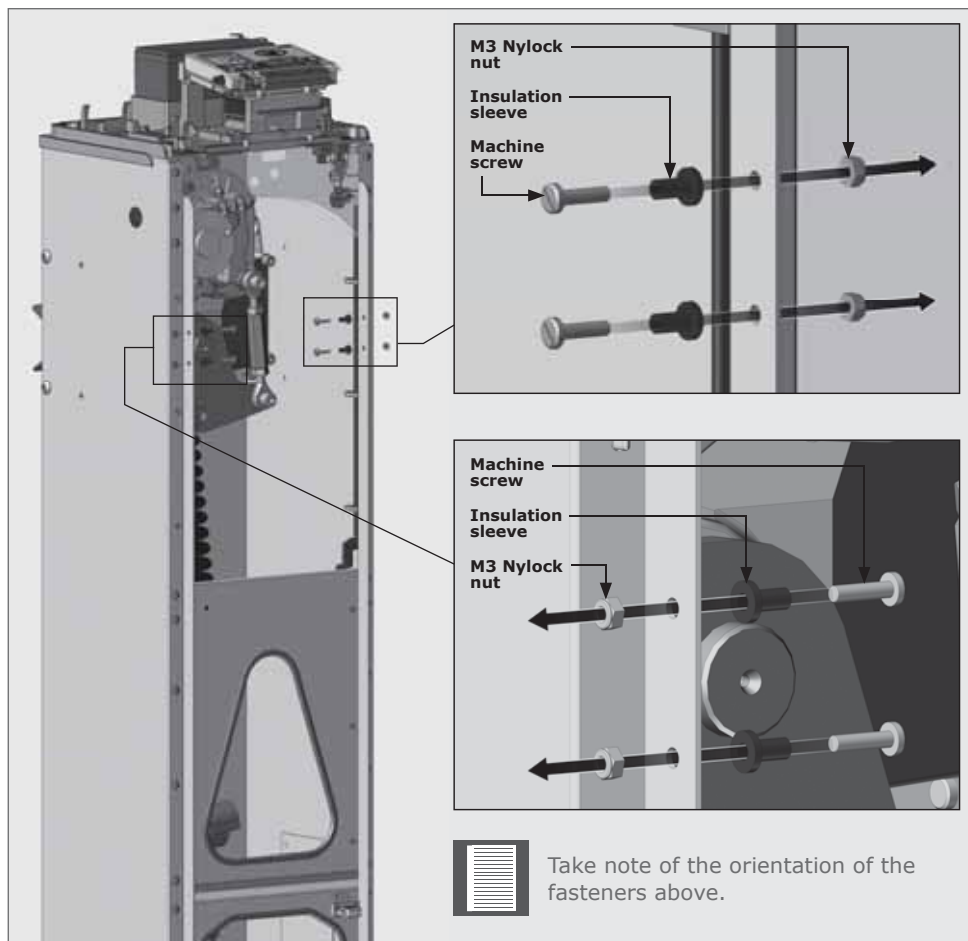
FIGURE 80

Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 16).



Complete the installation of the SECTOR II as per its full installation manual.

7.4.5. Fitting the CLAWS controller to the SECTOR II



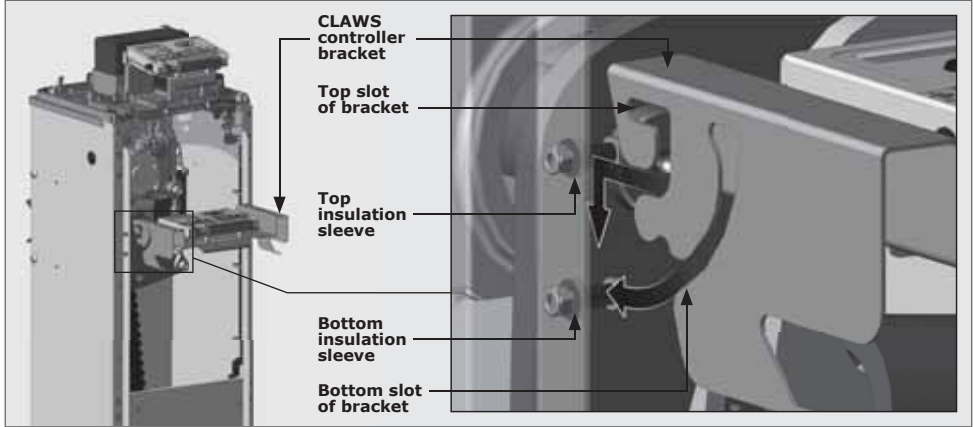
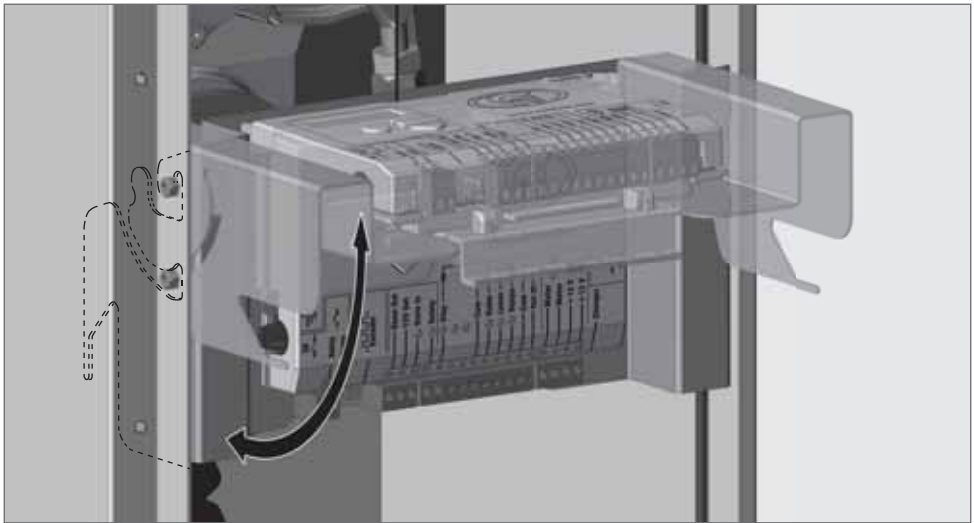
STEP 1

FIGURE 81

Take note of the orientation of the fasteners above.

STEP 2

Keeping the **CLAWS** Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.

**FIGURE 82****FIGURE 83**

The bracket can be moved into a set angle of 70° by pivoting it upward from the bottom for better viewing of the LCD screen (Section 7, Figure 84).

It can also be moved lower down for optimum space when working on the gearbox (Section 7, Figure 85).



Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 7, Figure 82).

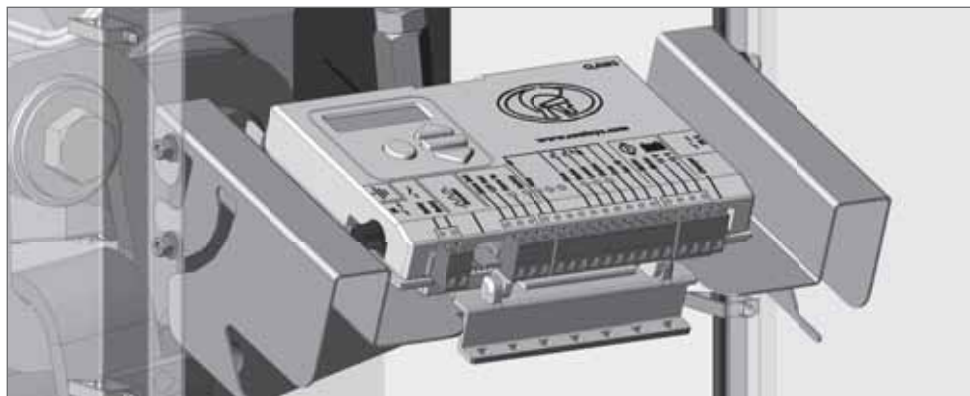


FIGURE 84. CLAWS CONTROLLER AND BRACKET AT FIXED 70° POSITION

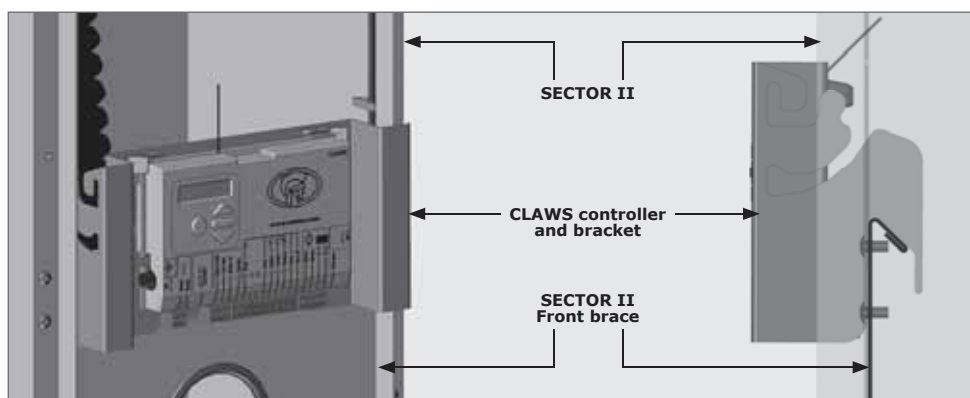


FIGURE 85. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION

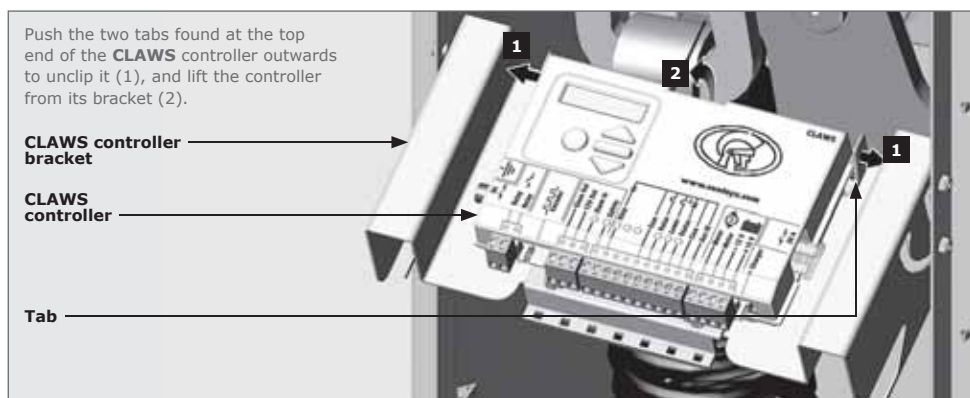


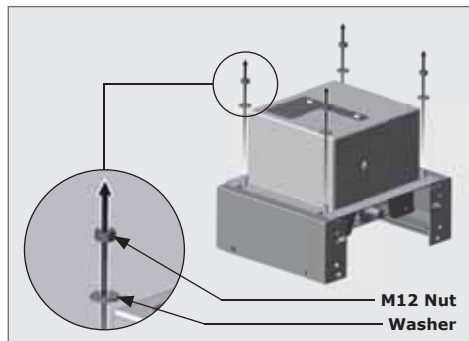
FIGURE 86. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET

STEP 3

Connect harness and power supply. Refer to the wiring diagrams and controller settings.

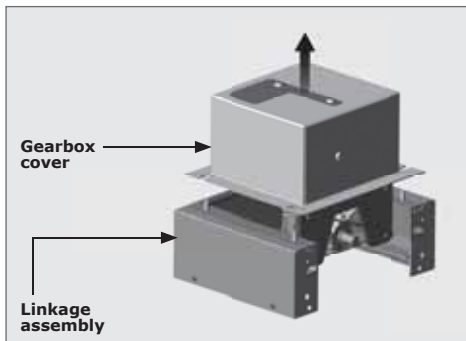
8. LHS Independent Drive Surface Mount - Opposing Direction of Travel

8.1. Preparing the Drive Linkage Assembly



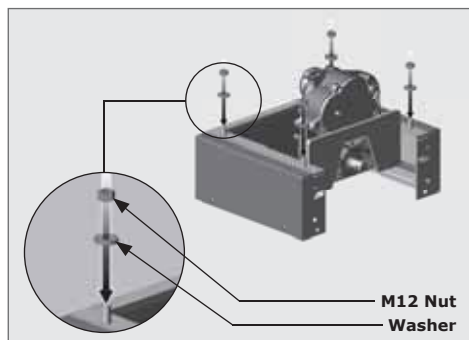
STEP 1

FIGURE 1



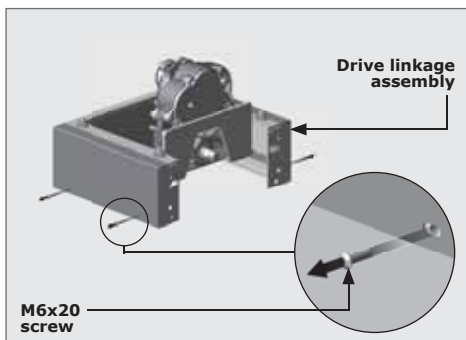
STEP 2

FIGURE 2



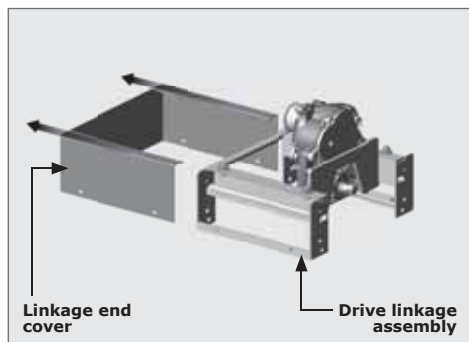
STEP 3

FIGURE 3



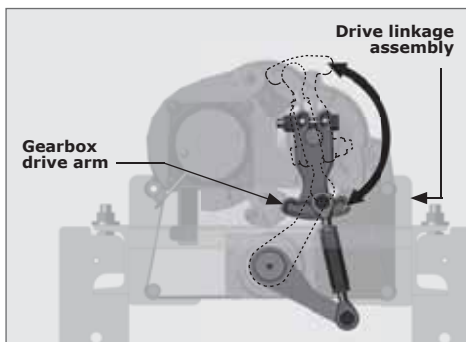
STEP 4

FIGURE 4



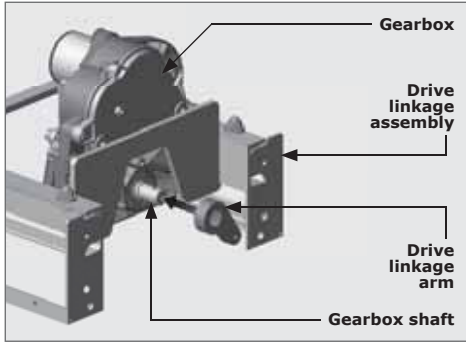
STEP 5

FIGURE 5



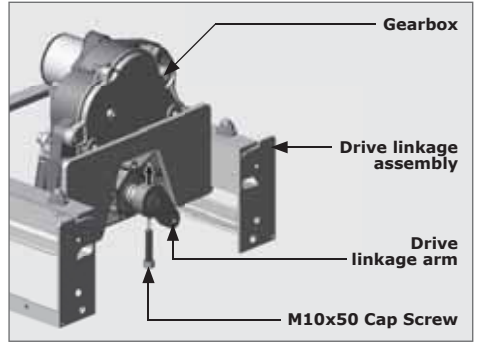
STEP 6

FIGURE 6



STEP 7

FIGURE 7

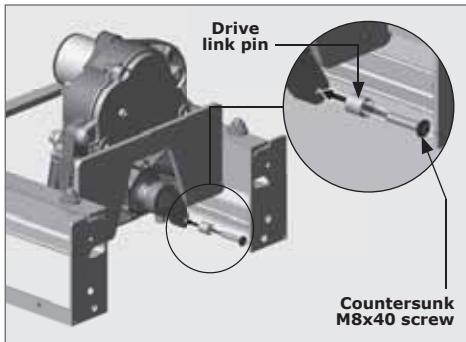


STEP 8

FIGURE 8



The drive linkage arm should point to a 5 o'clock position and the holes of the gearbox shaft and the linkage arm must line up as shown above.



STEP 9

FIGURE 9

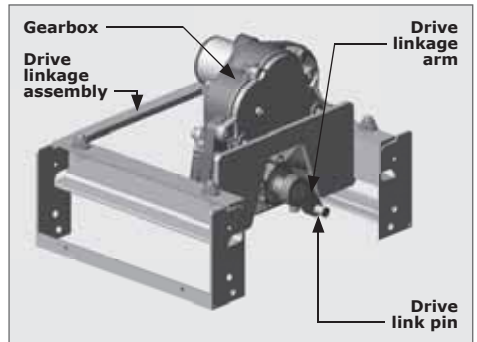


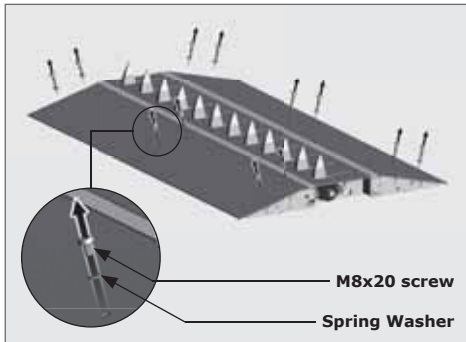
FIGURE 10



Tighten the Countersunk M8x40 screw to 20Nm (Section 8, Figure 9).

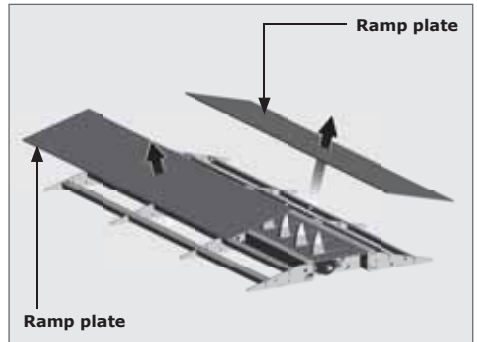
8.2. Spike Module Assembly

8.2.1. Preparing the Spike Model assembly(ies) for installation



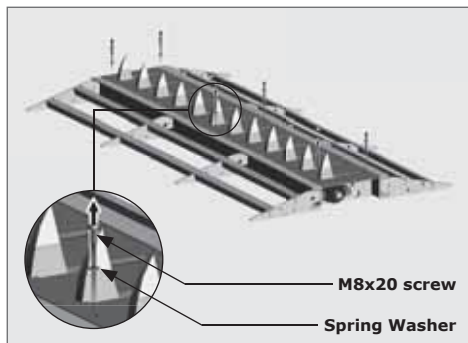
STEP 1

FIGURE 11

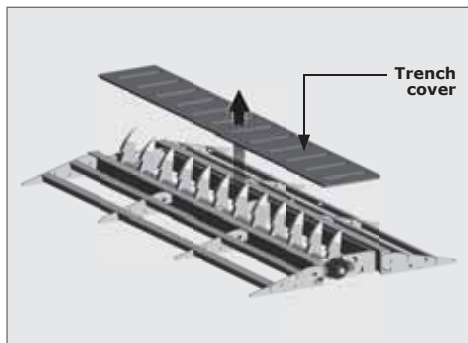


STEP 2

FIGURE 12



STEP 3 FIGURE 13

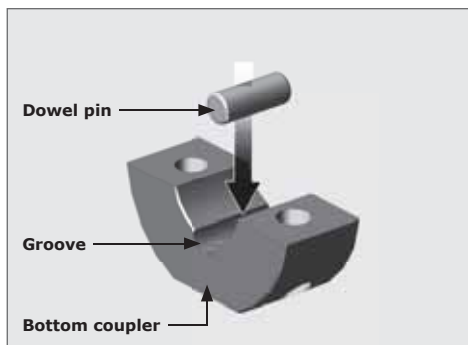


STEP 4 FIGURE 14

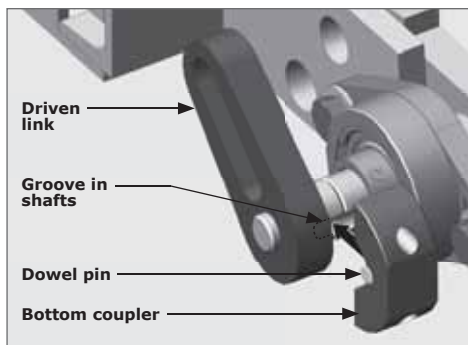
8.2.2. Attaching the Driven Link to the first spike module



Place the spikes into the down position to aid in the fitment of all the shaft couplings.



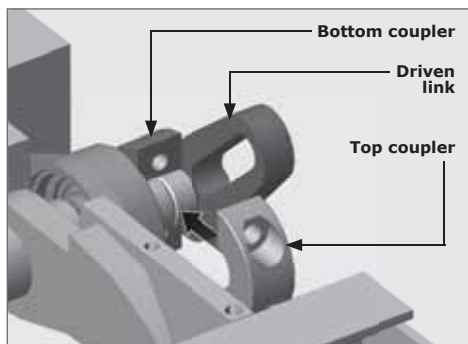
STEP 1 FIGURE 15



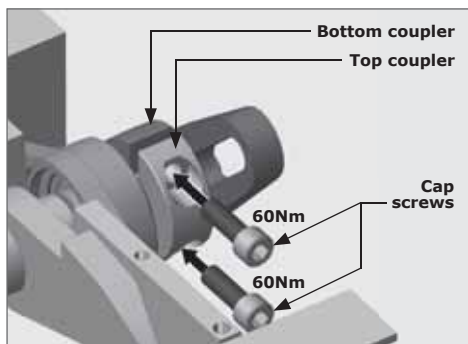
STEP 2 FIGURE 16



Ensure the Driven Link and the spikes are pointing in the same direction. (Section 8, Figures 16 to 19).



STEP 3 FIGURE 17



STEP 4 FIGURE 18

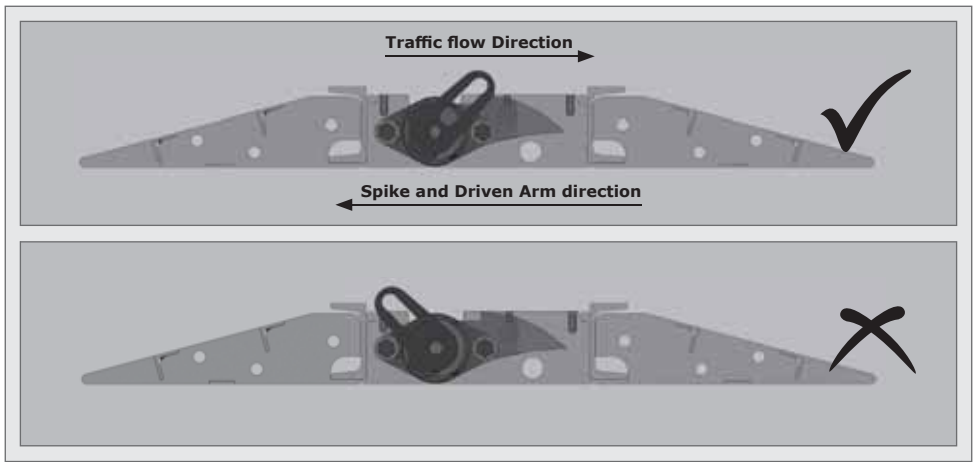


FIGURE 19

8.2.3. Aligning the Driven Linkage Arm to the Drive Linkage Arm.

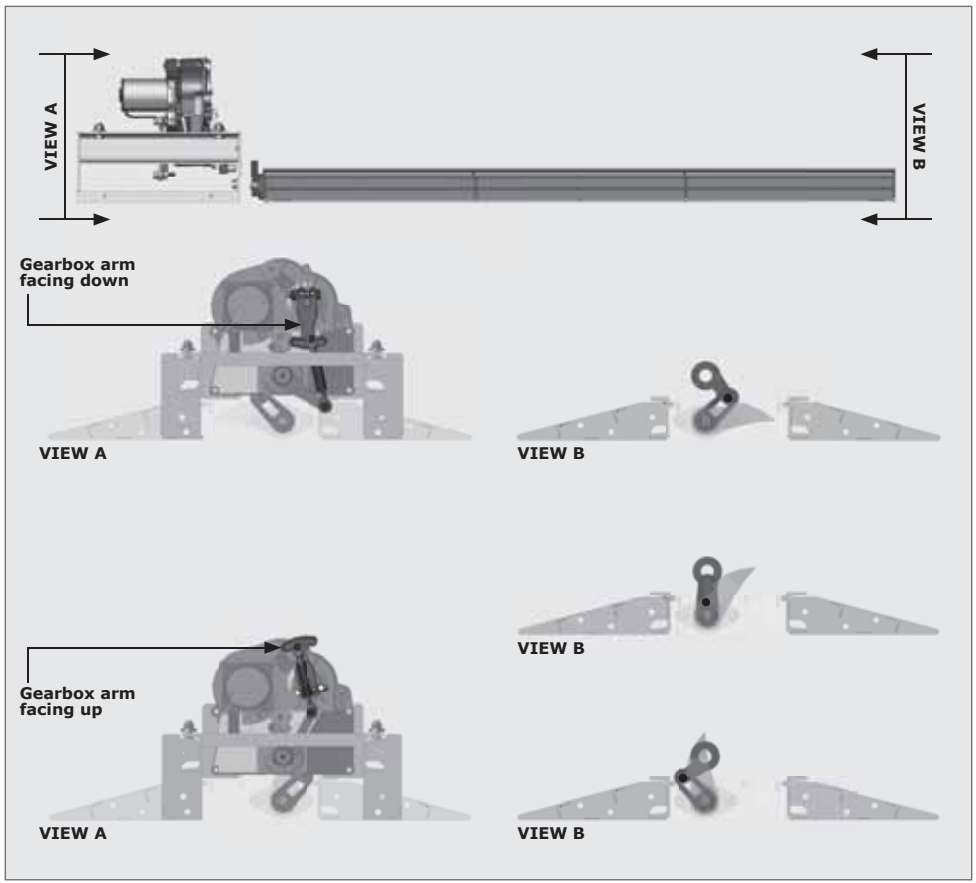
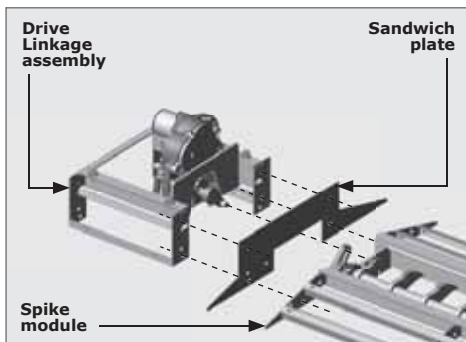


FIGURE 20

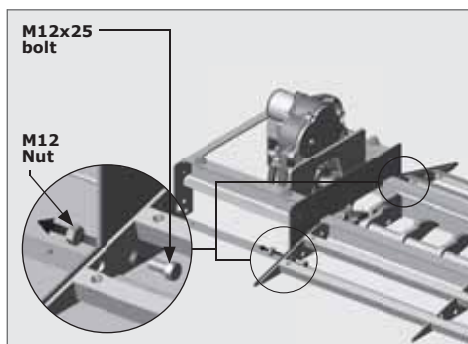
8.2.4. Attaching the drive linkage assembly to the spike module

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly. Ensure that the Sandwich Plate is lifted over the Driven Linkage Arm, so that the Driven Linkage Arm sits flush with the Drive Linkage Arm (Section 8, Figure 21).



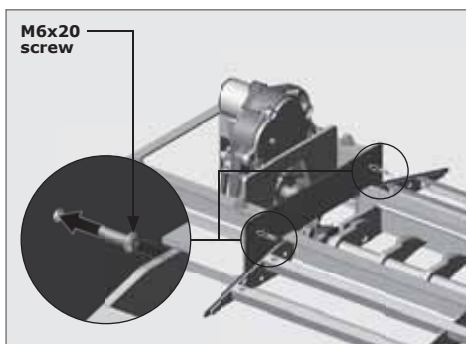
STEP 1

FIGURE 21



STEP 2

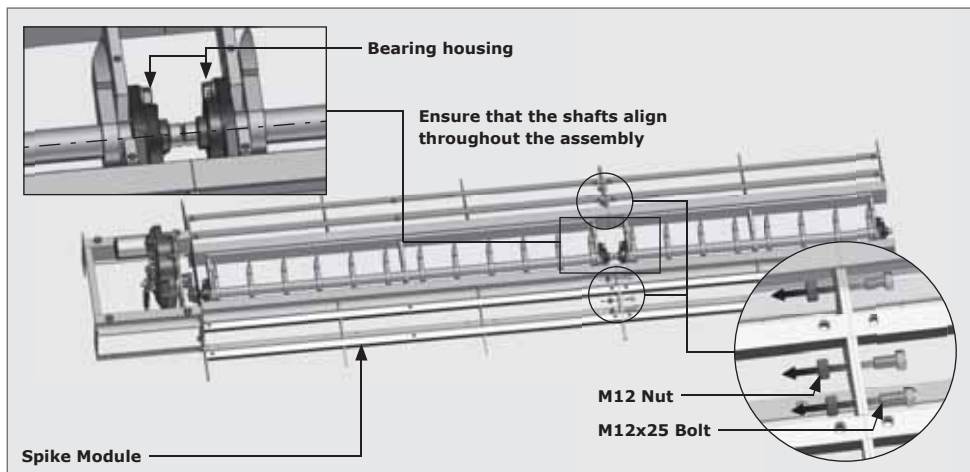
FIGURE 22



STEP 3

FIGURE 23

Using six M12x25 bolts, fix one spike module to another (Section 8, Figure 24).



STEP 4

FIGURE 24



To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

8.2.5. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.



It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.

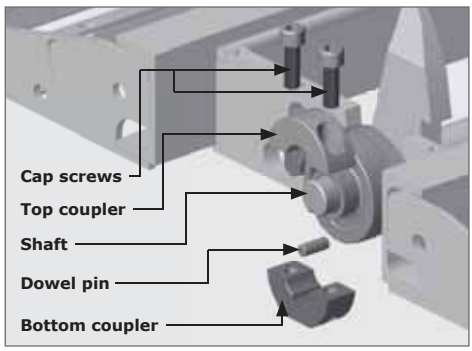


FIGURE 25. SHAFT COUPLER

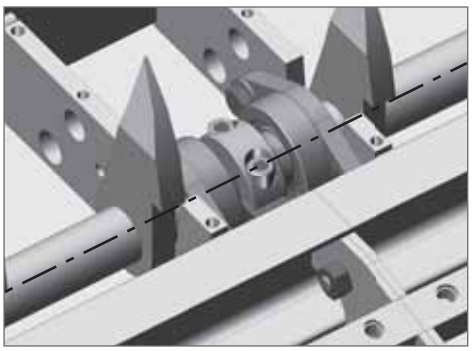
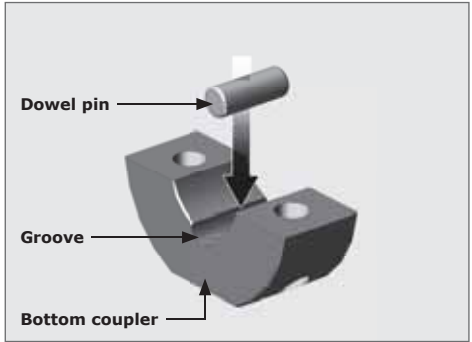


FIGURE 26

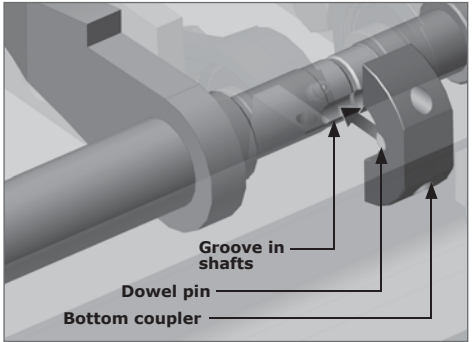


Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.



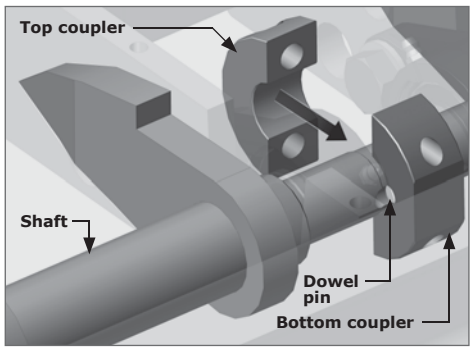
STEP 1

FIGURE 27



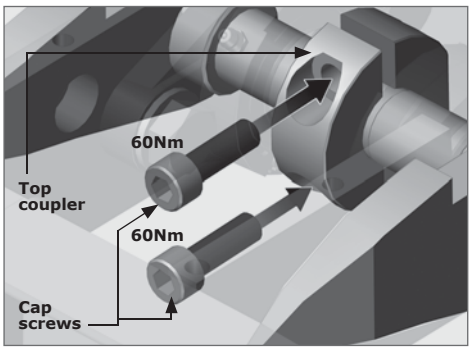
STEP 2

FIGURE 28



STEP 3

FIGURE 29



STEP 4

FIGURE 30

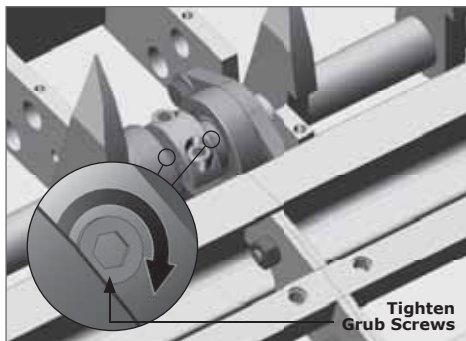
STEP 7

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.



STEP 5

FIGURE 31



STEP 6

FIGURE 32

8.2.6. Bolting down the assembly to the ground

If the **SECTOR II** and **CLAWS** are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and **SECTOR II**. (Section 8.4.2.)

These must be done before bolting the assembly to the ground. Once this preparation work has been completed, proceed with the installation below.

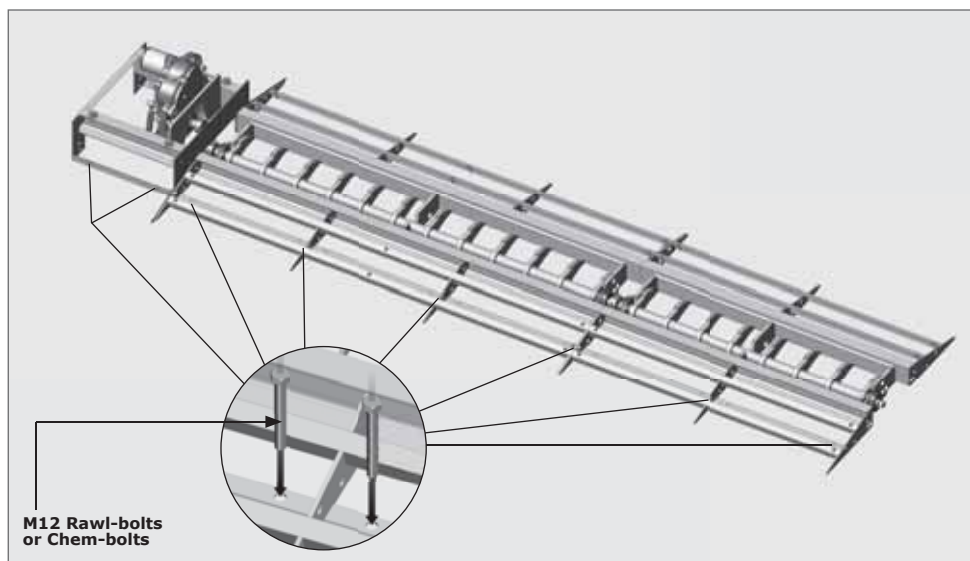
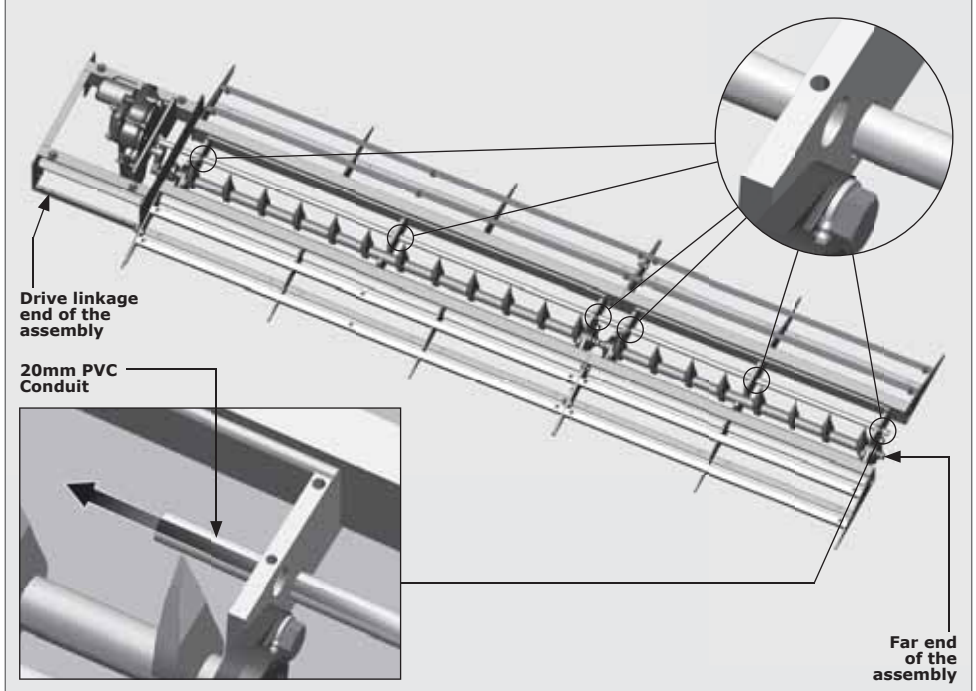


FIGURE 33



It is crucial that the surface it's mounted on is a reasonably even surface as an uneven surface could result in an uneven binding of the spike shafts. This will result in premature failure.

8.2.5. Proximity sensor installation



STEP 1

FIGURE 34



The length of the PVC conduit will be relative to the length of the spike modules and drive linkage unit combined. Ensure that a further 38mm is added to this to account for the modules and coupling (Refer to Section 8, Figure 35).

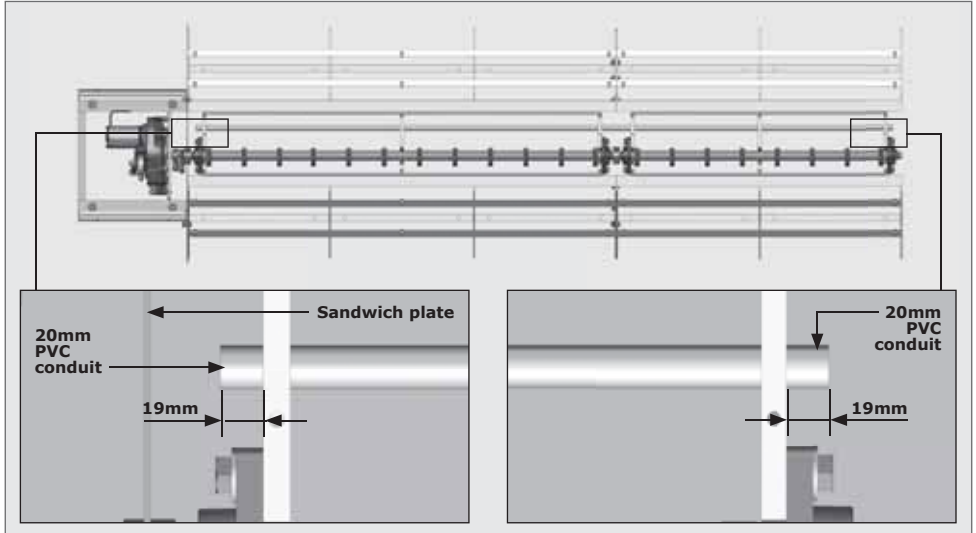
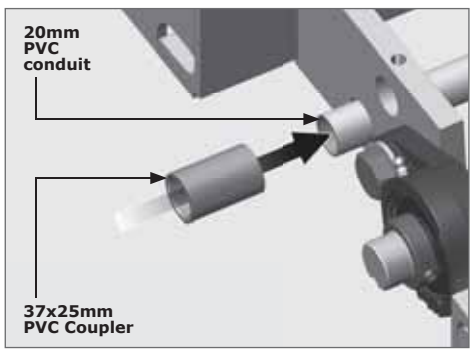


FIGURE 35

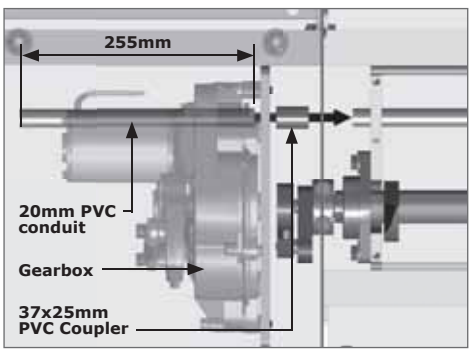


Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.



STEP 2

FIGURE 36

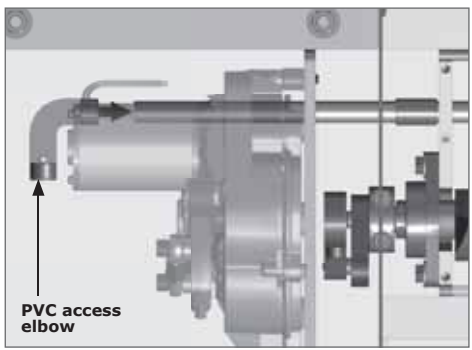


STEP 3

FIGURE 37

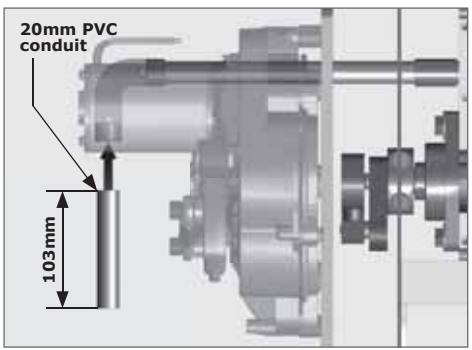


Steps 4-7 is only applicable if the SECTOR II will be mounted directly onto the **CLAWS** Gearbox. If they are going to be mounted separately, a trench for the conduit and proximity sensor cable will need to be dug (Section 8.4.2.).



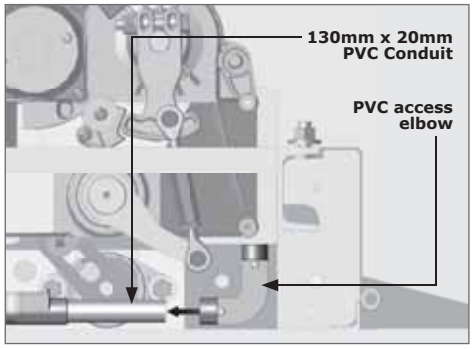
STEP 4

FIGURE 38



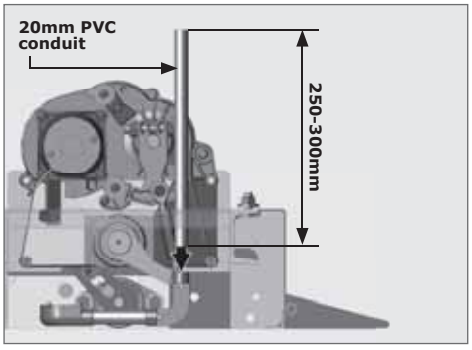
STEP 5

FIGURE 39



STEP 6

FIGURE 40



STEP 7

FIGURE 41



Please ensure that the moving mechanical parts do not rub against the conduit or cables.

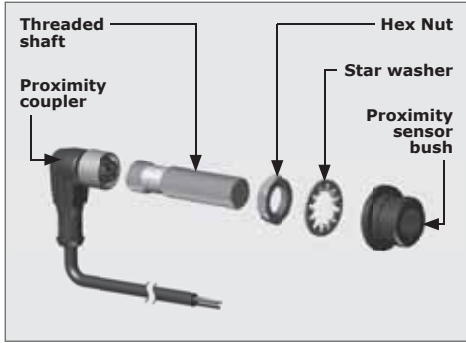


FIGURE 42. PROXIMITY SENSOR

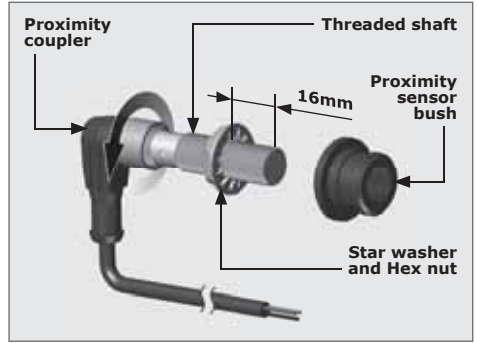


FIGURE 43. PROXIMITY SENSOR

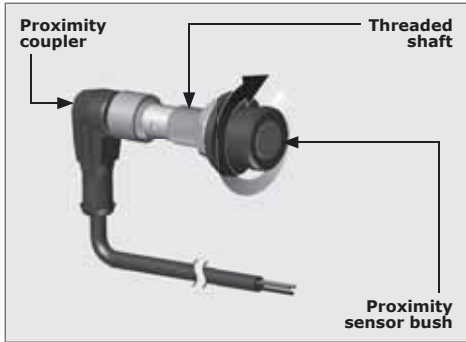
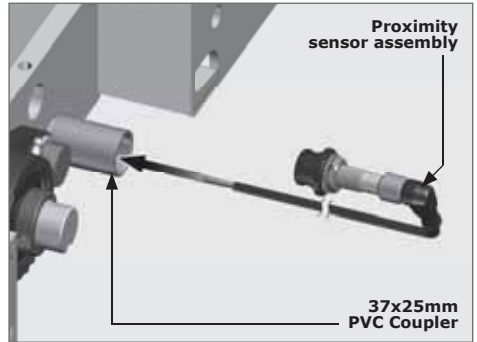


FIGURE 44. PROXIMITY SENSOR



STEP 8

FIGURE 45

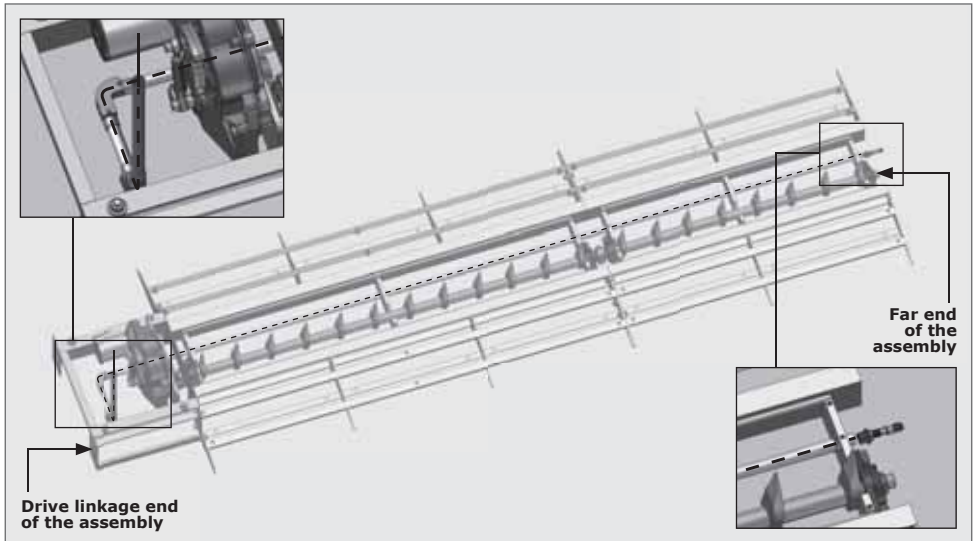
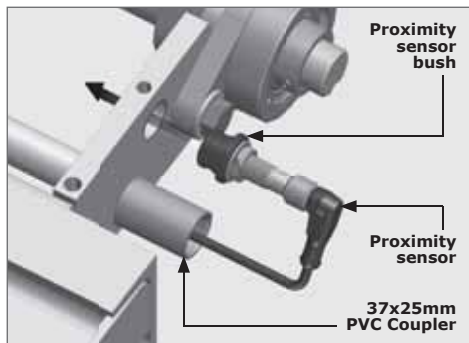


FIGURE 46

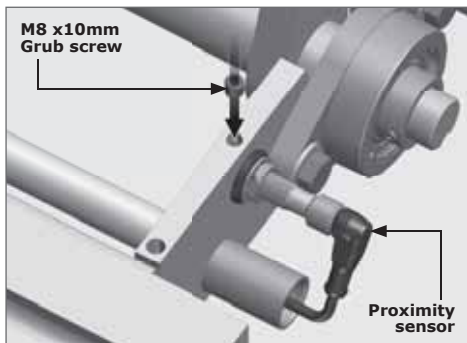


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed to the SECTOR II at a later stage.



STEP 9

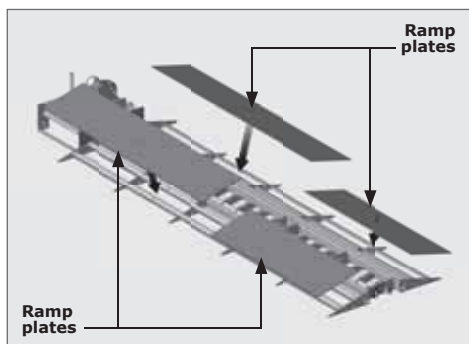
FIGURE 47



STEP 10

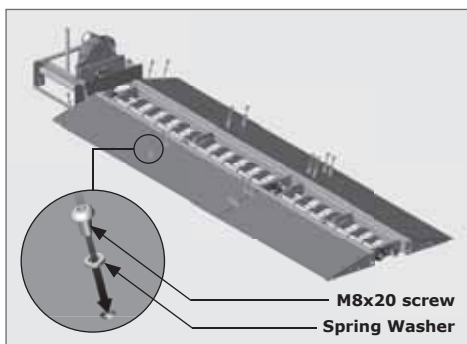
FIGURE 48

8.3. Re-assembling the ramp plates and linkage cover



STEP 1

FIGURE 49

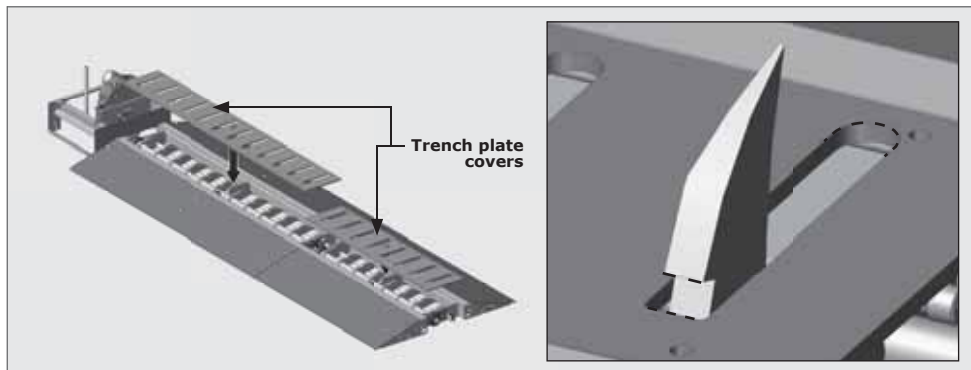


STEP 2

FIGURE 50



Leave out the four M8 screws and Spring Washers on the far end of the assembly as the module end cover will be assembled later.

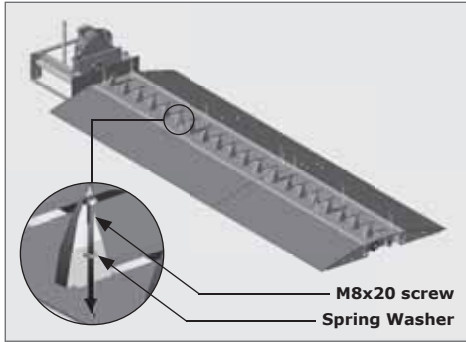


STEP 3

FIGURE 51

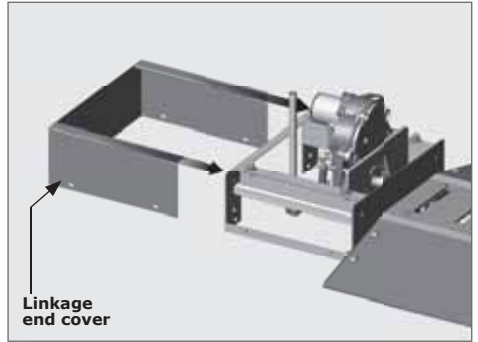


Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.



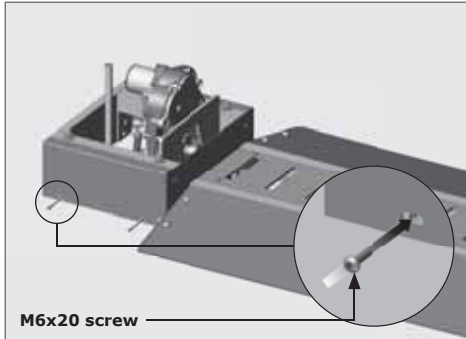
STEP 4

FIGURE 52



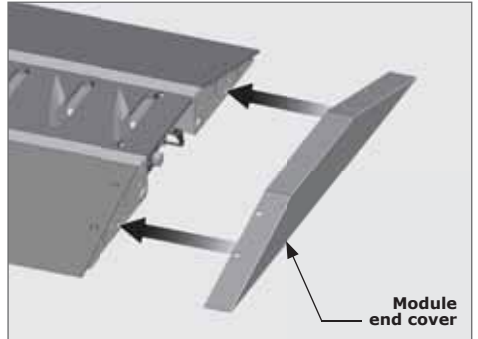
STEP 5

FIGURE 53



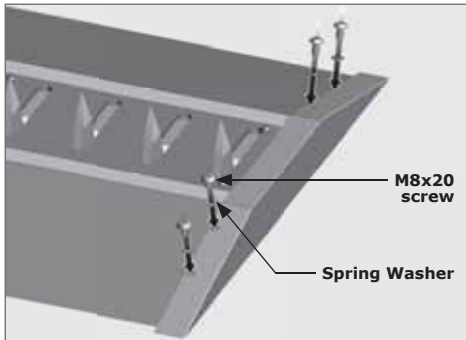
STEP 6

FIGURE 54



STEP 7

FIGURE 55



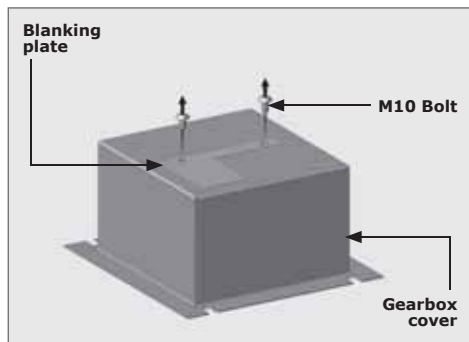
STEP 8

FIGURE 56

8.4. Integrating the SECTOR II with the CLAWS

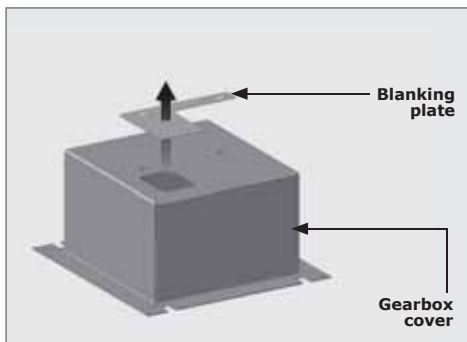
8.4.1. Directly mount THE SECTOR II onto the Independent Drive

8.4.1.1. Placing the gearbox cover into position



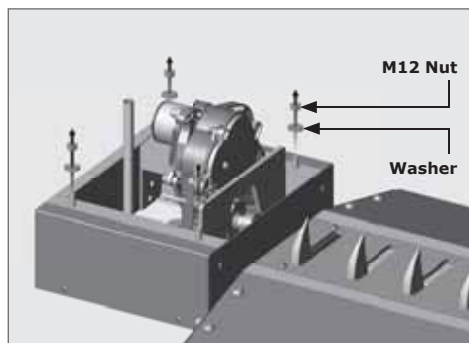
STEP 1

FIGURE 57



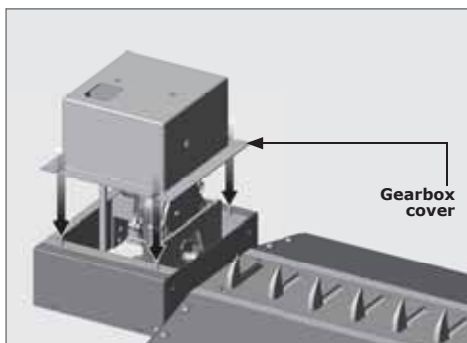
STEP 2

FIGURE 58



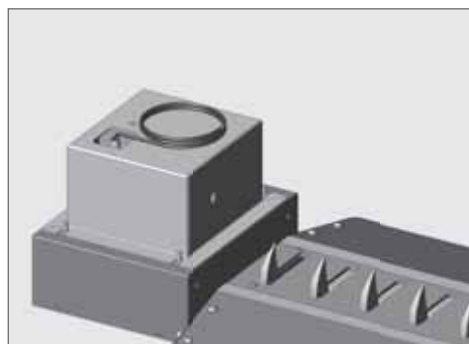
STEP 3

FIGURE 59



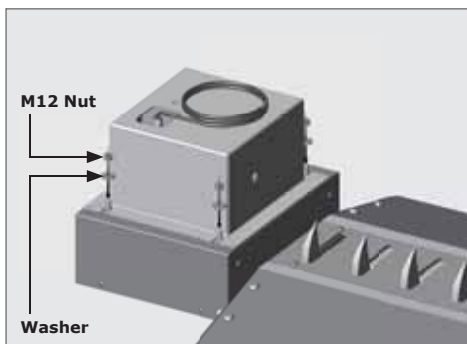
STEP 4

FIGURE 60



STEP 5

FIGURE 61



STEP 6

FIGURE 62

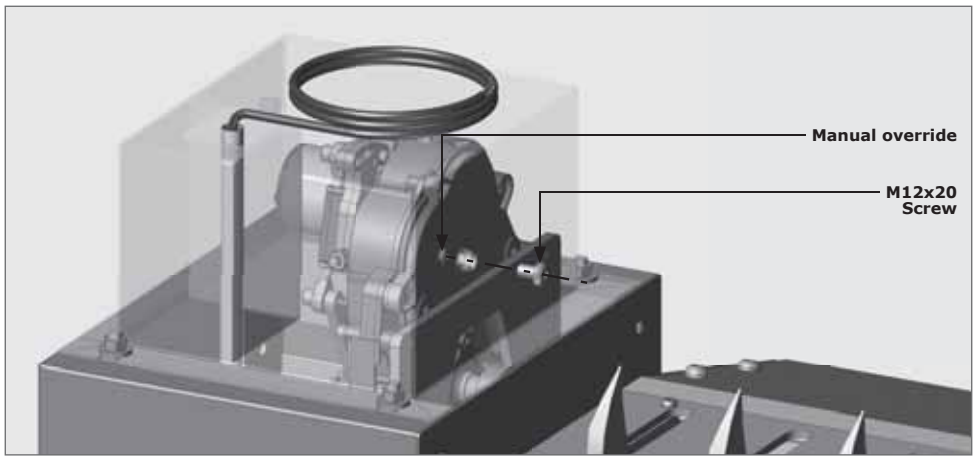
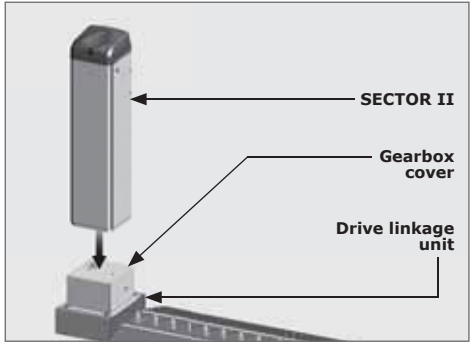
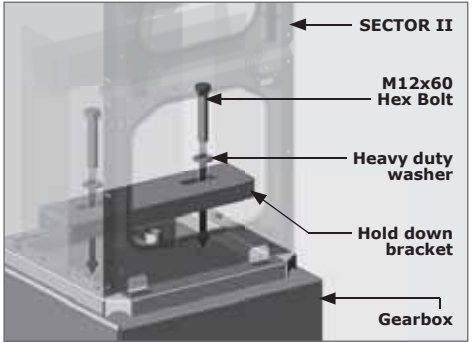


FIGURE 63. MANUAL OVERRIDE

8.4.1.2. Placing the SECTOR II into position



STEP 1 FIGURE 64



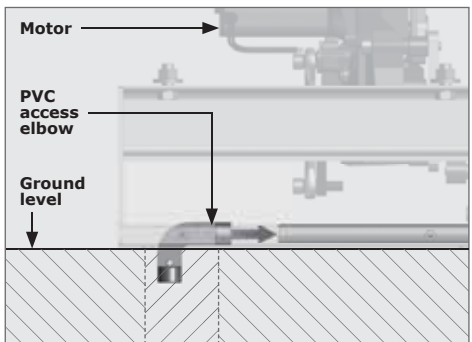
STEP 2 FIGURE 65

8.4.2. Separately-placed CLAWS and SECTOR II

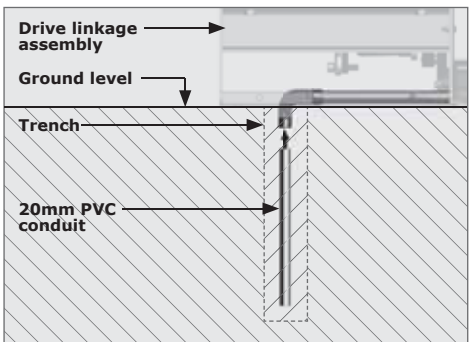
8.4.2.1. Running the conduit from the gearbox to the SECTOR II

STEP 1

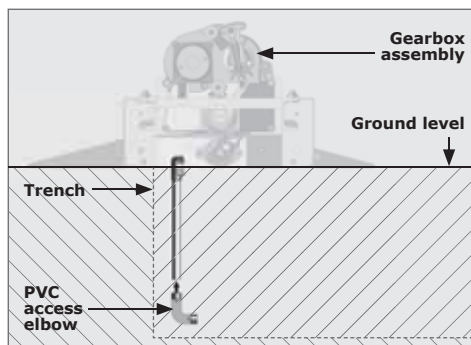
Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.



STEP 2 FIGURE 66

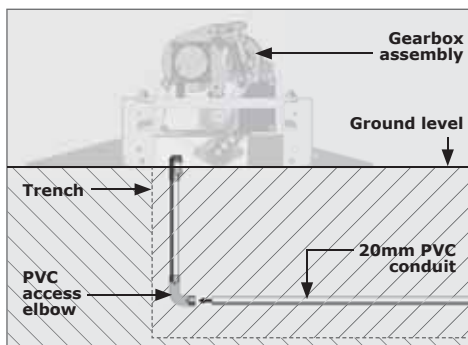


STEP 3 FIGURE 67



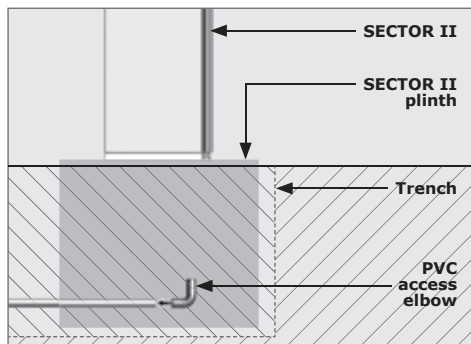
STEP 4

FIGURE 68



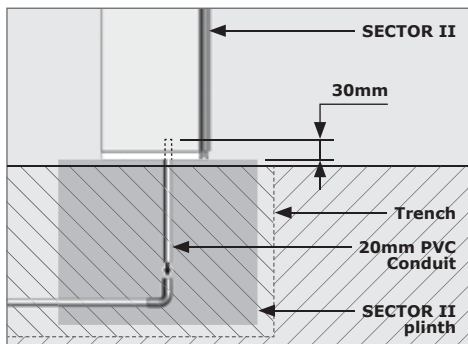
STEP 5

FIGURE 69



STEP 6

FIGURE 70



STEP 7

FIGURE 71

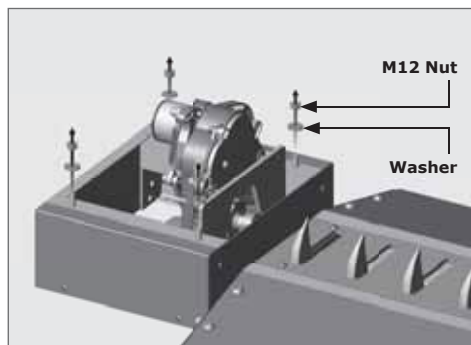
STEP 8

Route the **CLAWS** and Proximity sensor cables in the conduit to the SECTOR II.

STEP 9

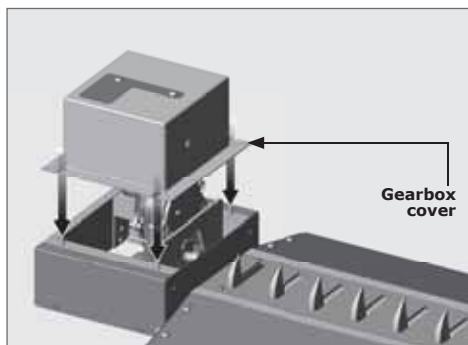
Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

8.4.2.2. Placing the gearbox cover into position



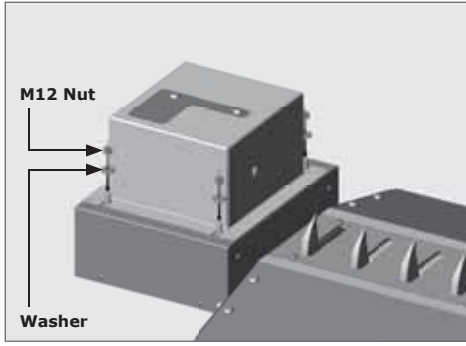
STEP 1

FIGURE 72



STEP 2

FIGURE 73



STEP 3

FIGURE 74

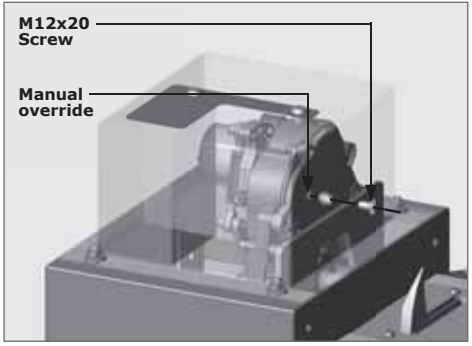
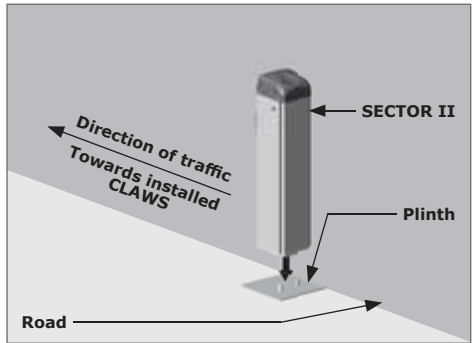


FIGURE 75. MANUAL OVERRIDE



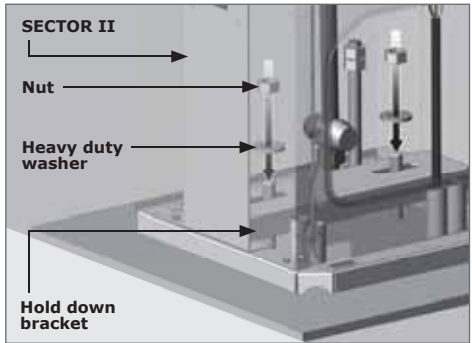
By removing the M12x20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.

8.4.2.3. Placing the SECTOR II into position



STEP 1

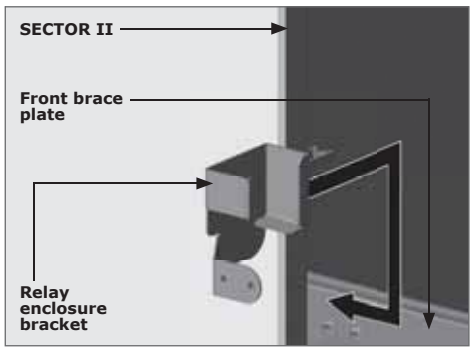
FIGURE 76



STEP 2

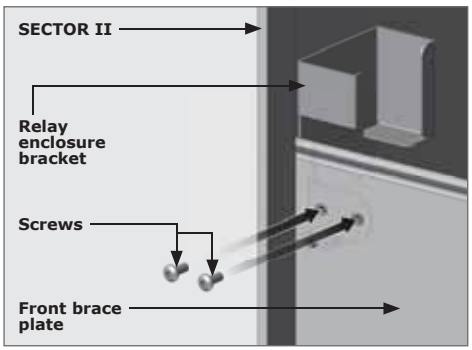
FIGURE 77

8.4.3. Fitting the relay enclosure and its bracket



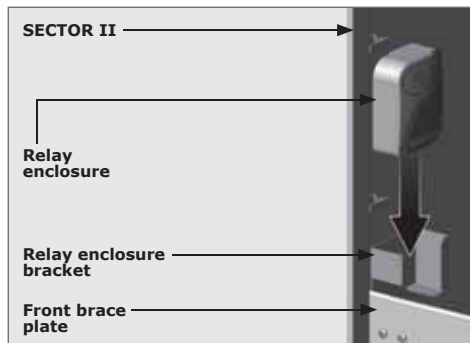
STEP 1

FIGURE 78



STEP 2

FIGURE 79



STEP 1

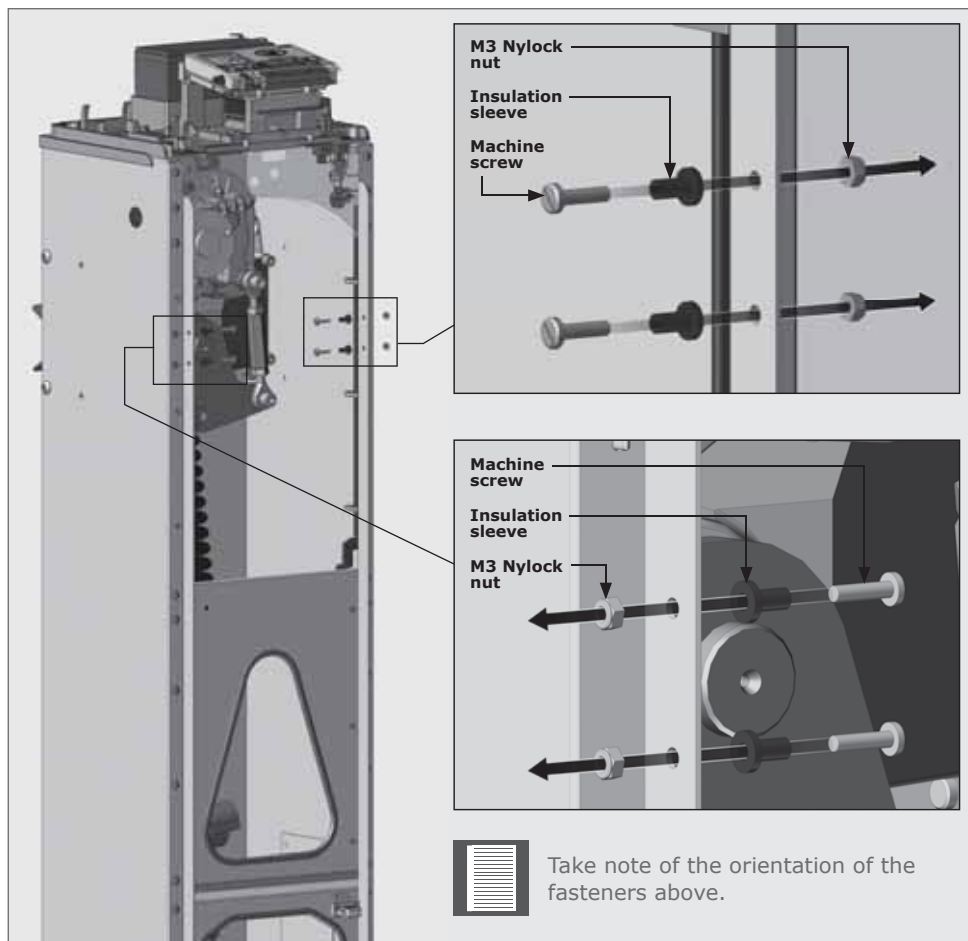
FIGURE 80

Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 16).



Complete the installation of the SECTOR II as per its full installation manual.

8.4.5. Fitting the CLAWS controller to the SECTOR II



STEP 1

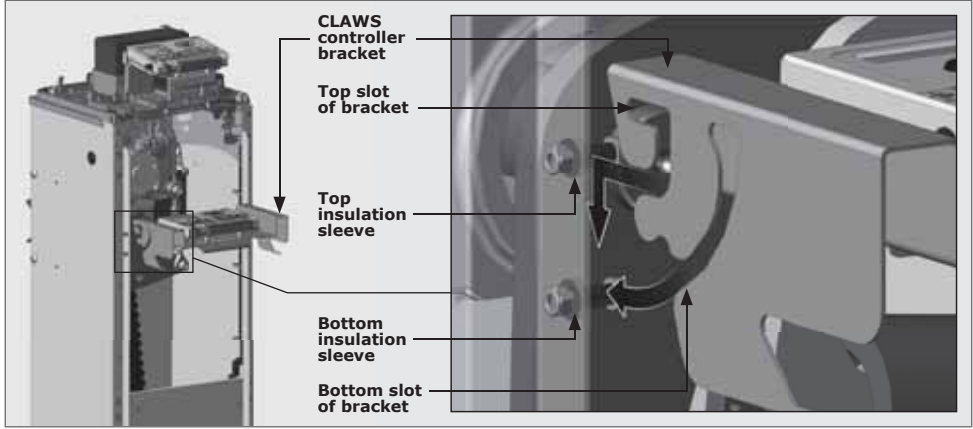
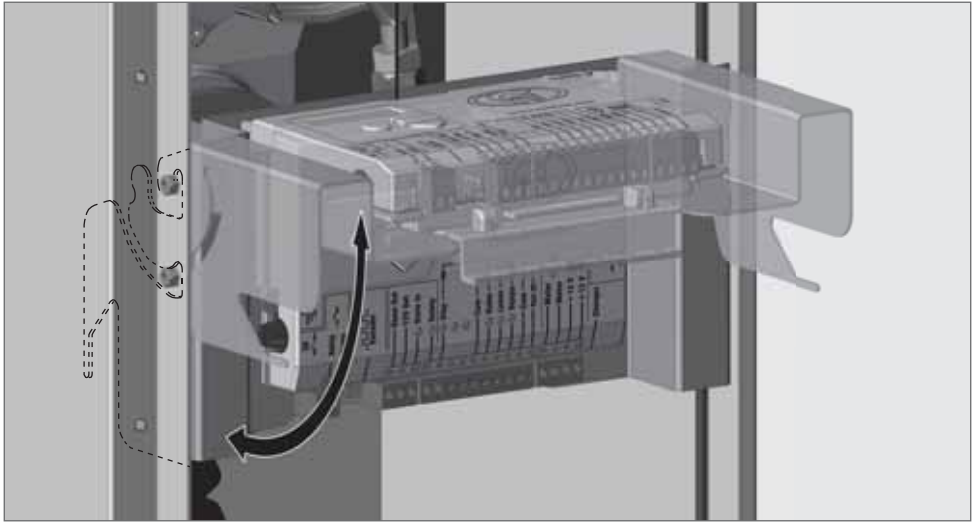
FIGURE 81



Take note of the orientation of the fasteners above.

STEP 2

Keeping the **CLAWS** Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.

**FIGURE 82****FIGURE 83**

The bracket can be moved into a set angle of 70° by pivoting it upward from the bottom for better viewing of the LCD screen (Section 8, Figure 84).

It can also be moved lower down for optimum space when working on the gearbox (Section 8, Figure 85).



Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 8, Figure 82).

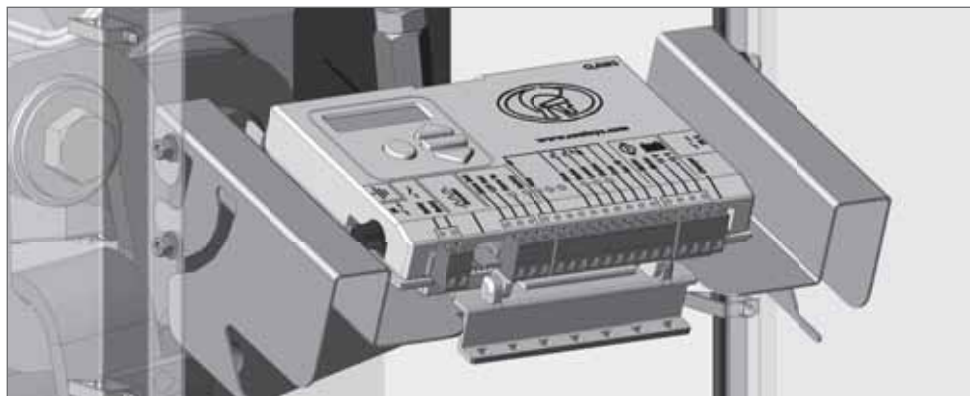


FIGURE 84. CLAWS CONTROLLER AND BRACKET AT FIXED 70° POSITION

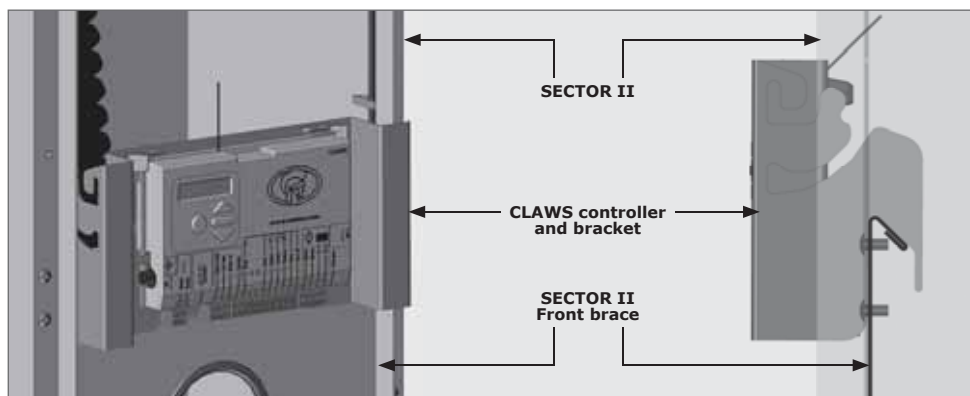


FIGURE 85. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION

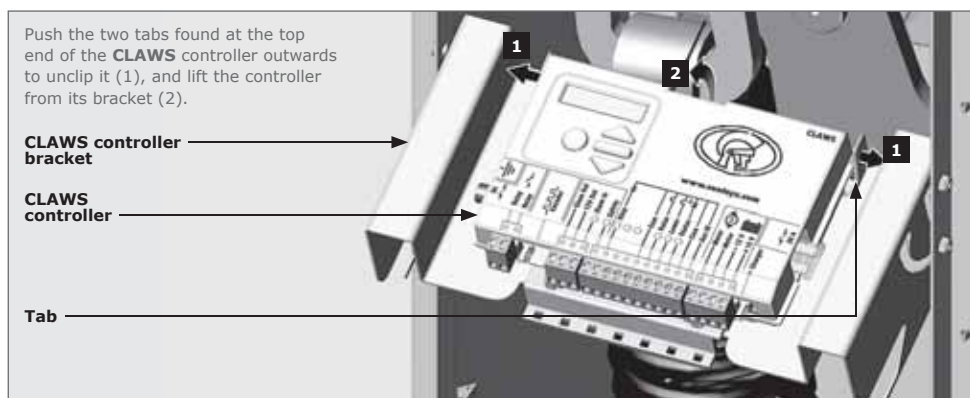


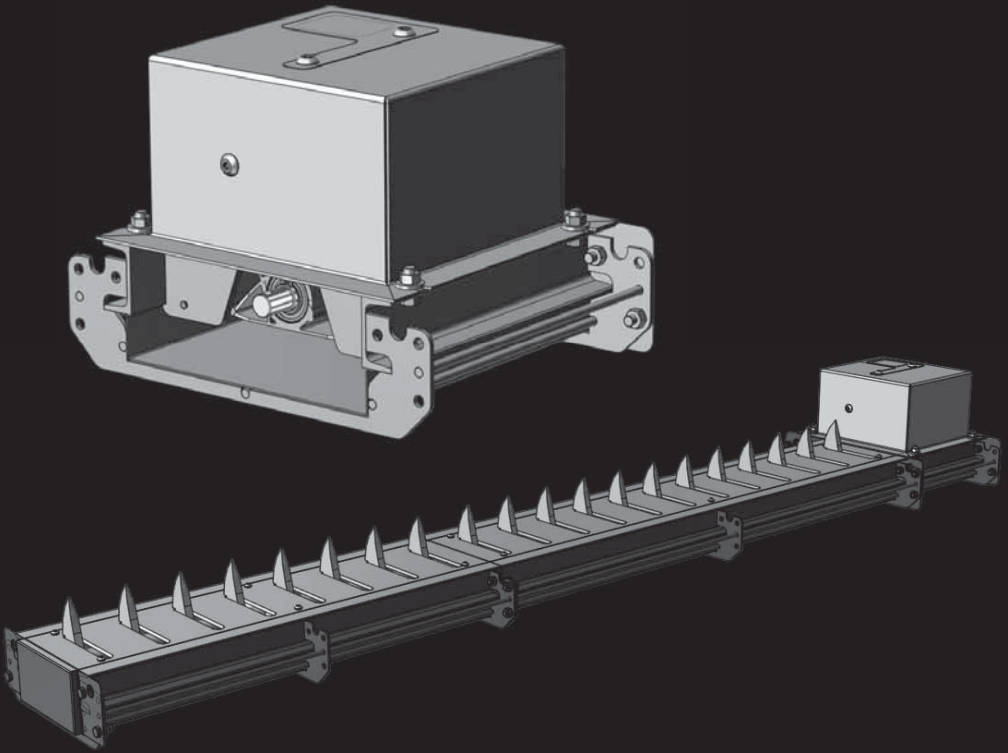
FIGURE 86. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET

STEP 3

Connect harness and power supply. Refer to the wiring diagrams and controller settings.

Independent Drive Flush Mount Installations

CLAWS



9. Product Identification

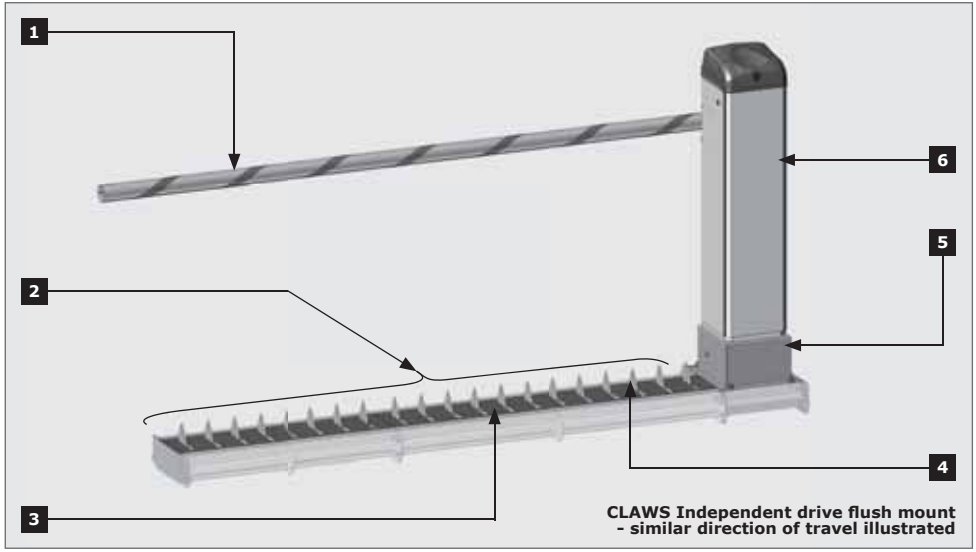











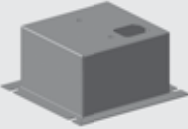



FIGURE 1. PRODUCT IDENTIFICATION

- 1. Boom pole
- 2. Spikes module assembly
- 3. Trench cover plate
- 4. Spikes
- 5. Drive linkage assembly
- 6. SECTOR II

	Module Frame
	Linkage Frame
	Sandwich Plate
	Top Coupler
	Bottom Coupler
	8x20 Dowel Pin

	Gearbox Coupler
	Bearing Housing
	Hold Down Bracket
	Linkage End Cover
	Blanking Plate
	Gearbox Cover
	Module End Cover

10. Tools Required

- 13mm, 17mm, and 19mm Spanners
- Ratchet
- 19mm, and 24mm Sockets
- Allen Key Set
- 20mm and 50mm Hole Saw
- Mallet
- Tape Measure
- Spirit Level
- Torque Wrench
- Conduit Spring for 20mm conduit

11. Introduction

This document describes the basic steps to follow when installing the flush-mountable **CLAWS** Spikes driven directly from a SECTOR II Barrier by a “push-pull” linkage system. The installation described in this document is a 2.5 meter installation which utilises modules of 1.5 and 1.0 meters.



The installation of the **CLAWS** Spikes requires a minimum of two persons.

11.1. Installation Configurations

The flush-mountable **CLAWS** Spikes can be installed in four different configurations. The configuration is dependent on two factors:

- Orientation of installation
- Direction of spike impact

11.1.1. Orientation of Installation

The orientation of installation is described as the side at which the drive linkage is installed when approaching the **CLAWS** Spikes. In other words, when driving up to the **CLAWS** Spikes, in the correct direction for traffic flow, and the drive is installed on the right-hand side of the vehicle, it's deemed a right-hand installation. And when driving up to the **CLAWS** Spikes, in the correct direction for traffic flow, and the drive is installed on the left-hand side of the vehicle, it's deemed a left-hand installation.



FIGURE 2. RHS CONFIGURATION

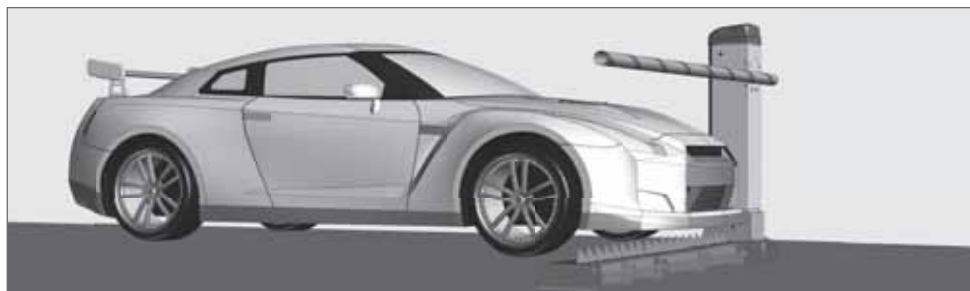


FIGURE 3. LHS CONFIGURATION

11.1.2. Spike Impact Direction

The **CLAWS** Spikes are designed to take a much larger or more frequent impact in one direction. The spikes can be installed to face either towards oncoming traffic (similar) or face towards traffic (opposing) trying to enter from the wrong direction or lane.



FIGURE 4. SPIKE IMPACT DIRECTION - SIMILAR



FIGURE 5. SPIKE IMPACT DIRECTION - OPPOSING

There are four types of typical installations. Refer to Section 11, Figures 2 and 3 to determine if the installation is left- or right-hand orientated. Secondly; pay attention to the spike impact direction:

- **Similar direction of travel** prevents vehicles from exiting whilst the boom pole is still down (Normal direction of traffic)
- **Opposing direction of travel** prevents vehicles entering against the flow of traffic whilst the boom pole is down

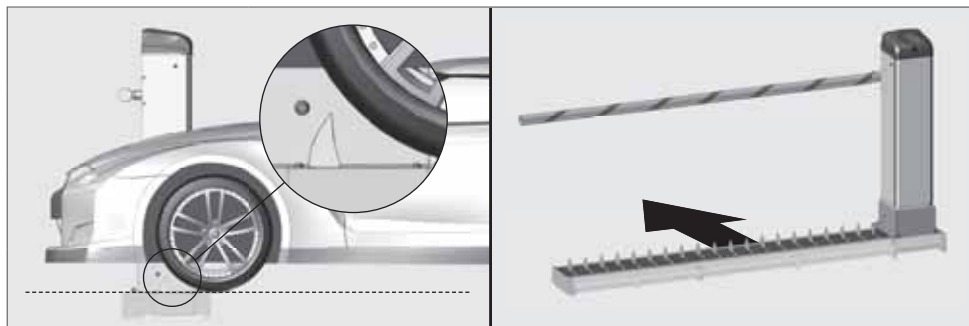


FIGURE 6. RHS SIMILAR DIRECTION OF TRAVEL

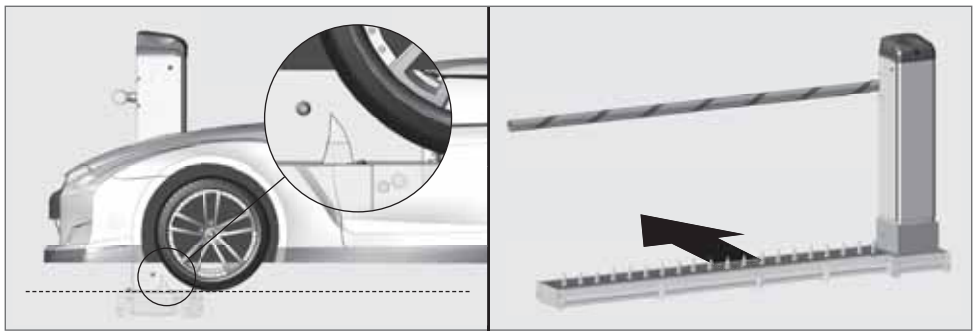


FIGURE 7. RHS OPPOSED DIRECTION OF TRAVEL

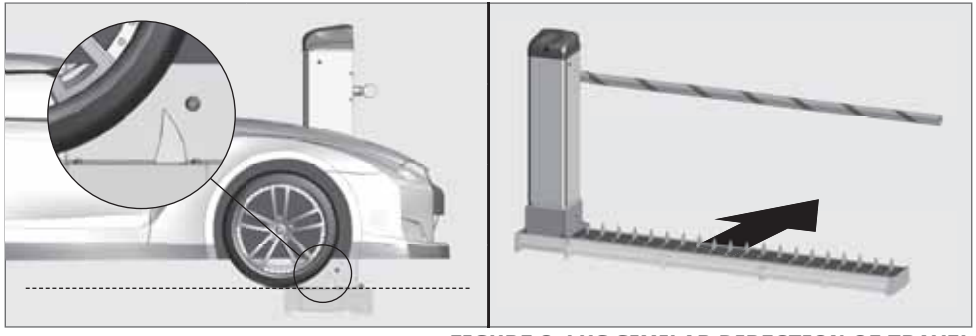


FIGURE 8. LHS SIMILAR DIRECTION OF TRAVEL

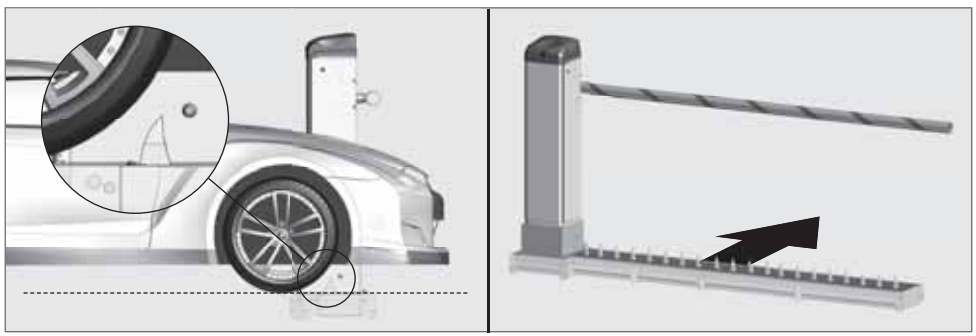
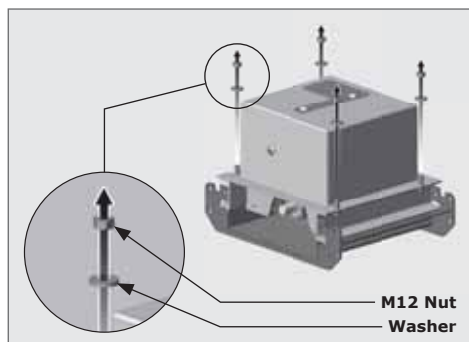


FIGURE 9. LHS OPPOSED DIRECTION OF TRAVEL

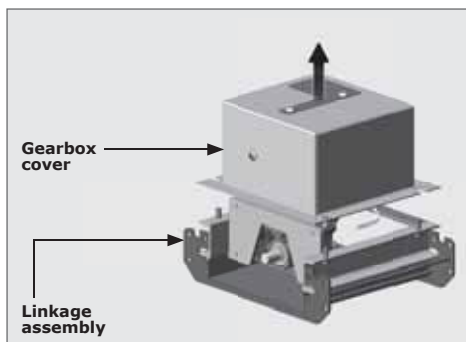
12. RHS Independent Drive Flush Mount - Similar Direction of Travel

12.1. Preparing the Drive Linkage Assembly



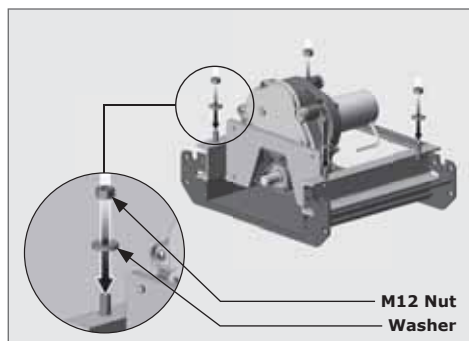
STEP 1

FIGURE 10



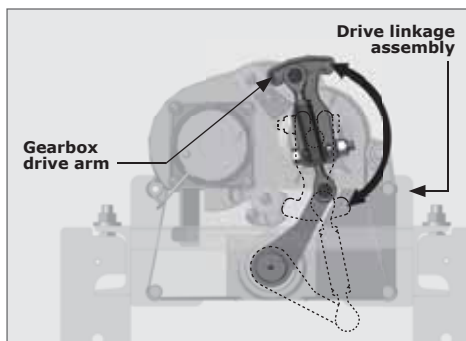
STEP 2

FIGURE 11



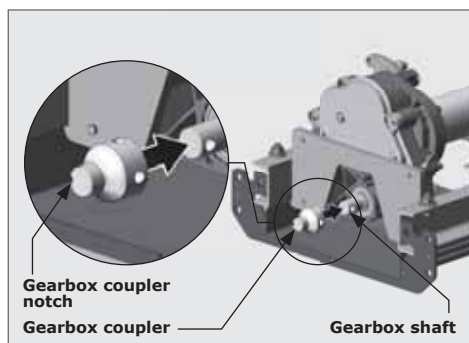
STEP 3

FIGURE 12



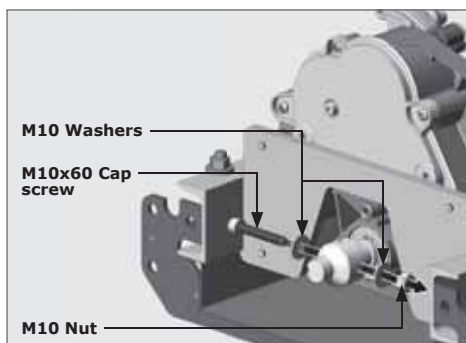
STEP 4

FIGURE 13



STEP 5

FIGURE 14



STEP 6

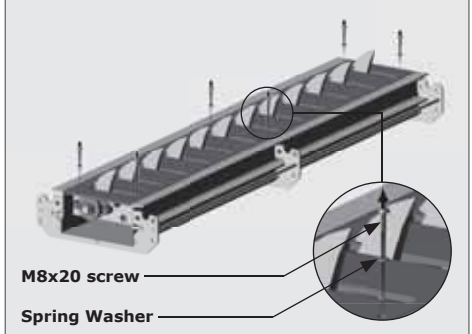
FIGURE 15



Note the orientation of the gearbox coupler notch is at the 9 o'clock position and that the gearbox drive arm is up as shown in Section 12, Figure 14.

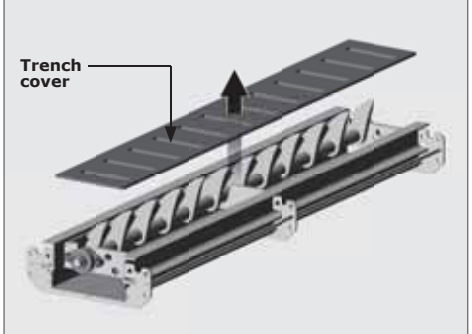
12.2. Spike Module Assembly

12.2.1. Preparing the Spike Module assembly(ies) for installation



STEP 1

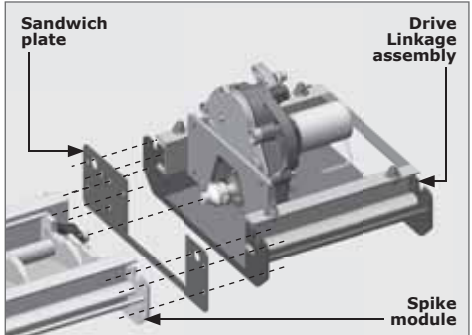
FIGURE 16



STEP 2

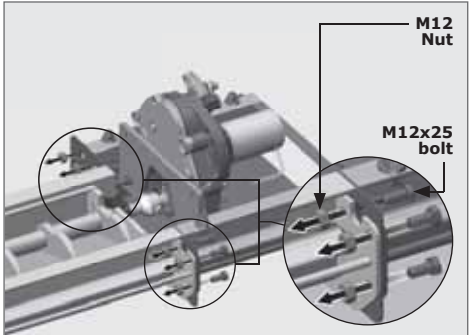
FIGURE 17

12.2.2. Attaching the drive linkage assembly to the spike module



STEP 1

FIGURE 18



STEP 2

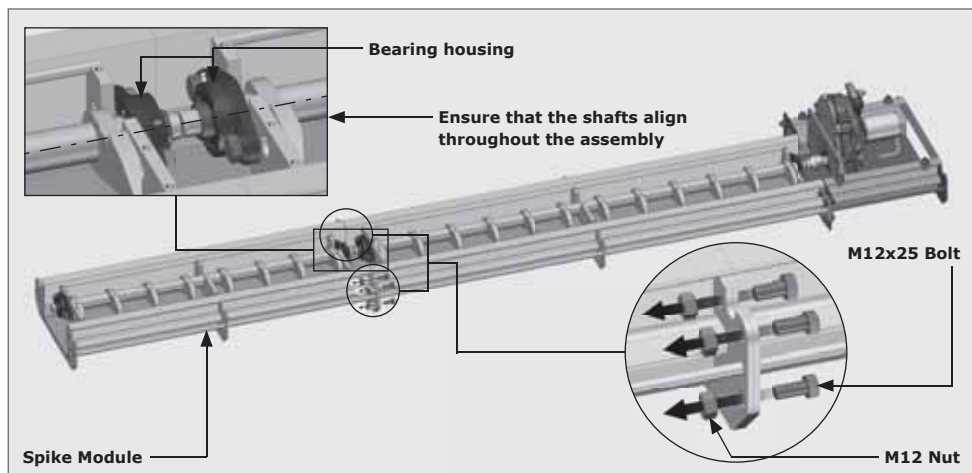
FIGURE 19



Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly.

STEP 3

Using six M12x25 bolts, fix one spike module to another (Section 12, Figure 20).

**FIGURE 20**

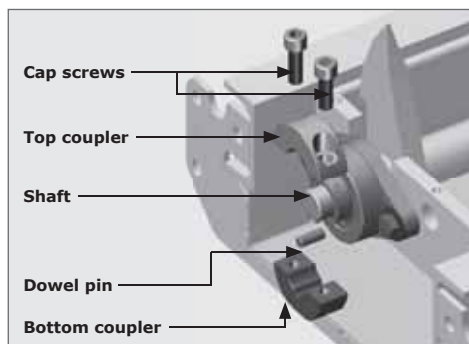
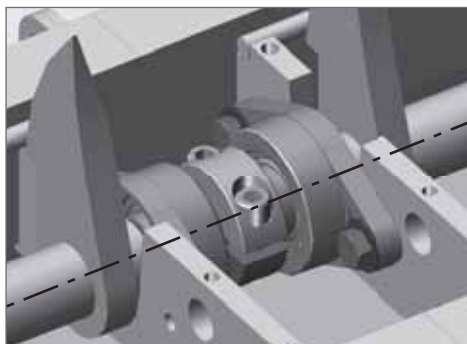
To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

12.2.3. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

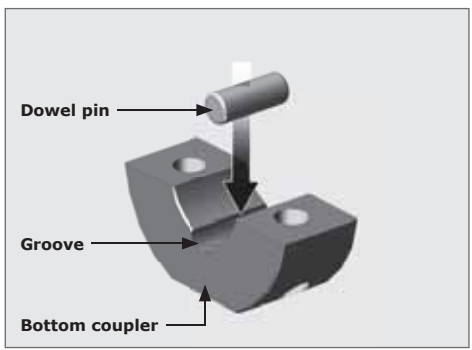


It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.

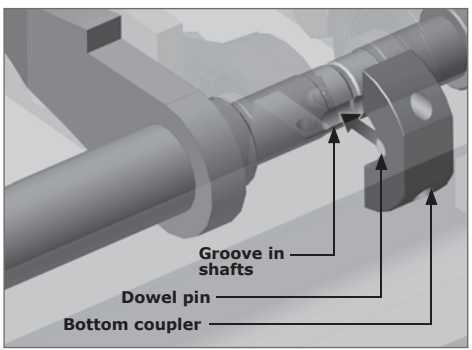
**FIGURE 21. SHAFT COUPLER****FIGURE 22**



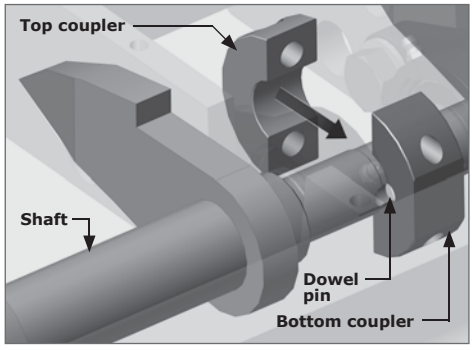
Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.



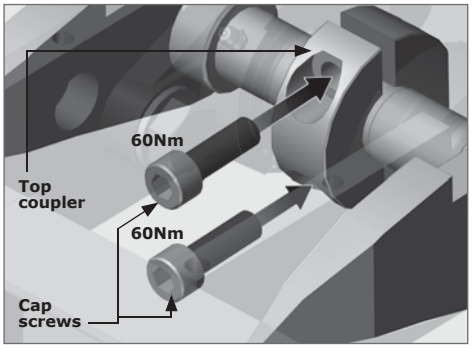
STEP 1 FIGURE 23



STEP 2 FIGURE 24

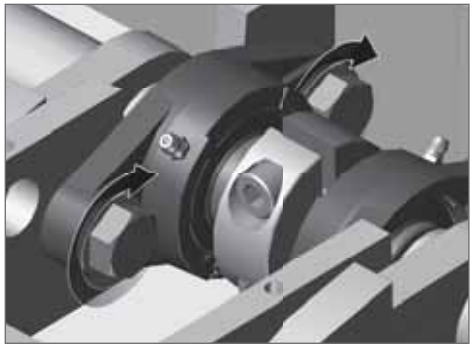


STEP 3 FIGURE 25

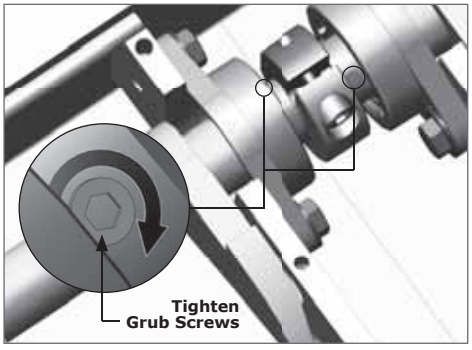


STEP 4 FIGURE 26

STEP 5
Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.



STEP 6 FIGURE 27



STEP 7 FIGURE 28

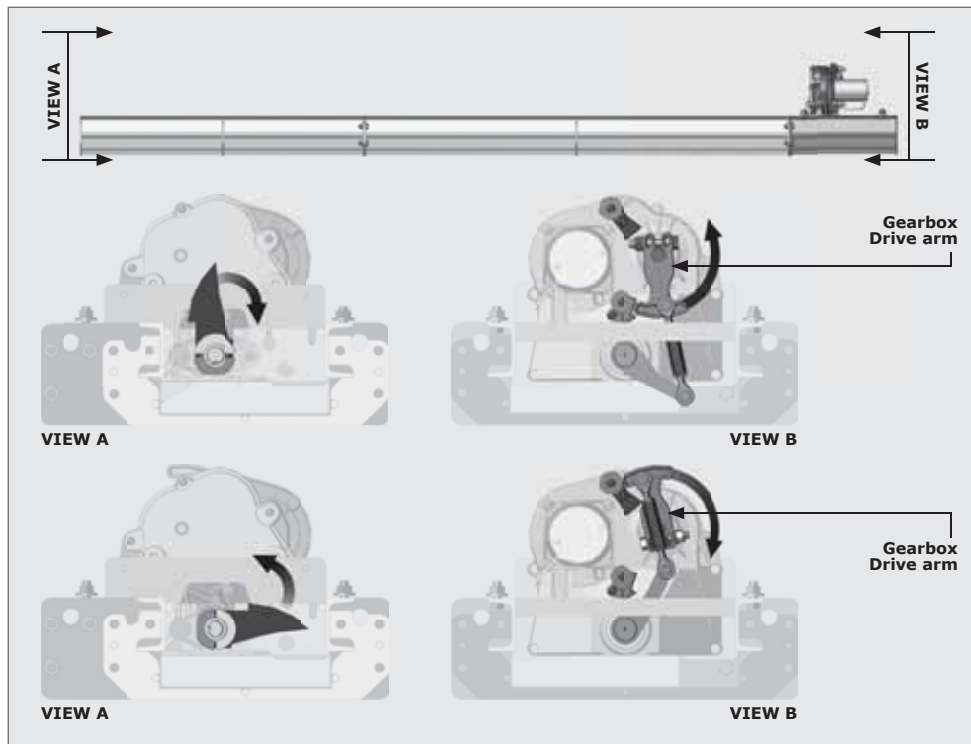
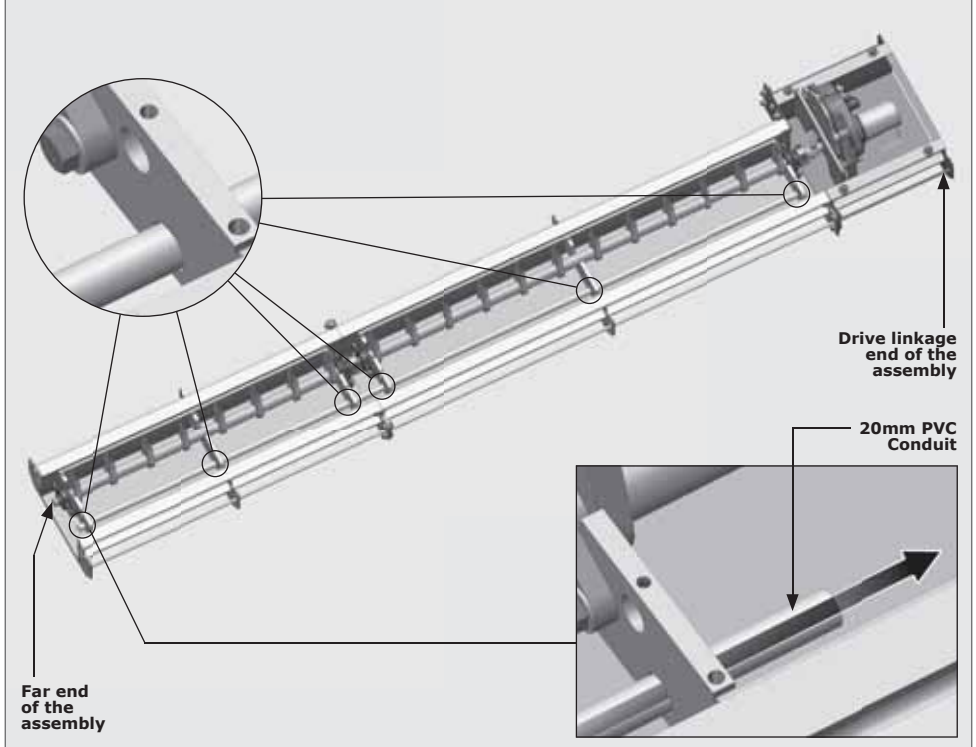


FIGURE 29. CORRECTLY ALIGNED SPIKE AND DRIVE MODULES

12.2.4. Proximity sensor installation



STEP 1

FIGURE 30



The length of the PVC conduit will be relative to the length of the spike modules combined. Ensure that a further 38mm is added to this to account for the modules and coupling (Refer to Section 12, Figure 31).

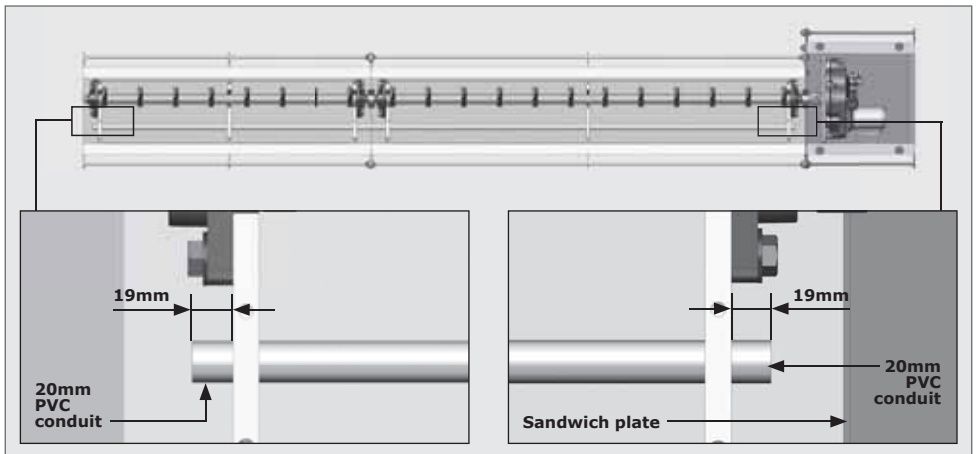
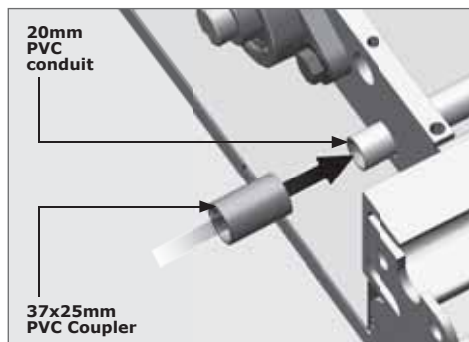


FIGURE 31

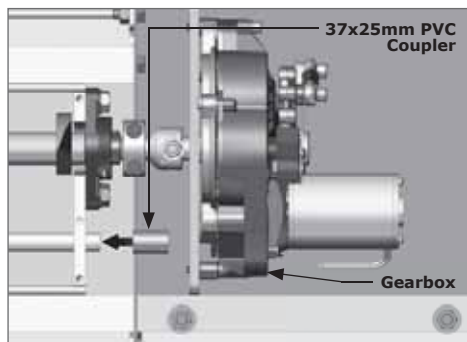


Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.



STEP 2

FIGURE 32

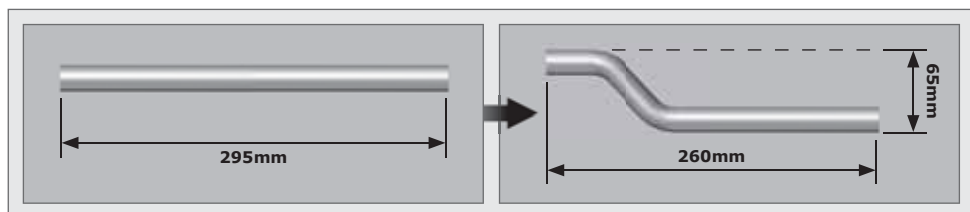


STEP 3

FIGURE 33



It is necessary to bend PVC conduit to circumvent the gearbox bulkhead to continue. The use of a conduit spring is recommended to avoid collapsing the pipe. Section 12, Figure 34 below is a guideline that can be used to achieve this.



STEP 4

FIGURE 34

STEP 5

Connect the bent piece of conduit to the PVC coupler installed in Section 12, Figure 33 Step 3. After it is connected, it should resemble Section 12, Figure 35.

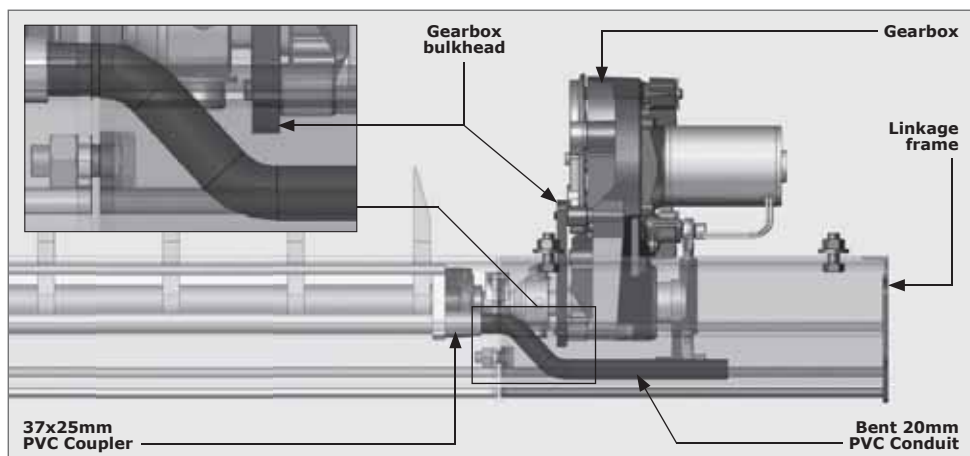
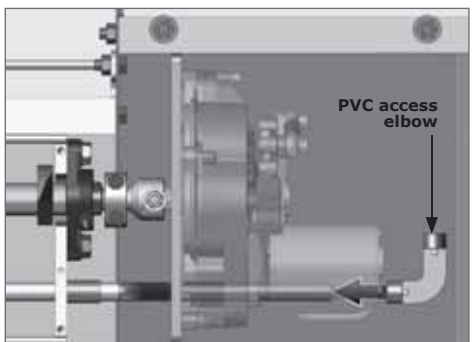


FIGURE 35

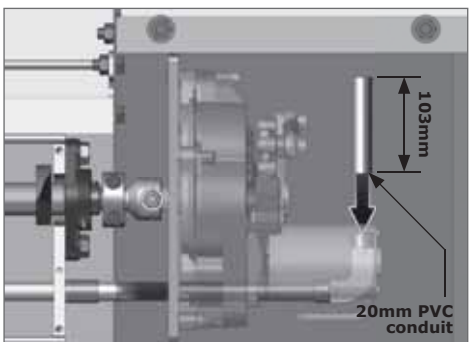


Steps 6-9 is only applicable if the SECTOR II will be mounted directly onto the **CLAWS** Gearbox. If they are going to be mounted separately, a trench for the conduit and cables will need to be dug (Refer to Section 12.5.2.).



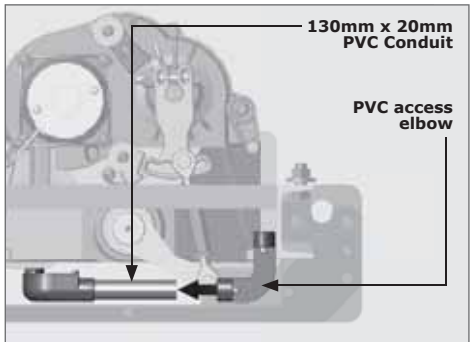
STEP 6

FIGURE 36



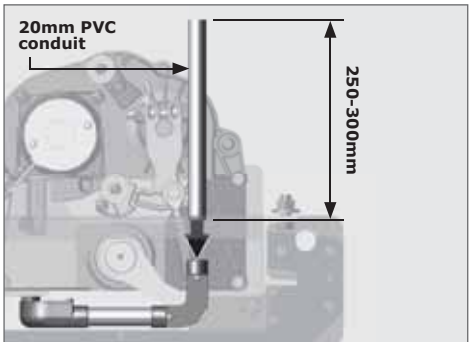
STEP 7

FIGURE 37



STEP 8

FIGURE 38



STEP 9

FIGURE 39



Please ensure that the moving mechanical parts do not rub against the conduit or cables.

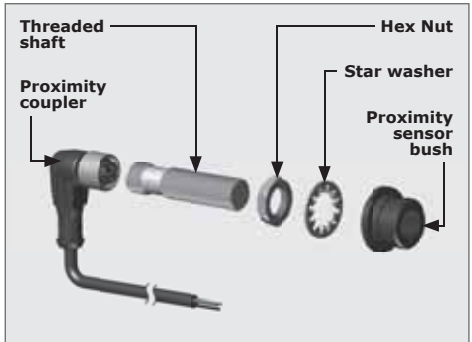


FIGURE 40. PROXIMITY SENSOR

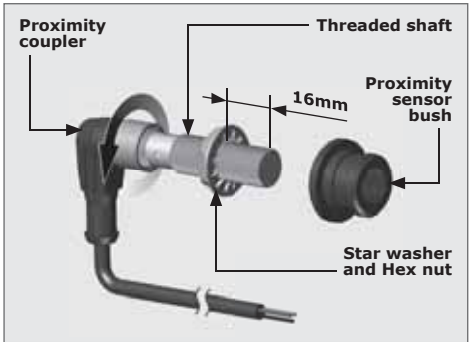


FIGURE 41. PROXIMITY SENSOR

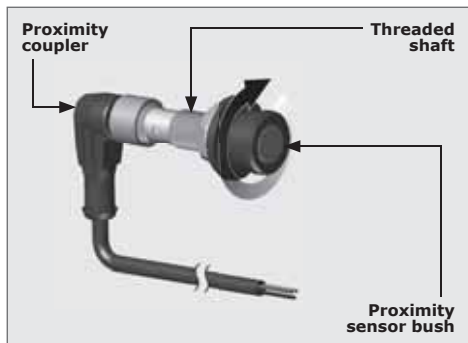
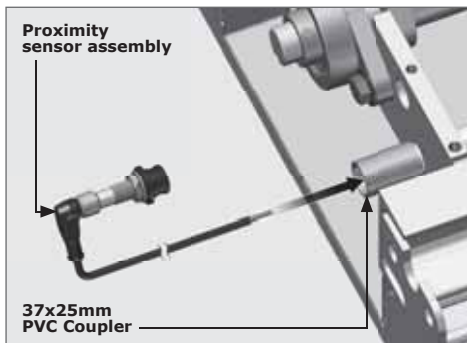


FIGURE 42. PROXIMITY SENSOR



STEP 6

FIGURE 43

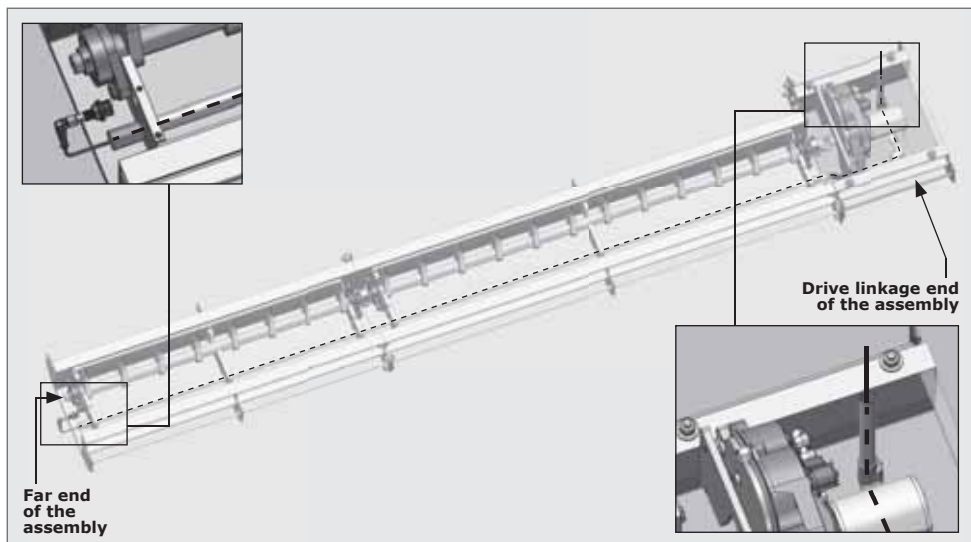
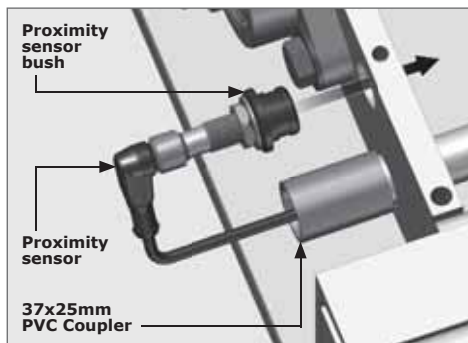


FIGURE 44

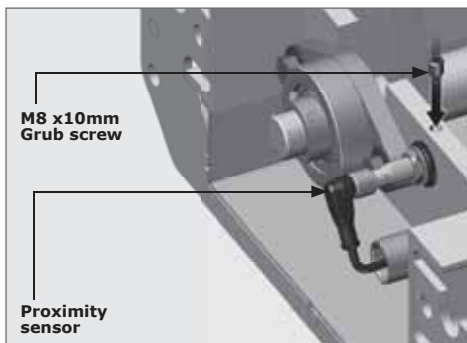


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed up the SECTOR II at a later stage.



STEP 7

FIGURE 45

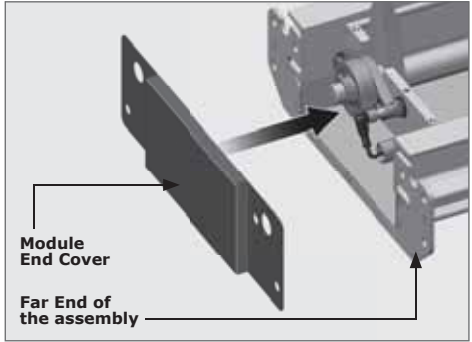


STEP 8

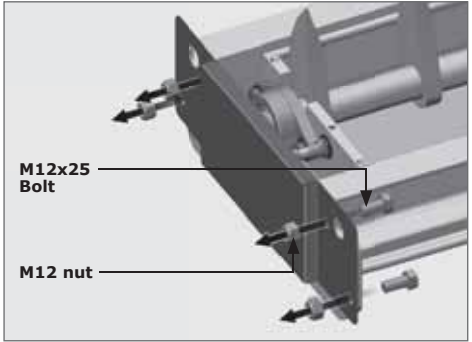
FIGURE 46

12.2.5. Attaching the End Covers to the Assembly

12.2.5.1. Attaching the Module End cover

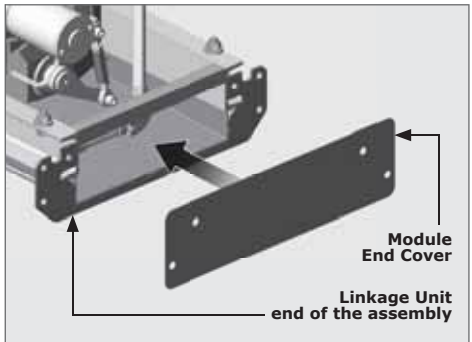


STEP 1 FIGURE 47

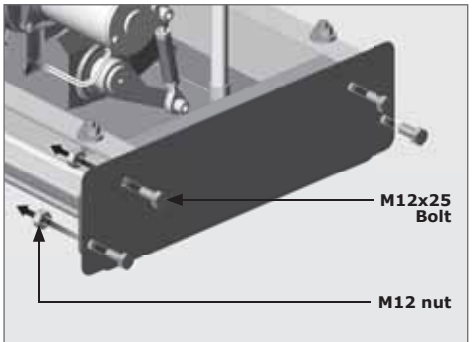


STEP 2 FIGURE 48

12.2.5.2. Attaching the Linkage Unit End cover



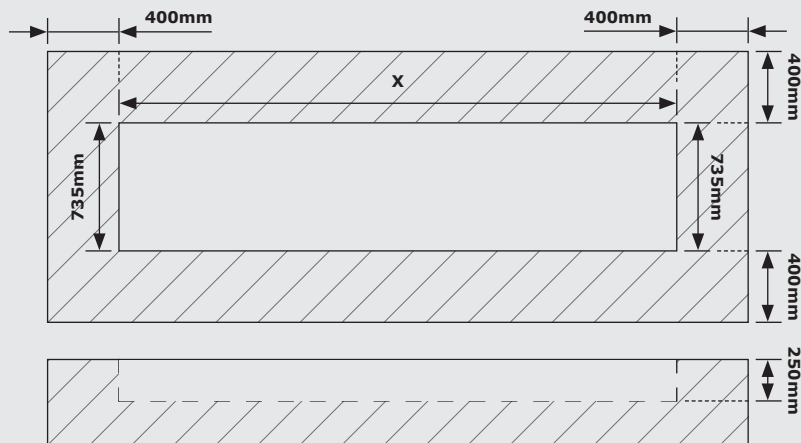
STEP 1 FIGURE 49



STEP 2 FIGURE 50

12.3. Preparing the trench and drainage system

Dig a hole following the dimensions below. Dimension 'X' is relative to the total length of the linkage unit and spike models combined.



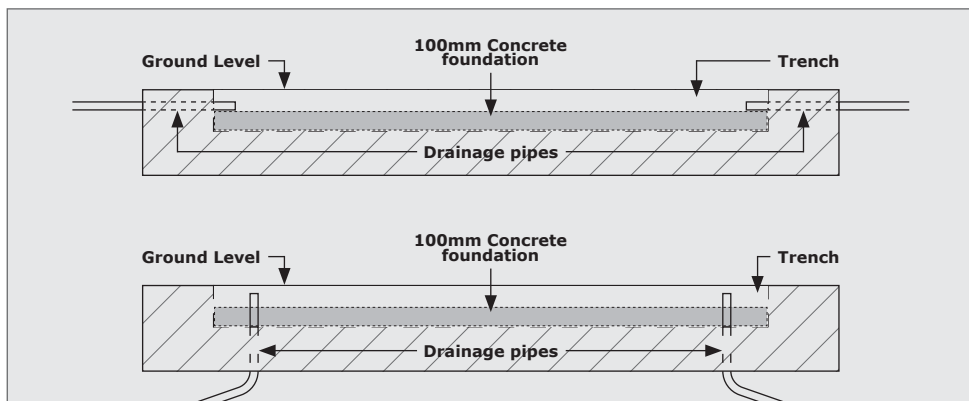
STEP 1

FIGURE 51

Drainage pipes must be laid at one or both ends of the trench to allow water to flow either into storm water drains or into any other area away from the installation. Section 12, Figure 52 shows two recommended drainage configurations. Once complete, hold them in place by pouring a 100mm concrete foundation and level off.



If the **SECTOR II** and **CLAWS** are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and **SECTOR II**. This must be done before any concrete is poured (Section 12.5.2.).



STEP 2

FIGURE 52



Make sure the drain pipes do not interfere with the structure when it will be placed in the trench.

12.3.1. Concreting the assembly into the trench.

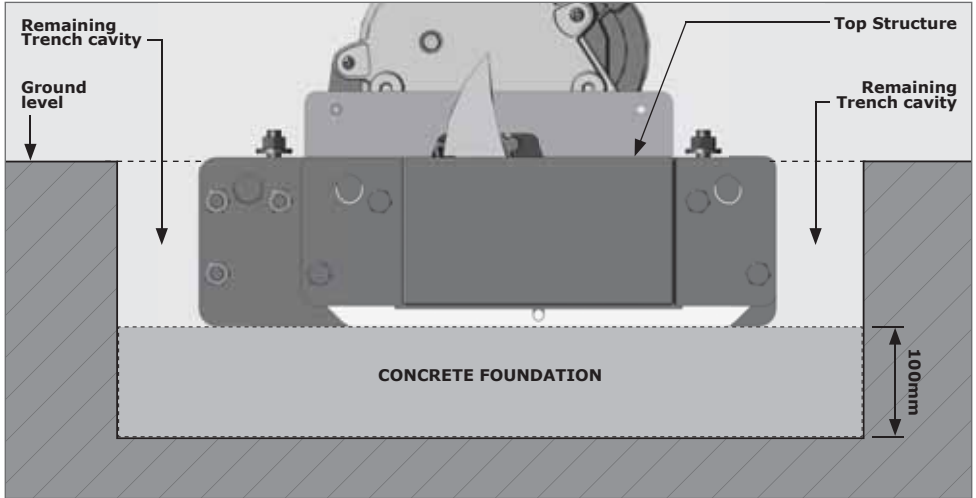


Ensure that the drain pipes will not interfere with the structure when it is placed in the trench.

Place the assembly in the trench and level the assembly using any type of propping or jacking method. Make sure that the top of the assembly is either in line with or a little higher than the ground level and pour concrete (minimum 45MPa after 28 days) into the cavity that remains.



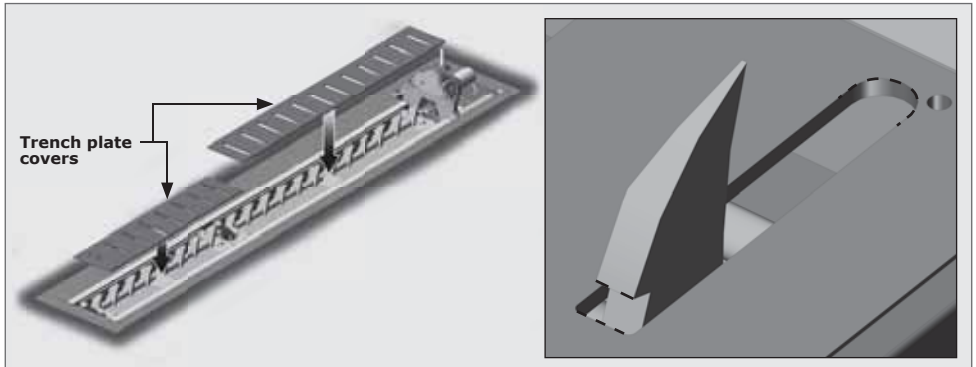
Do not pour any concrete into the gutter of the spikes module or drive link assembly.



STEP 3

FIGURE 53

12.4. Re-assembling the trench plates

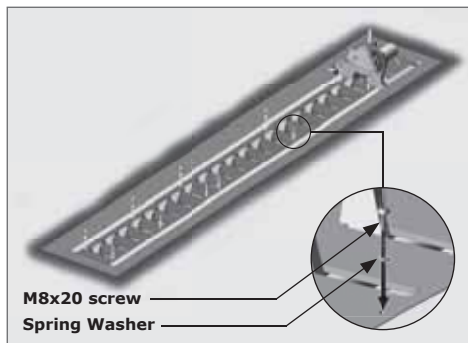


STEP 1

FIGURE 54



Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.



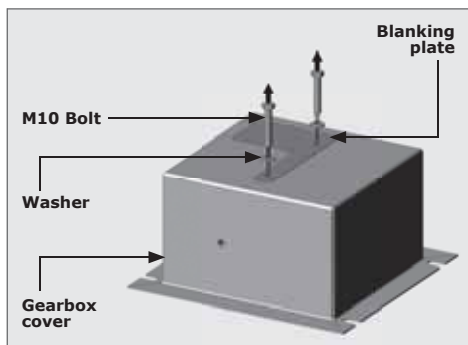
STEP 2

FIGURE 55

12.5. Integrating the SECTOR II with the CLAWS

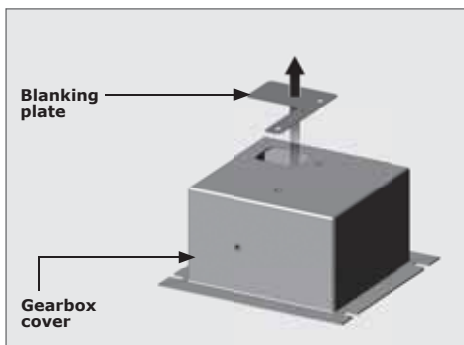
12.5.1. Directly mount THE SECTOR II onto the Independent Drive

12.5.1.1. Placing the gearbox cover into position



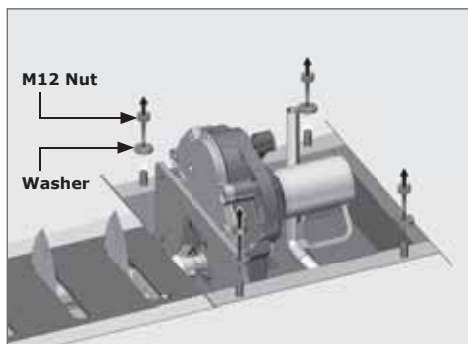
STEP 1

FIGURE 56



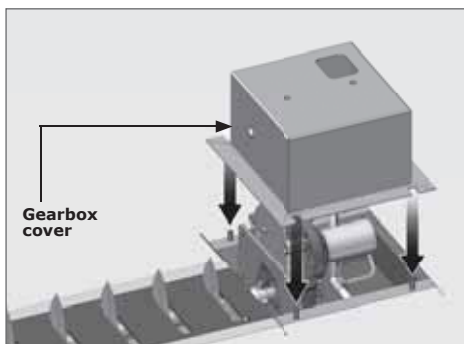
STEP 2

FIGURE 57



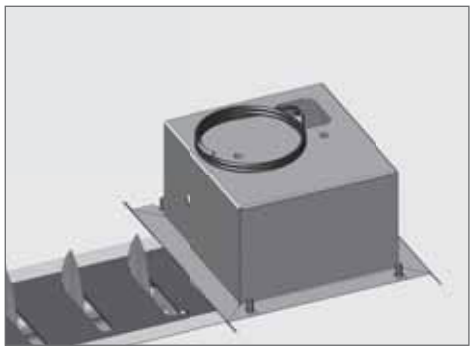
STEP 3

FIGURE 58



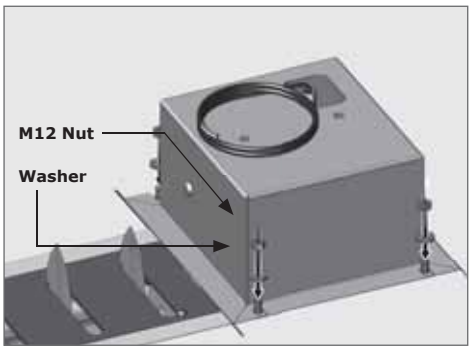
STEP 4

FIGURE 59



STEP 5

FIGURE 60



STEP 6

FIGURE 61

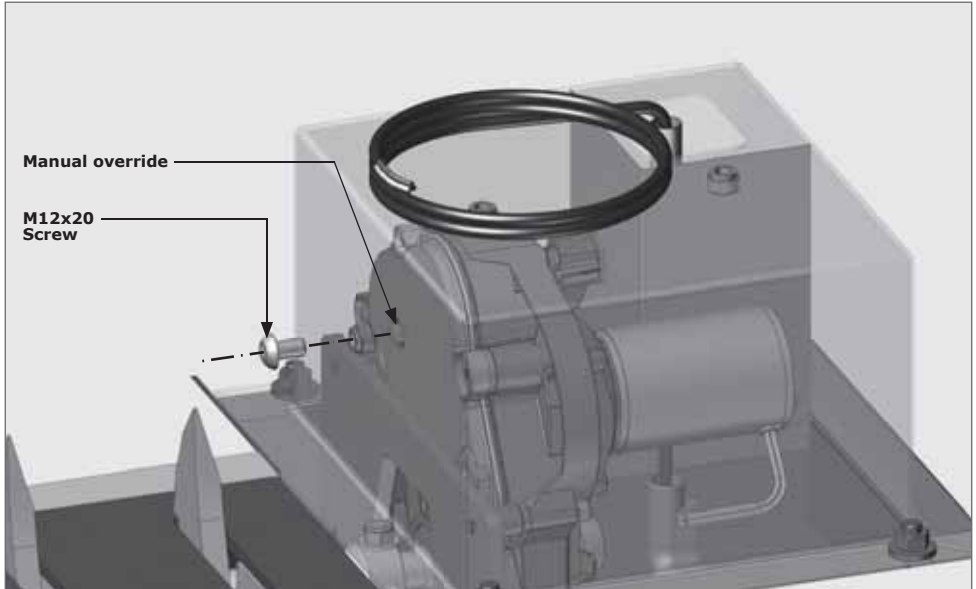
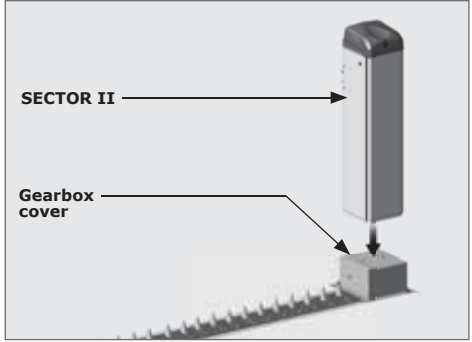


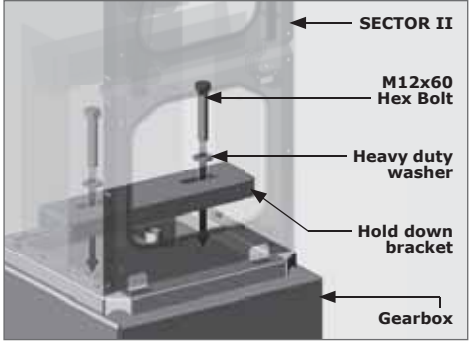
FIGURE 62. MANUAL OVERRIDE

12.5.1.2. Placing the SECTOR II into position



STEP 1

FIGURE 63



STEP 2

FIGURE 64

12.5.2. Separately-placed CLAWS and SECTOR II

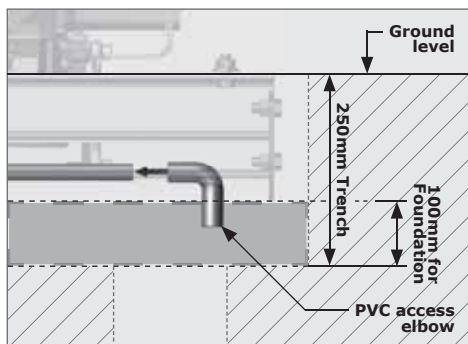
12.5.2.1. Running the conduit from the gearbox to the SECTOR II

STEP 1

Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.

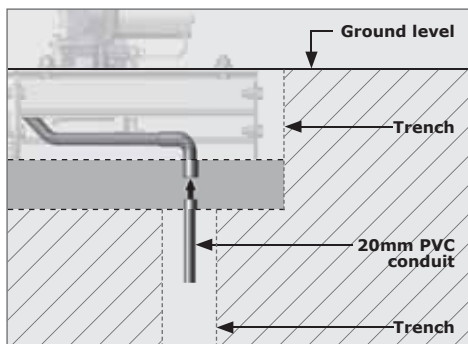


Drill a 20mm hole through the gutter plate using a 20mm hole saw for the proximity sensor conduit



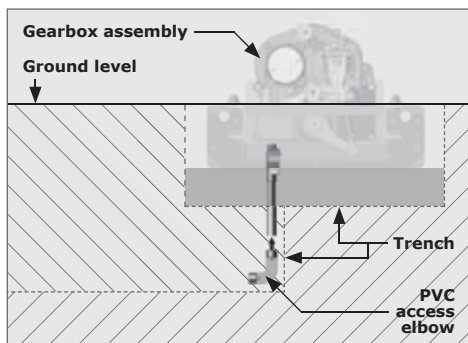
STEP 2

FIGURE 65



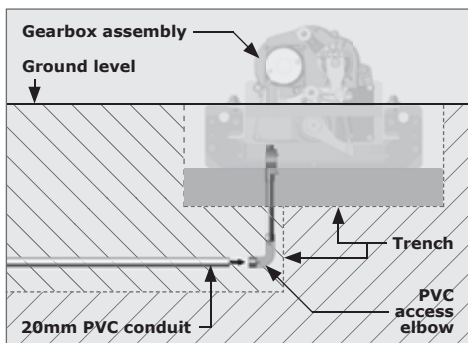
STEP 3

FIGURE 66



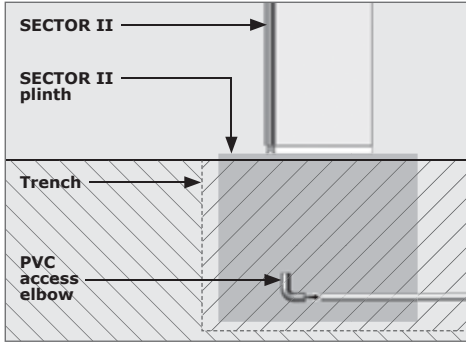
STEP 4

FIGURE 67



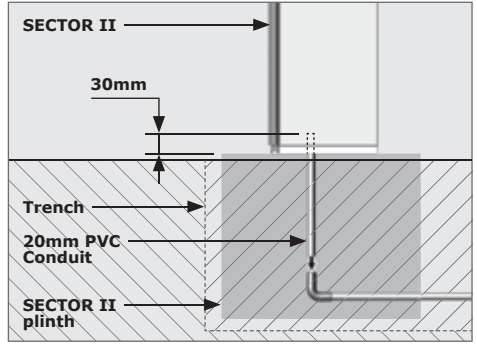
STEP 5

FIGURE 68



STEP 6

FIGURE 69



STEP 7

FIGURE 70

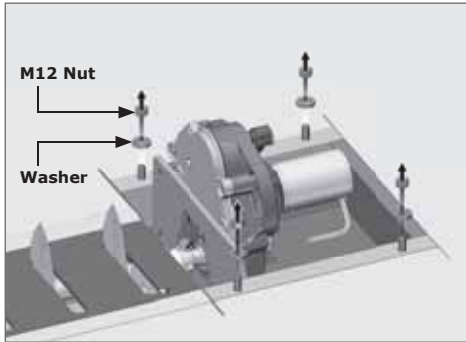
STEP 8

Route the **CLAWS** and Proximity sensor cables in the conduit to the SECTOR II.

STEP 9

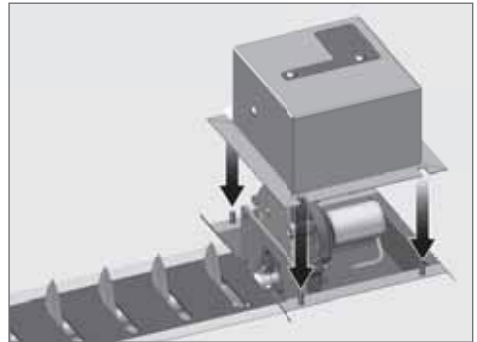
Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

12.5.2.2. Placing the gearbox cover into position



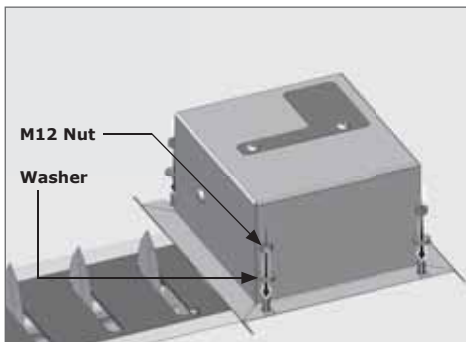
STEP 1

FIGURE 71



STEP 2

FIGURE 72



STEP 3

FIGURE 73

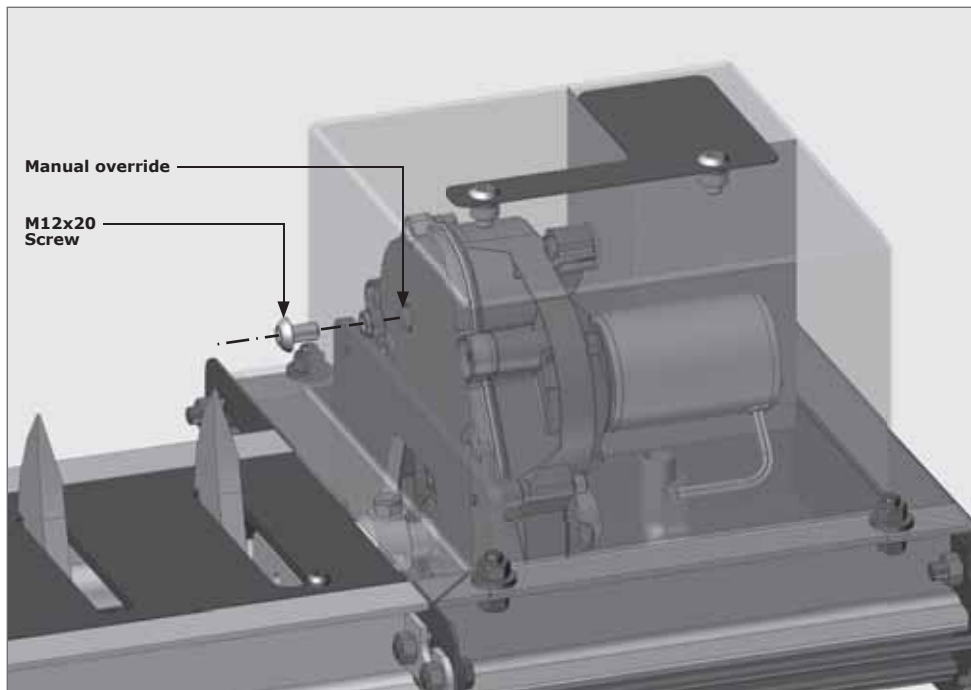
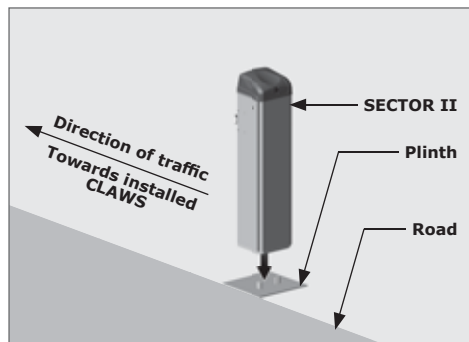


FIGURE 74. MANUAL OVERRIDE



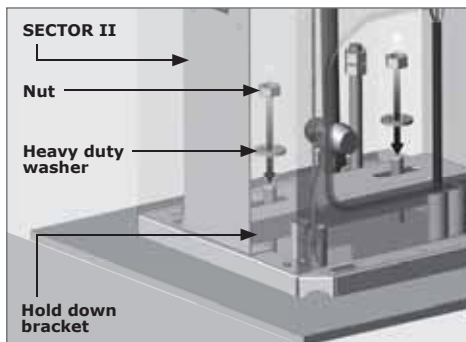
By removing the M12x20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.

12.5.2.3. Placing the SECTOR II into position



STEP 1

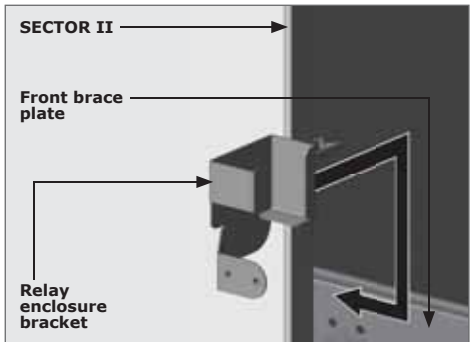
FIGURE 75



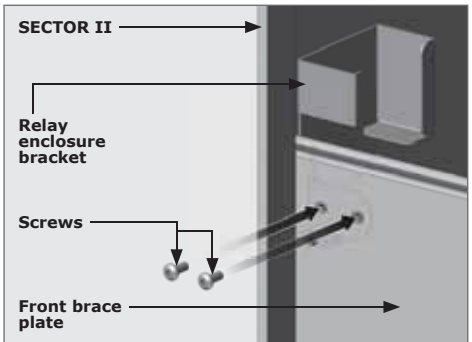
STEP 2

FIGURE 76

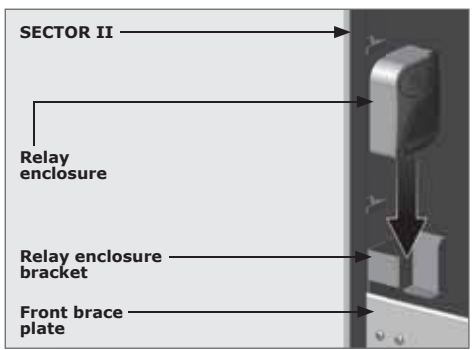
12.5.3. Fitting the relay enclosure and its bracket



STEP 1 FIGURE 77



STEP 2 FIGURE 78



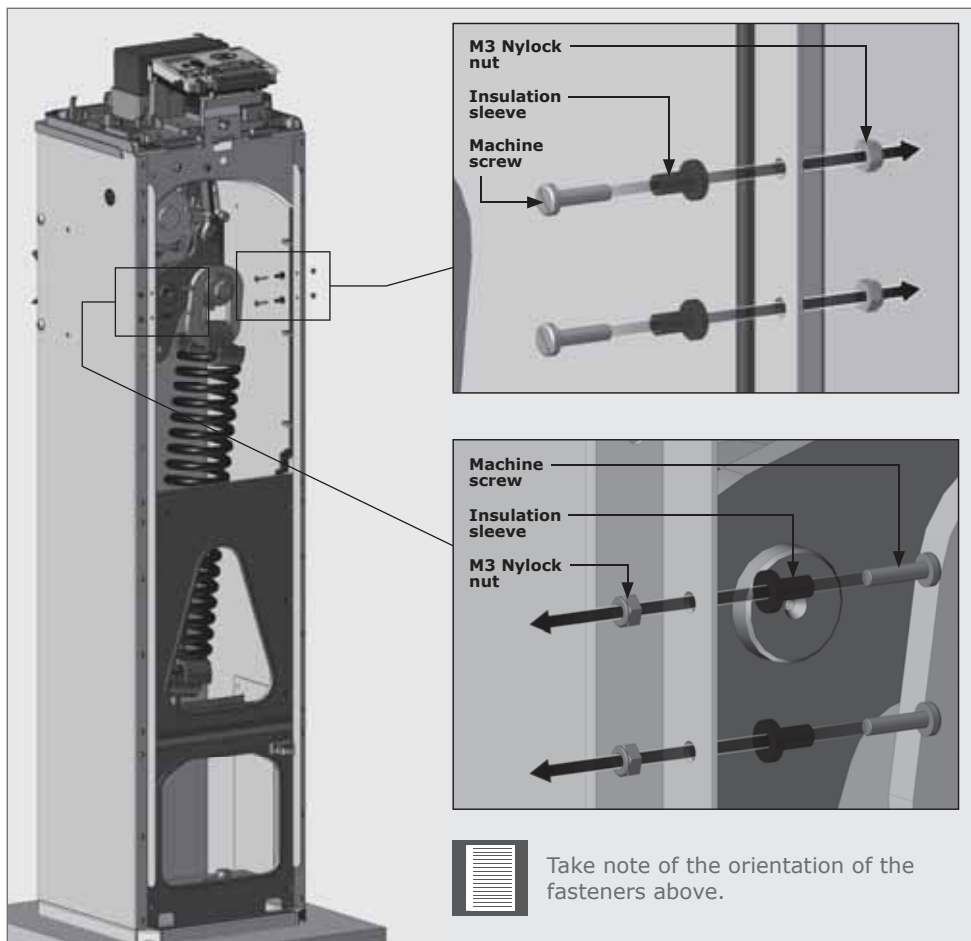
STEP 3 FIGURE 79



Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 16).

Complete the installation of the SECTOR II as per its full installation manual.

12.5.5. Fitting the CLAWS controller to the SECTOR II



STEP 1

FIGURE 80

STEP 2

Keeping the **CLAWS** Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.

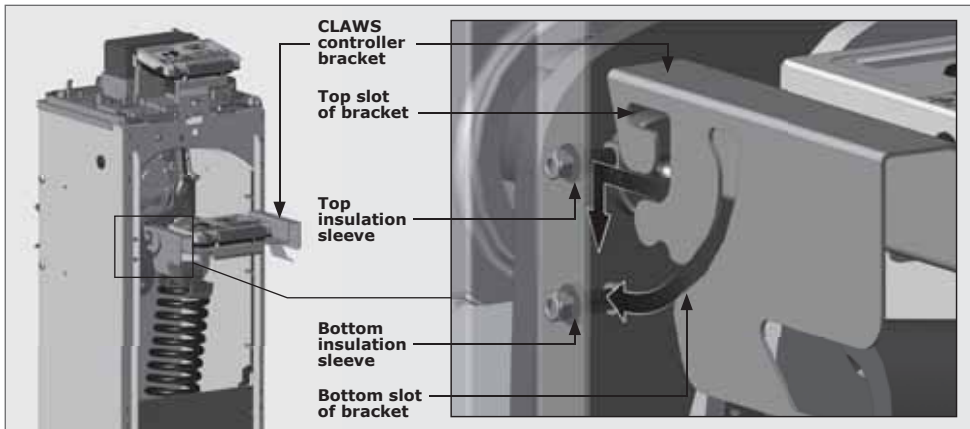


FIGURE 81

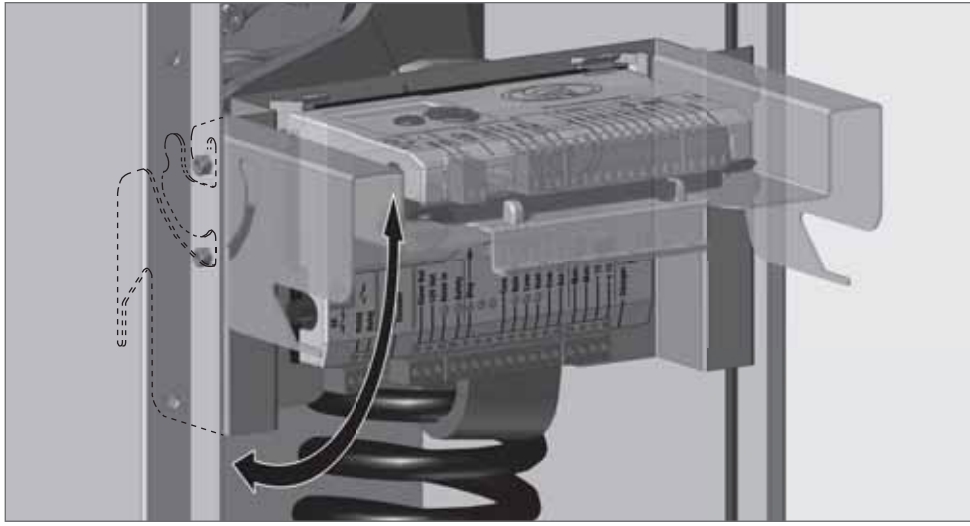


FIGURE 82



The bracket can be moved into a set angle of 70° by pivoting it upward from the bottom for better viewing of the LCD screen (Section 12, Figure 83).

It can also be moved lower down for optimum space when working on the gearbox (Section 12, Figure 84).



Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 12, Figure 81).

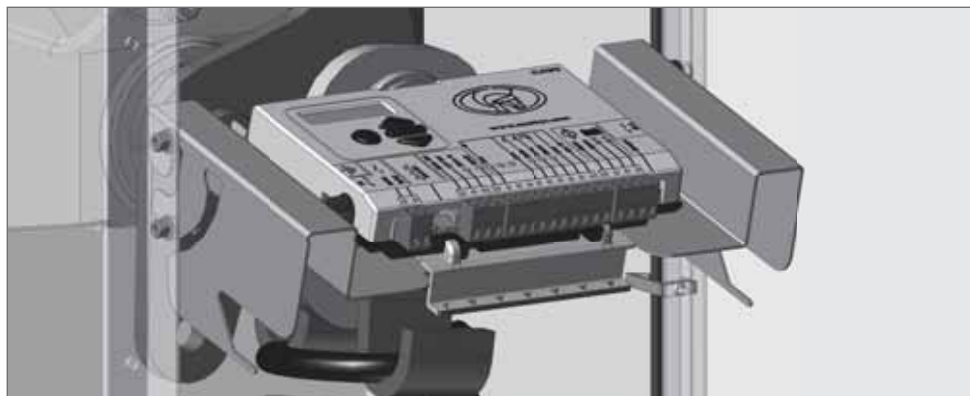


FIGURE 83. CLAWS CONTROLLER AND BRACKET AT FIXED 70° POSITION

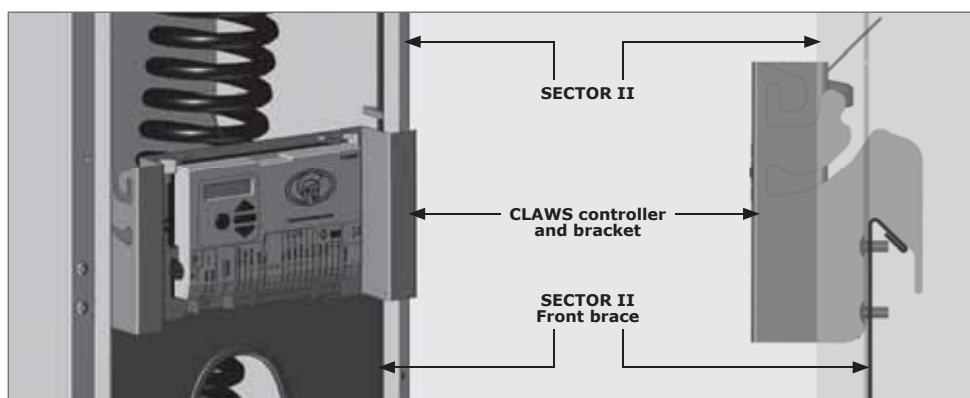


FIGURE 84. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION

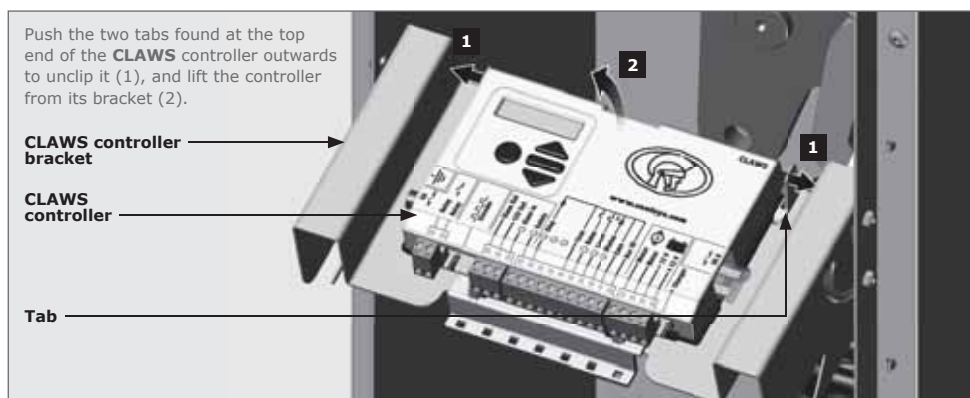


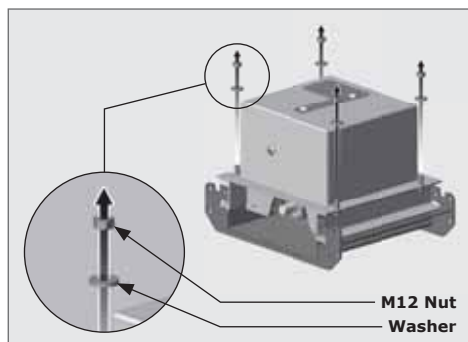
FIGURE 85. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET

STEP 3

Connect harness and power supply. Refer to the wiring diagrams and controller settings.

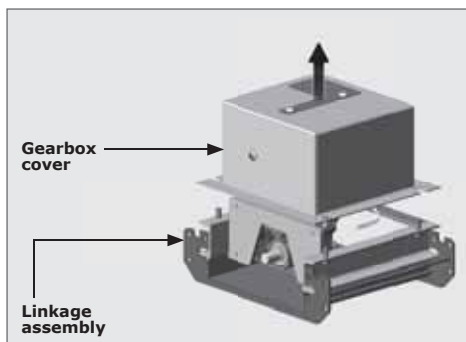
13. LHS Independent Drive Flush Mount - Opposing Direction of Travel

13.1. Preparing the Drive Linkage Assembly



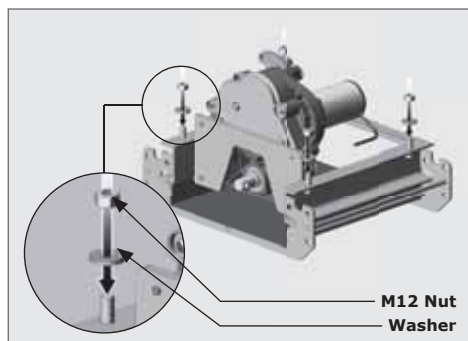
STEP 1

FIGURE 1



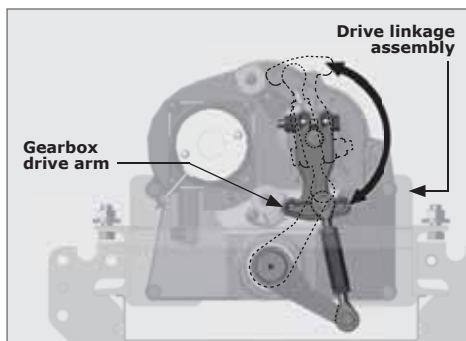
STEP 2

FIGURE 2



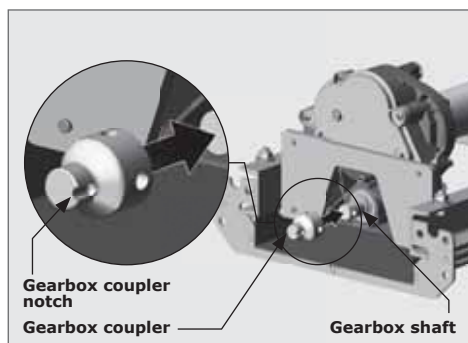
STEP 3

FIGURE 3



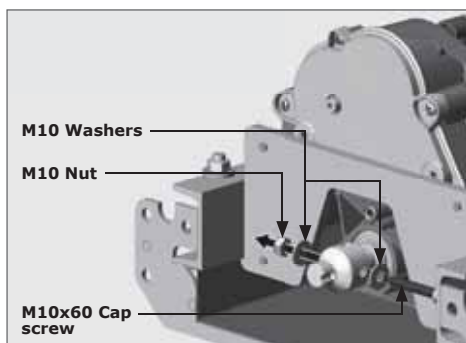
STEP 4

FIGURE 4



STEP 5

FIGURE 5



STEP 6

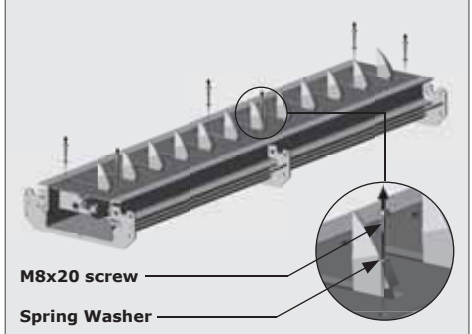
FIGURE 6



Note the orientation of the gearbox coupler notch is at the 3 o'clock position and that the gearbox drive arm is down as shown in Section 13, Figure 5.

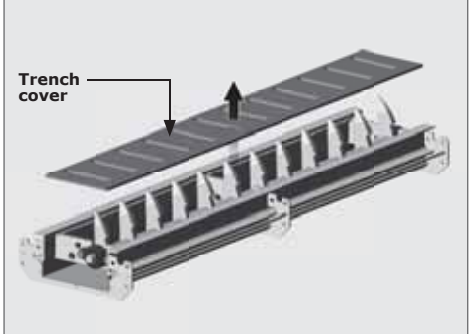
13.2. Spike Module Assembly

13.2.1. Preparing the Spike Module assembly(ies) for installation



STEP 1

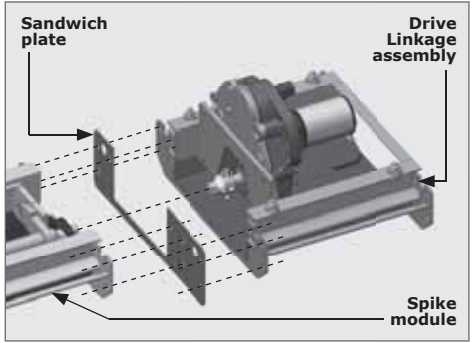
FIGURE 7



STEP 2

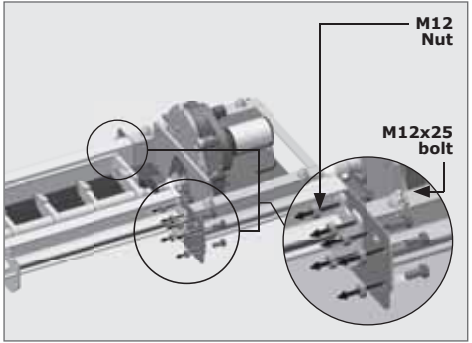
FIGURE 8

13.2.2. Attaching the drive linkage assembly to the spike module



STEP 1

FIGURE 9



STEP 2

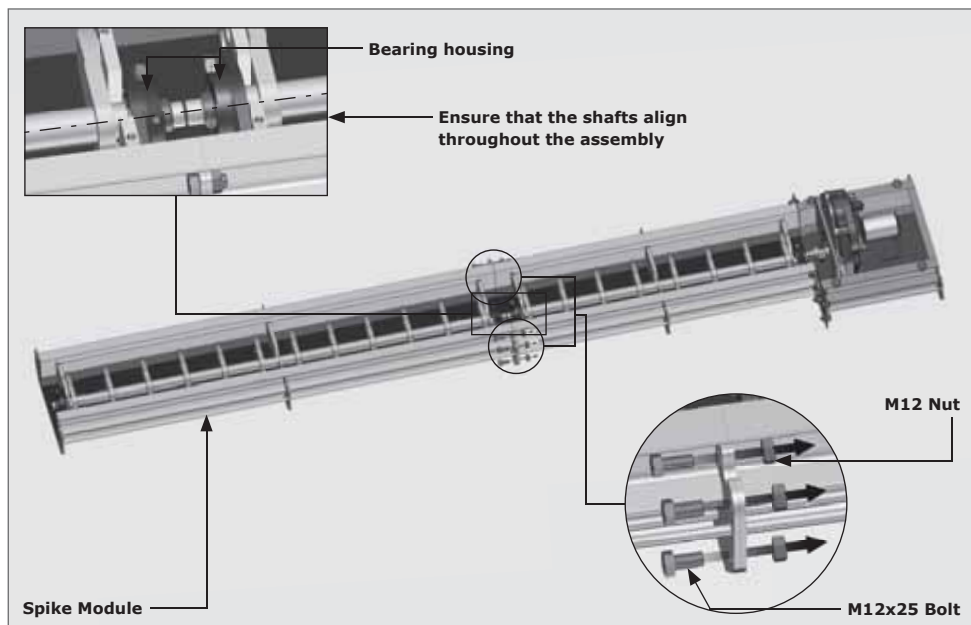
FIGURE 10



Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly.

STEP 3

Using six M12x25 bolts, fix one spike module to another (Section 13, Figure 11).

**FIGURE 11**

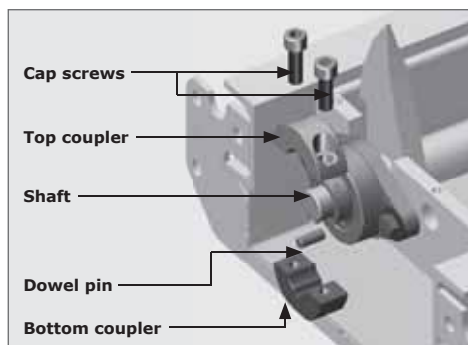
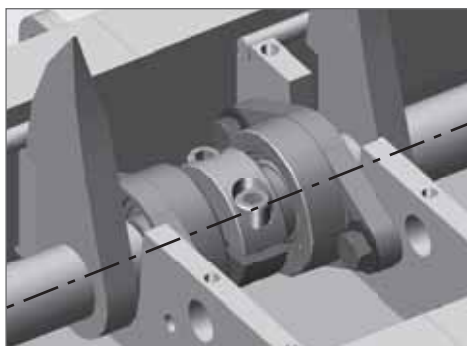
To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

13.2.3. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

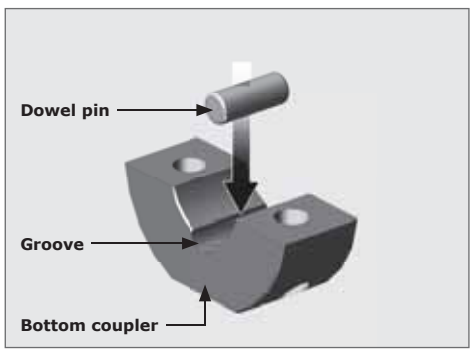


It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.

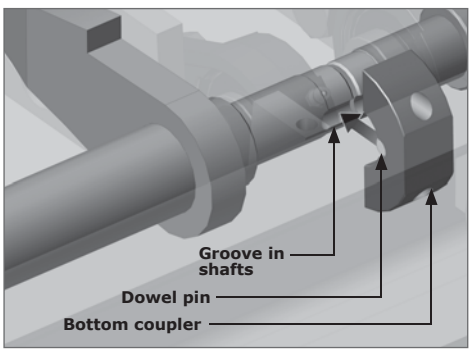
**FIGURE 12. SHAFT COUPLER****FIGURE 13**



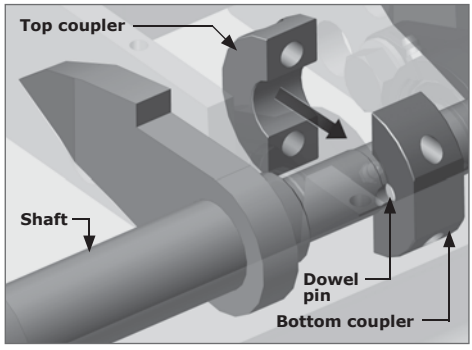
Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.



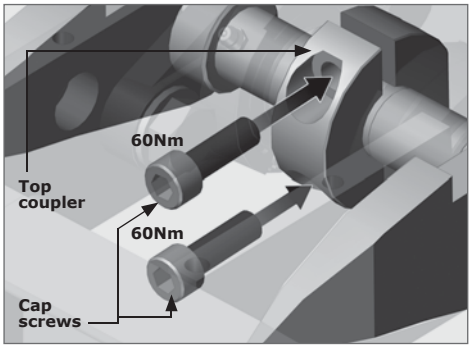
STEP 1 FIGURE 14



STEP 2 FIGURE 15

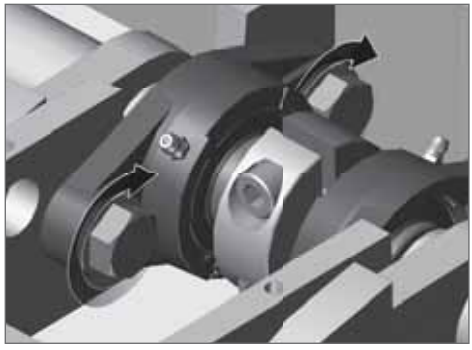


STEP 3 FIGURE 16

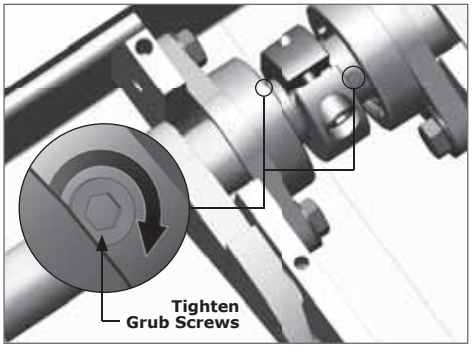


STEP 4 FIGURE 17

STEP 5
Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.



STEP 6 FIGURE 18



STEP 7 FIGURE 19

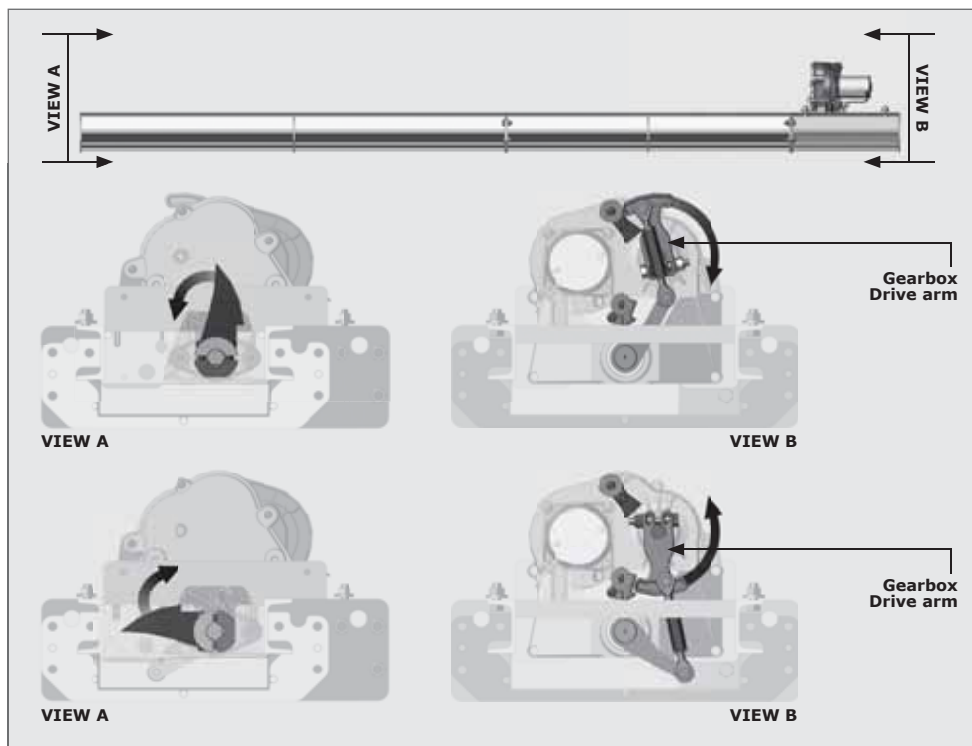
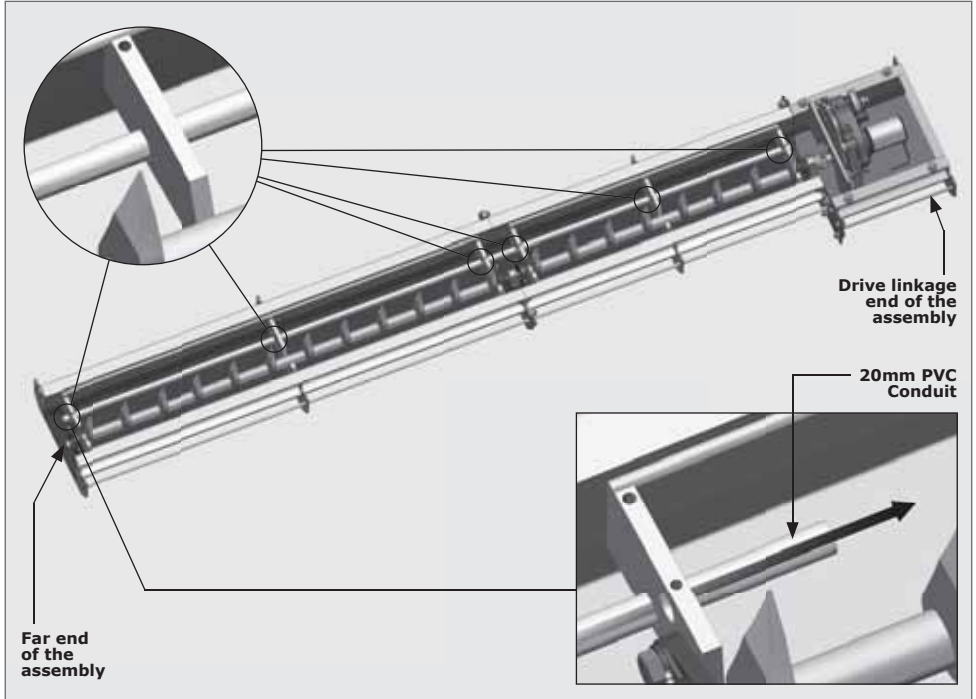


FIGURE 20. CORRECTLY ALIGNED SPIKE AND DRIVE MODULES

13.2.4. Proximity sensor installation



STEP 1

FIGURE 21



The length of the PVC conduit will be relative to the length of the spike modules combined. Ensure that a further 38mm is added to this to account for the modules and coupling (Refer to Section 13, Figure 22).

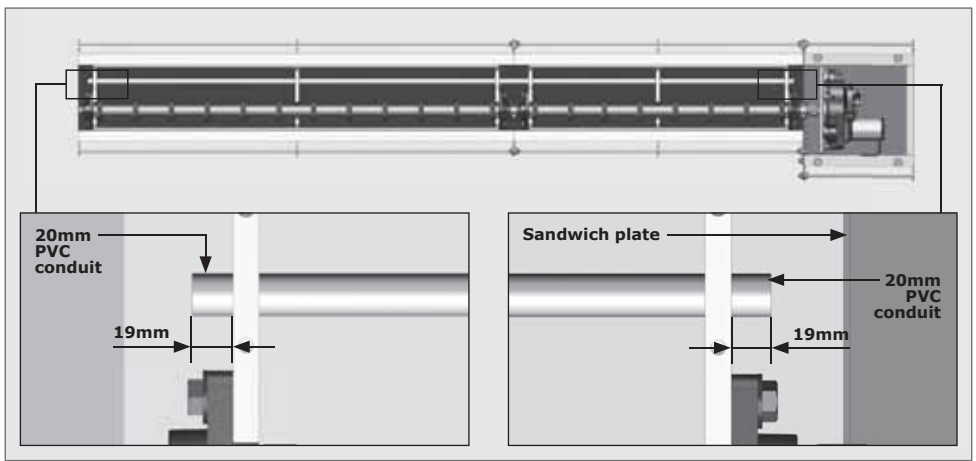
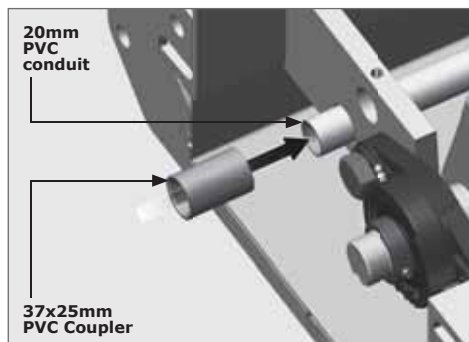


FIGURE 22

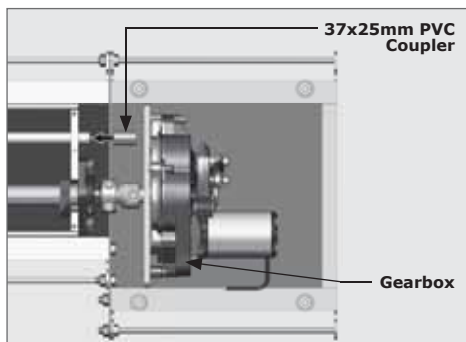


Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.



STEP 2

FIGURE 23

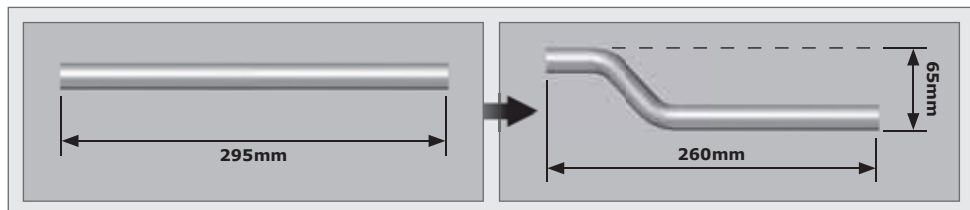


STEP 3

FIGURE 24



It is necessary to bend PVC conduit to circumvent the gearbox bulkhead to continue. The use of a conduit spring is recommended to avoid collapsing the pipe. Section 13, Figure 25 below is a guideline that can be used to achieve this.



STEP 4

FIGURE 25

STEP 5

Connect the bent piece of conduit to the PVC coupler installed in Section 13, Figure 24 Step 3. After it is connected, it should resemble Section 13, Figure 26.

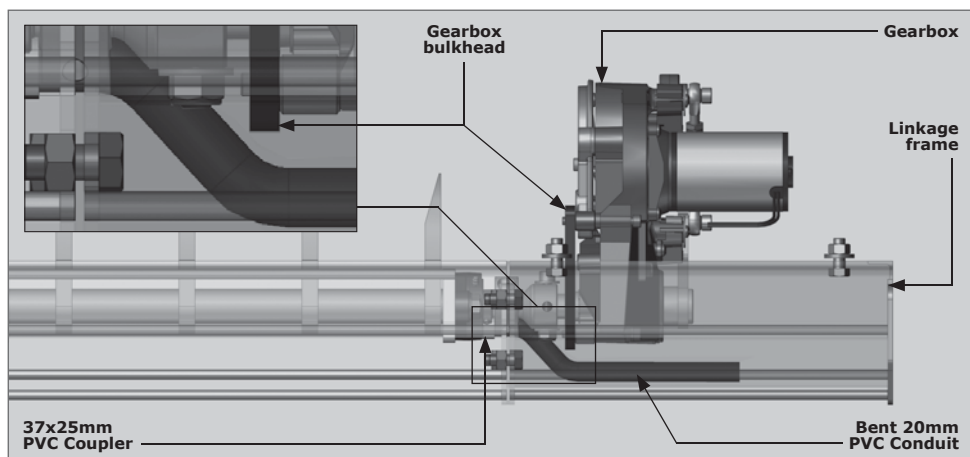
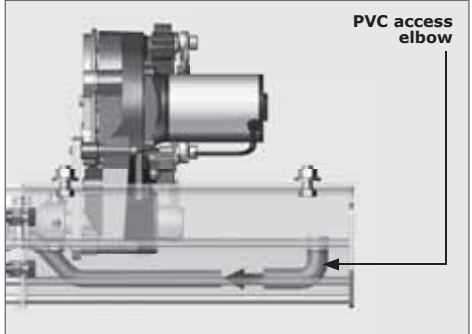


FIGURE 26

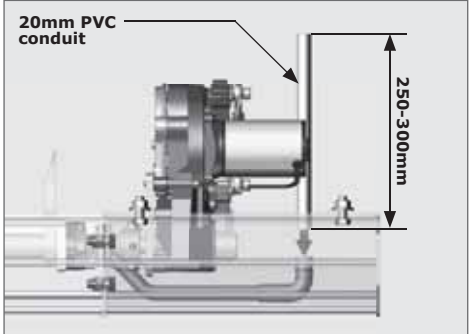


Steps 6-9 is only applicable if the SECTOR II will be mounted directly onto the **CLAWS** Gearbox. If they are going to be mounted separately, a trench for the conduit and cables will need to be dug (Refer to Section 13.5.2.).



STEP 6

FIGURE 27



STEP 7

FIGURE 28



Please ensure that the moving mechanical parts do not rub against the conduit or cables.

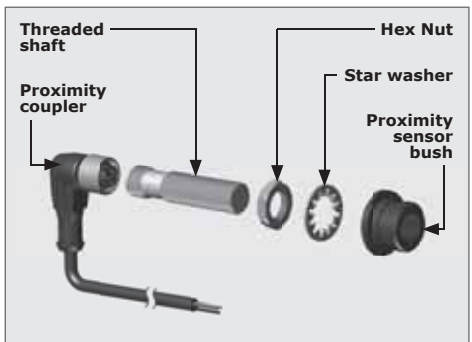


FIGURE 29. PROXIMITY SENSOR

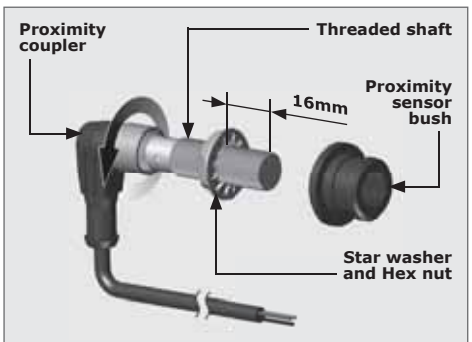


FIGURE 30. PROXIMITY SENSOR

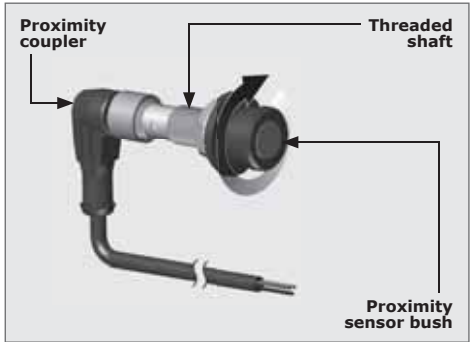
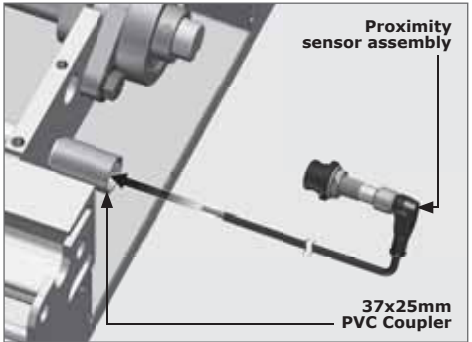


FIGURE 31. PROXIMITY SENSOR



STEP 6

FIGURE 32

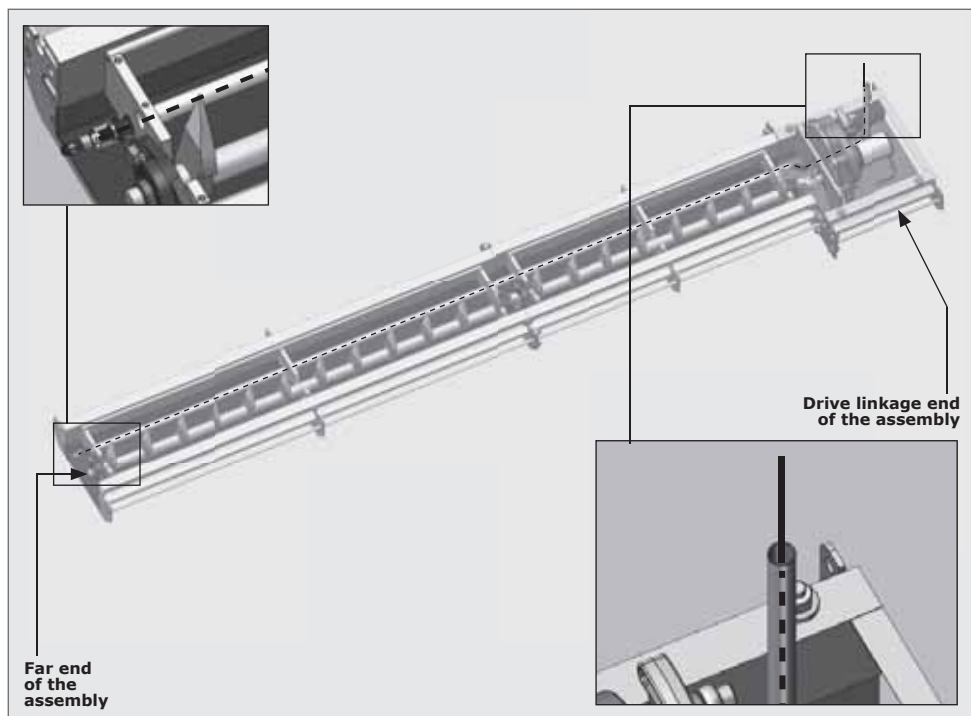
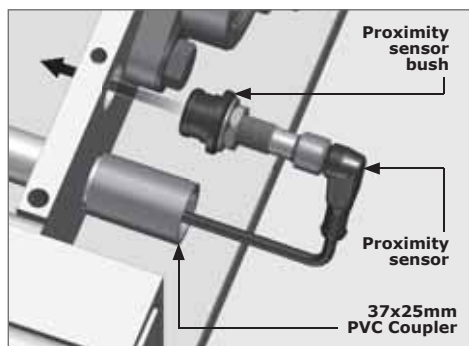


FIGURE 33

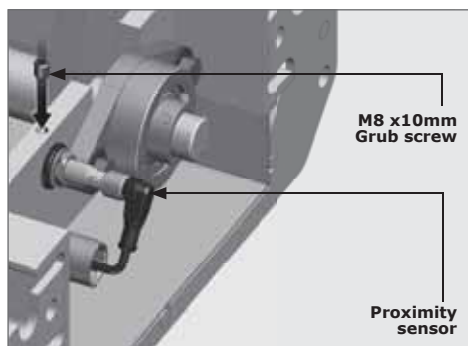


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed up the SECTOR II at a later stage.



STEP 7

FIGURE 34

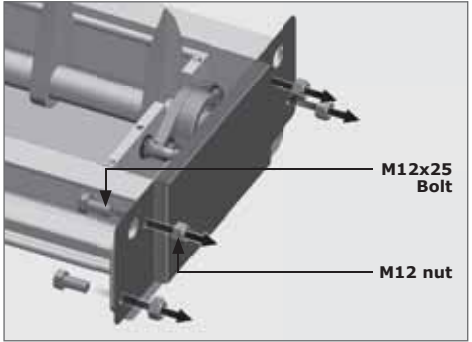
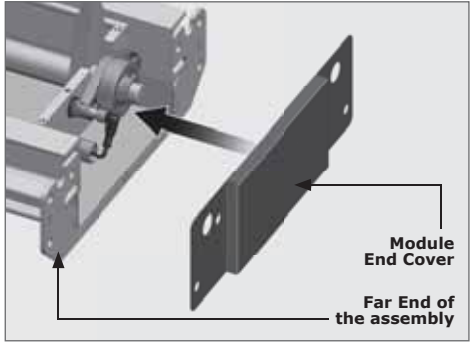


STEP 8

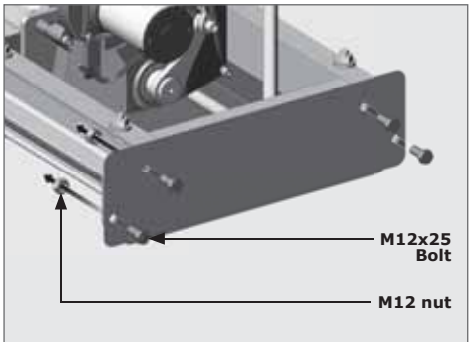
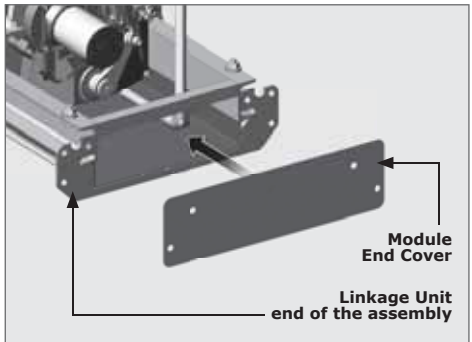
FIGURE 35

13.2.5. Attaching the End Covers to the Assembly

13.2.5.1. Attaching the Module End cover

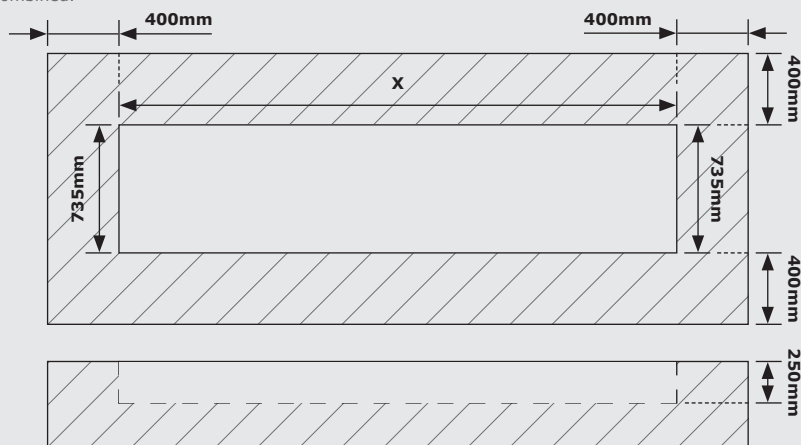


13.2.5.2. Attaching the Linkage Unit End cover



13.3. Preparing the trench and drainage system

Dig a hole following the dimensions below. Dimension 'X' is relative to the total length of the linkage unit and spike models combined.



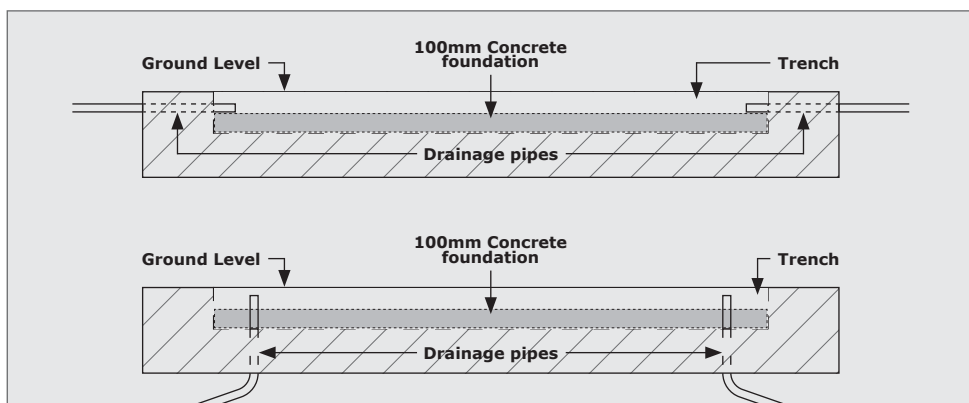
STEP 1

FIGURE 40

Drainage pipes must be laid at one or both ends of the trench to allow water to flow either into storm water drains or into any other area away from the installation. Section 13, Figure 41 shows two recommended drainage configurations. Once complete, hold them in place by pouring a 100mm concrete foundation and level off.



If the SECTOR II and **CLAWS** are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. This must be done before any concrete is poured (Section 13.5.2.).



STEP 2

FIGURE 41

Make sure the drain pipes do not interfere with the structure when it will be placed in the trench.



13.3.1. Concreting the assembly into the trench.

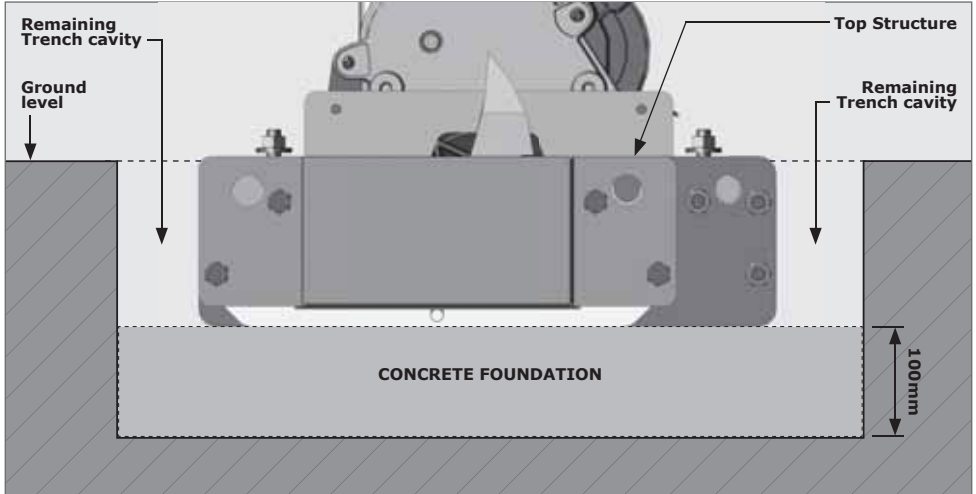


Ensure that the drain pipes will not interfere with the structure when it is placed in the trench.

Place the assembly in the trench and level the assembly using any type of propping or jacking method. Make sure that the top of the assembly is either in line with or a little higher than the ground level and pour concrete (minimum 45MPa after 28 days) into the cavity that remains.



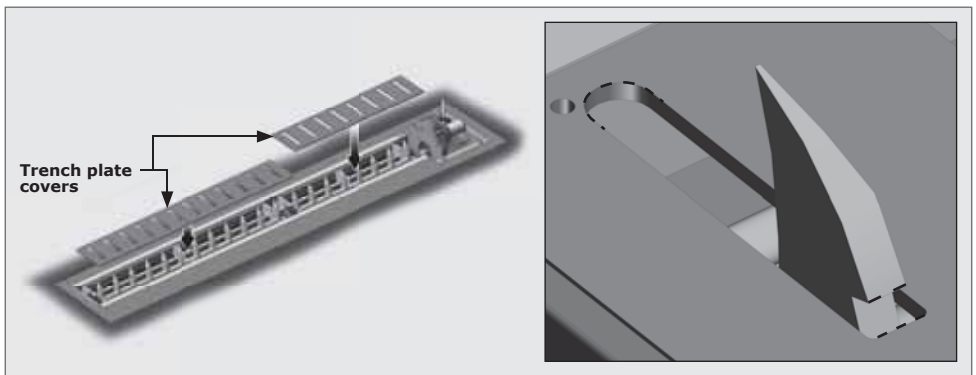
Do not pour any concrete into the gutter of the spikes module or drive link assembly.



STEP 3

FIGURE 42

13.4. Re-assembling the trench plates

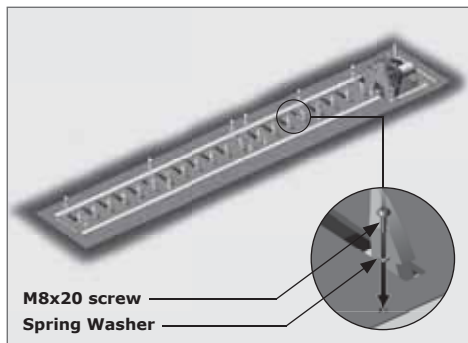


STEP 1

FIGURE 43



Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.



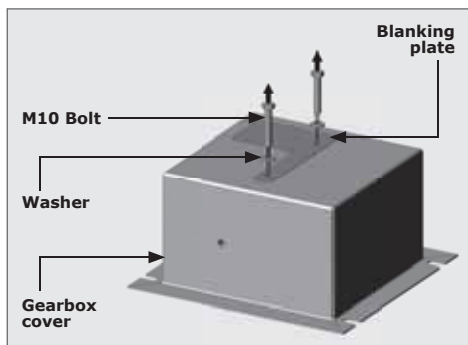
STEP 2

FIGURE 44

13.5. Integrating the SECTOR II with the CLAWS

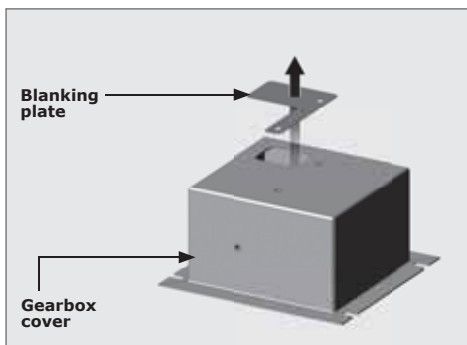
13.5.1. Directly mount THE SECTOR II onto the Independent Drive

13.5.1.1. Placing the gearbox cover into position



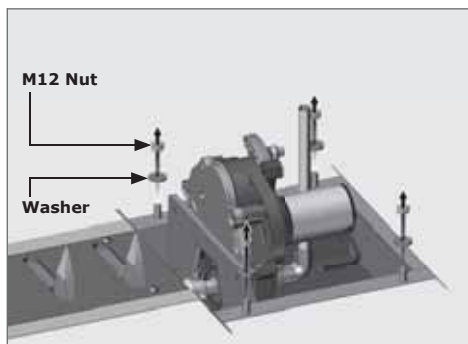
STEP 1

FIGURE 45



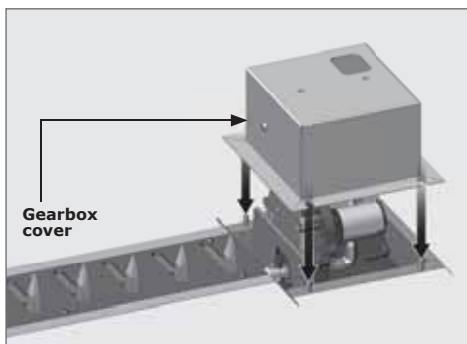
STEP 2

FIGURE 46



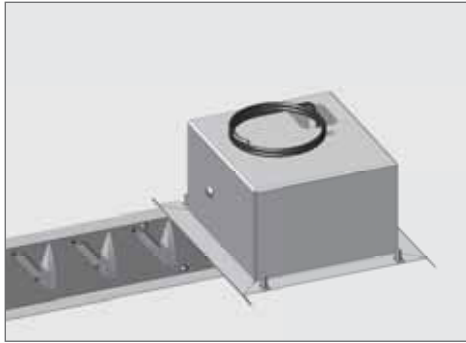
STEP 3

FIGURE 47



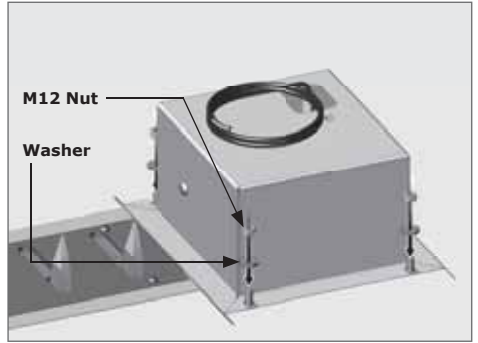
STEP 4

FIGURE 48



STEP 5

FIGURE 49



STEP 6

FIGURE 50

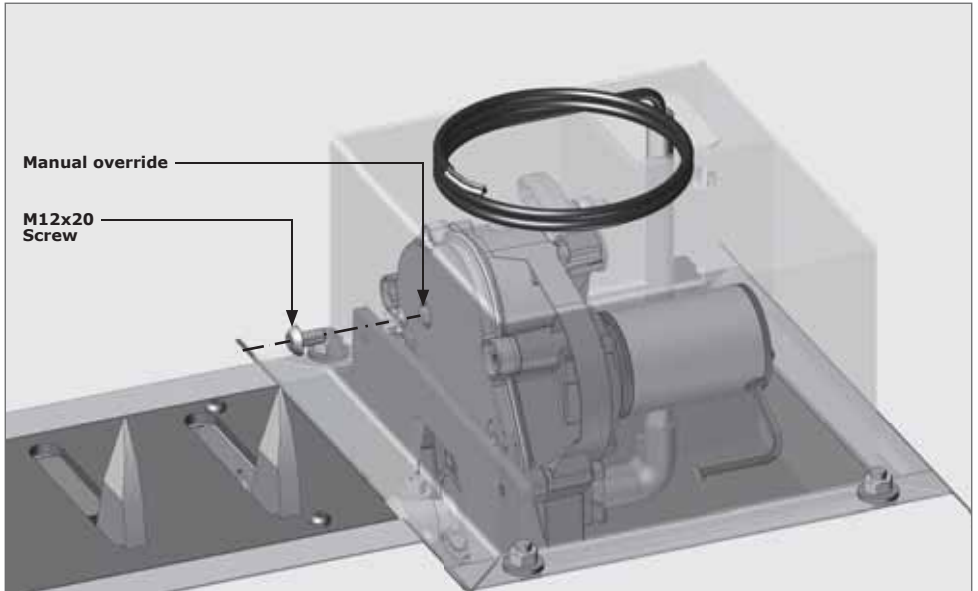
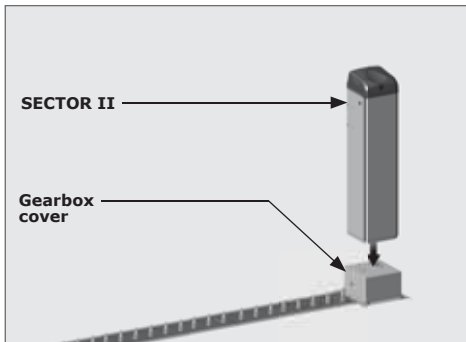


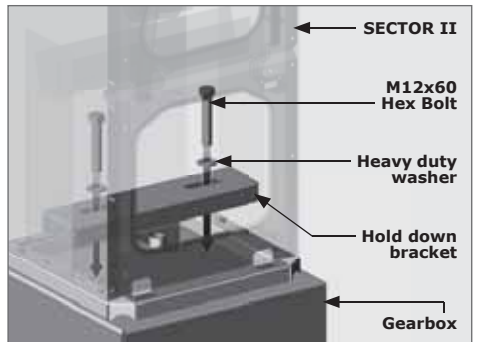
FIGURE 51. MANUAL OVERRIDE

13.5.1.2. Placing the SECTOR II into position



STEP 1

FIGURE 52



STEP 2

FIGURE 53

13.5.2. Separately-placed CLAWS and SECTOR II

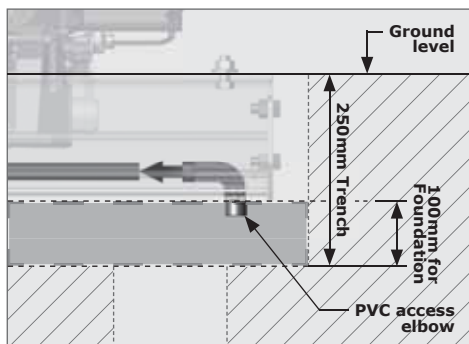
13.5.2.1. Running the conduit from the gearbox to the SECTOR II

STEP 1

Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.

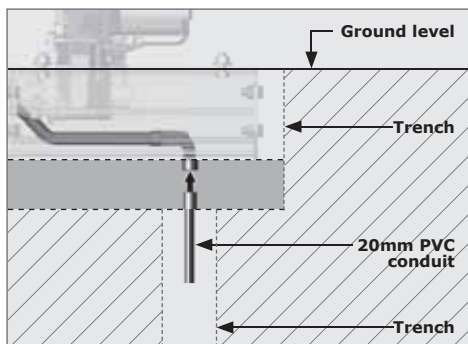


Drill a 20mm hole through the gutter plate using a 20mm hole saw for the proximity sensor conduit



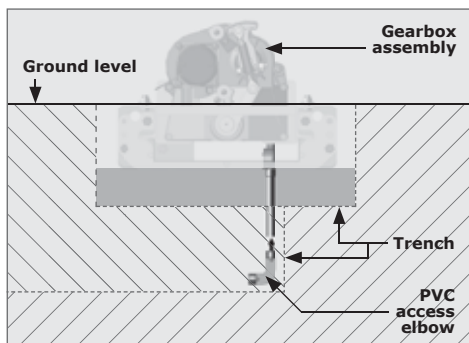
STEP 2

FIGURE 54



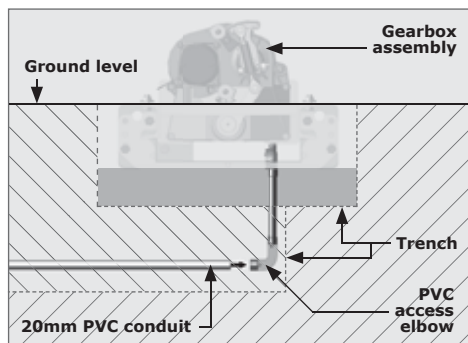
STEP 3

FIGURE 55



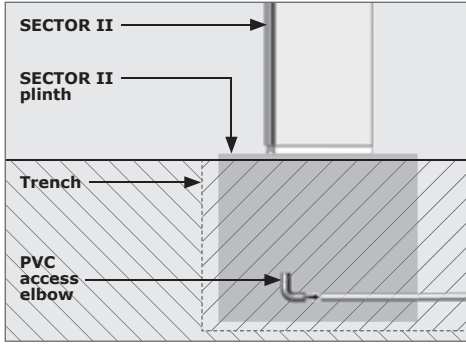
STEP 4

FIGURE 56



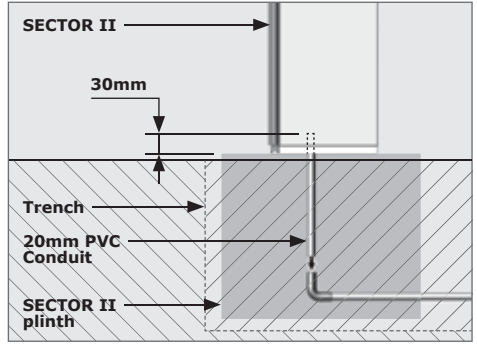
STEP 5

FIGURE 57



STEP 6

FIGURE 58



STEP 7

FIGURE 59

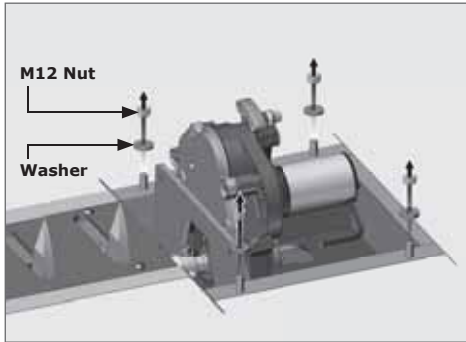
STEP 8

Route the **CLAWS** and Proximity sensor cables in the conduit to the SECTOR II.

STEP 9

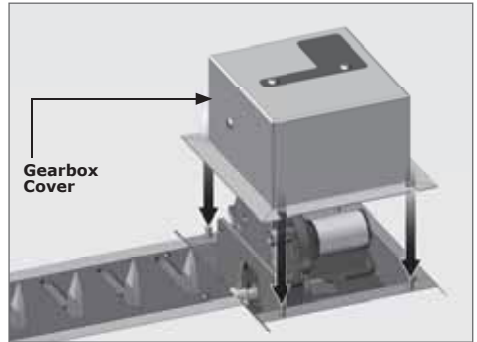
Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

13.5.2.2. Placing the gearbox cover into position



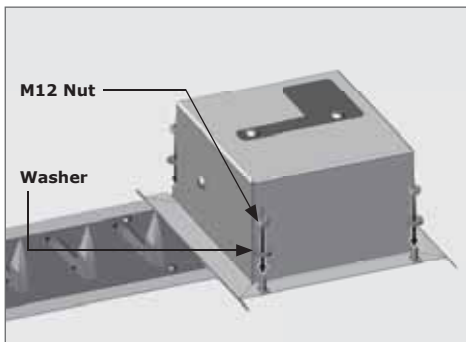
STEP 1

FIGURE 60



STEP 2

FIGURE 61



STEP 3

FIGURE 62

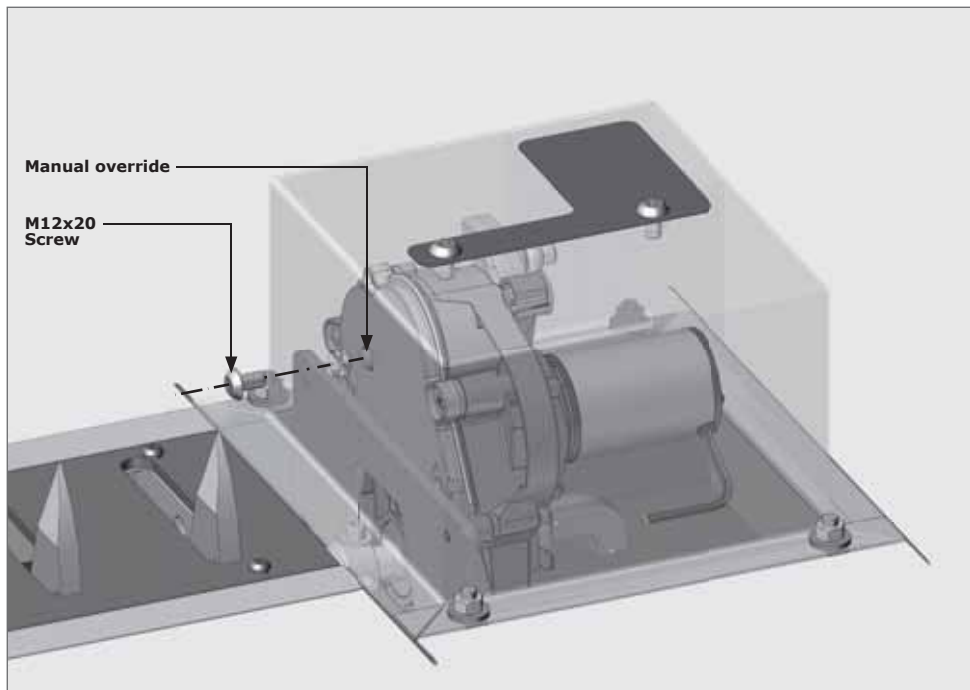
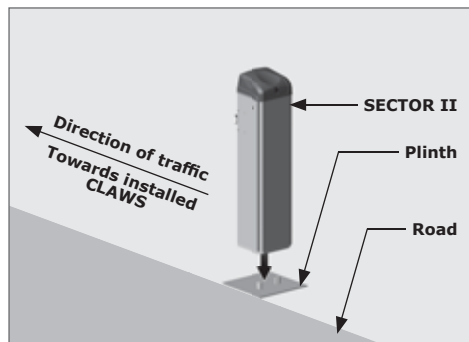


FIGURE 63. MANUAL OVERRIDE



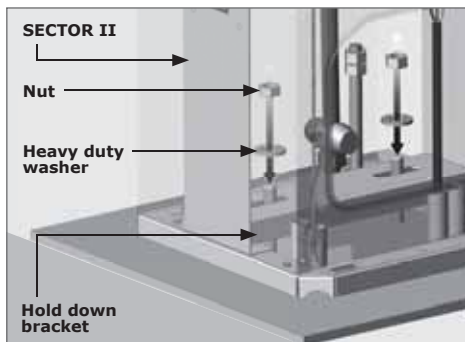
By removing the M12x20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.

13.5.2.3. Placing the SECTOR II into position



STEP 1

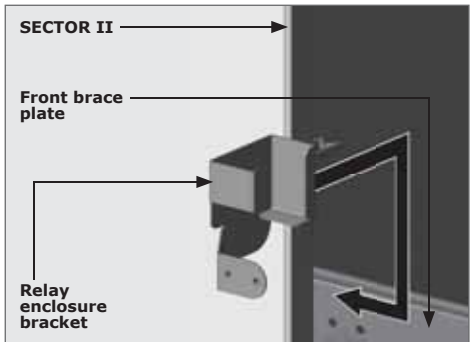
FIGURE 64



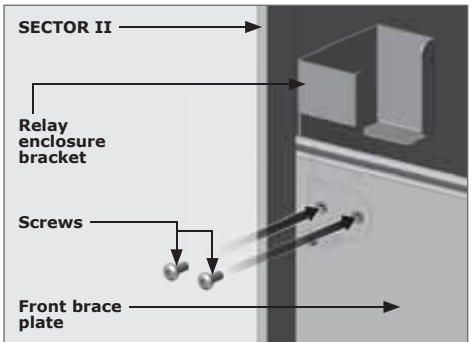
STEP 2

FIGURE 65

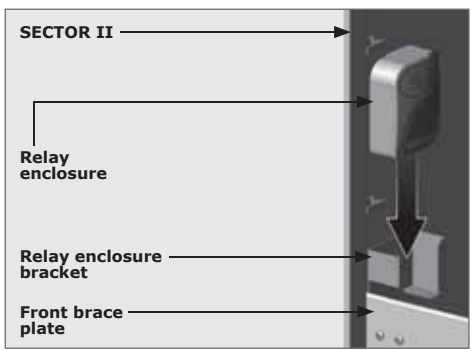
13.5.3. Fitting the relay enclosure and its bracket



STEP 1 FIGURE 66



STEP 2 FIGURE 67



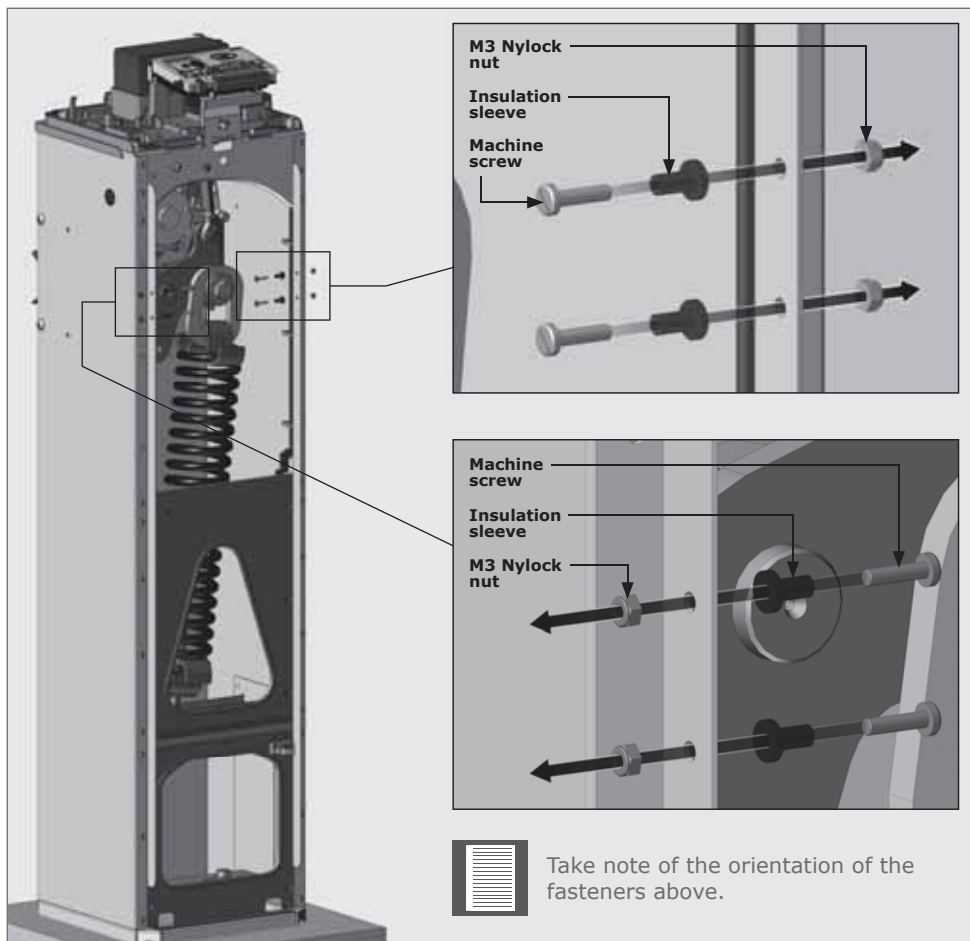
STEP 3 FIGURE 68



Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 16).

Complete the installation of the SECTOR II as per its full installation manual.

13.5.5. Fitting the CLAWS controller to the SECTOR II

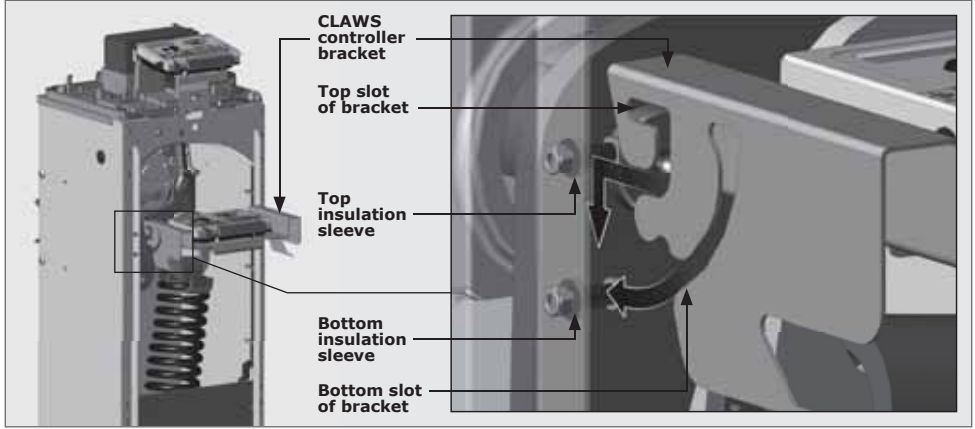
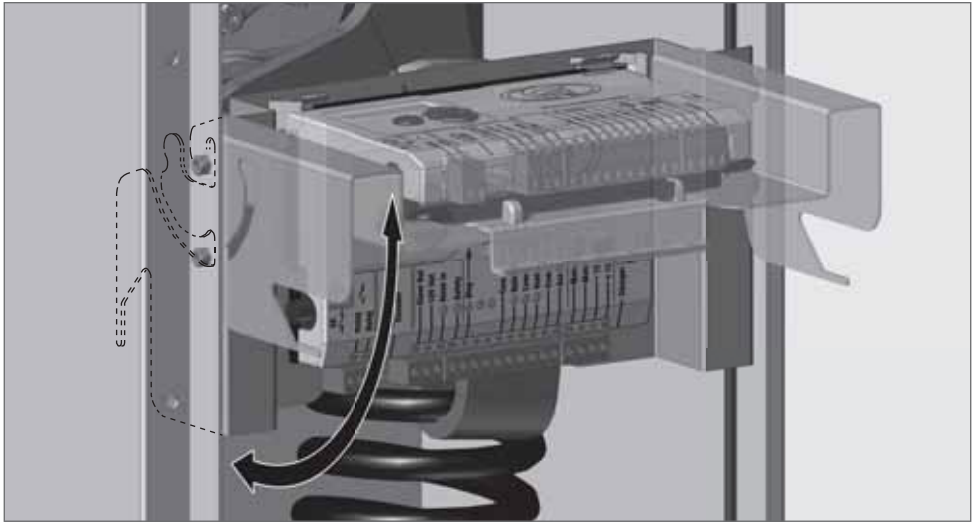


STEP 1

FIGURE 69

STEP 2

Keeping the **CLAWS** Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.

**FIGURE 70****FIGURE 71**

The bracket can be moved into a set angle of 70° by pivoting it upward from the bottom for better viewing of the LCD screen (Section 13, Figure 72).

It can also be moved lower down for optimum space when working on the gearbox (Section 13, Figure 73).



Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 13, Figure 70).

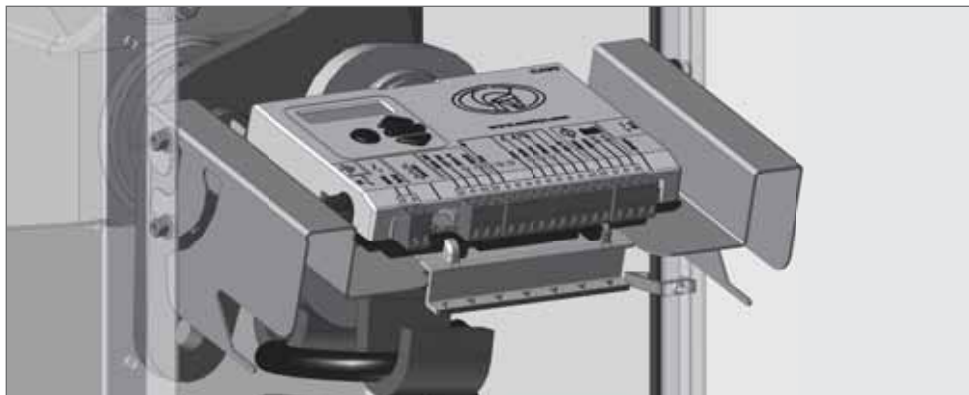


FIGURE 72. CLAWS CONTROLLER AND BRACKET AT FIXED 70° POSITION

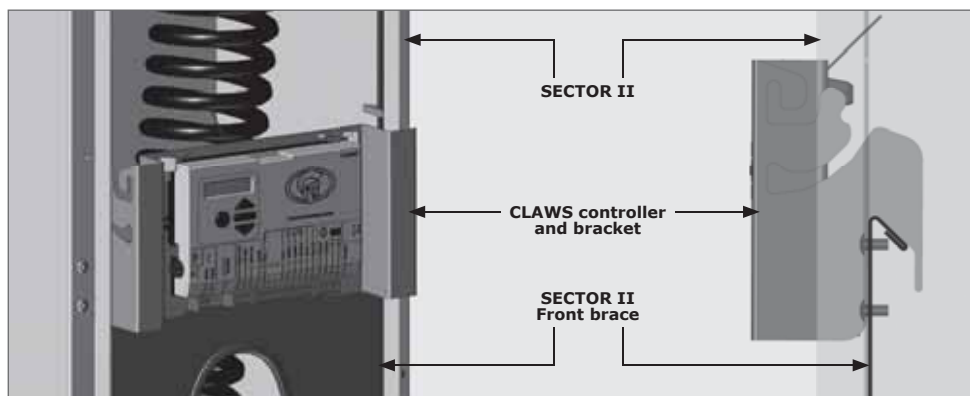


FIGURE 73. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION

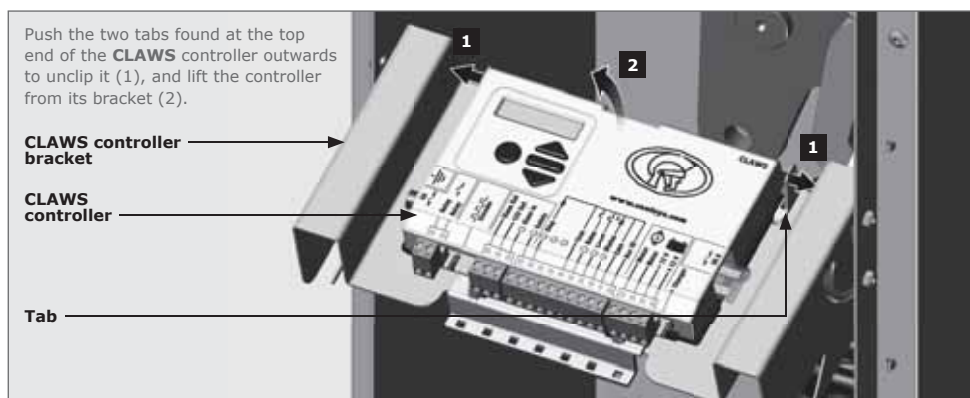


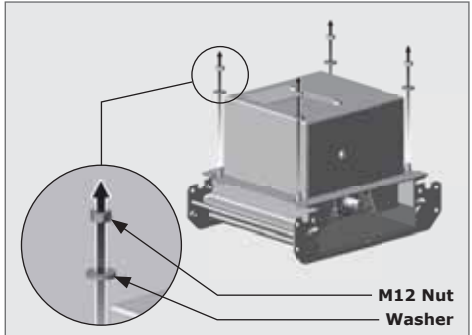
FIGURE 74. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET

STEP 3

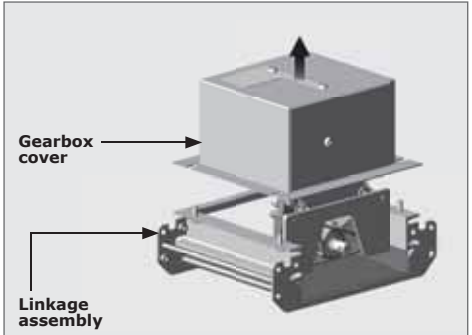
Connect harness and power supply. Refer to the wiring diagrams and controller settings.

14. LHS Independent Drive Flush Mount - Similar Direction of Travel

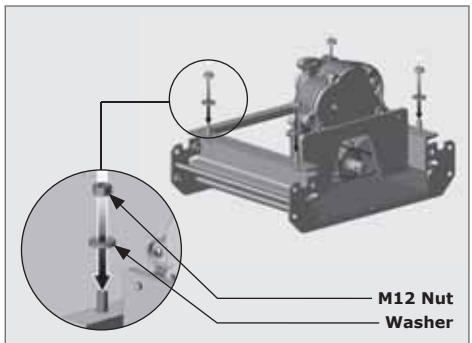
14.1. Preparing the Drive Linkage Assembly



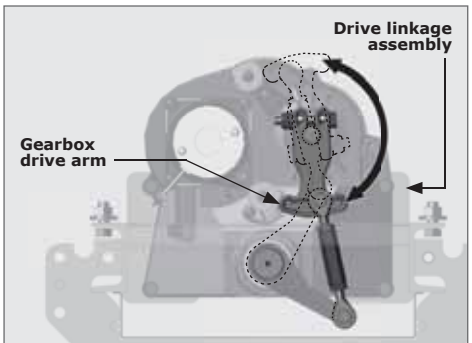
STEP 1 FIGURE 1



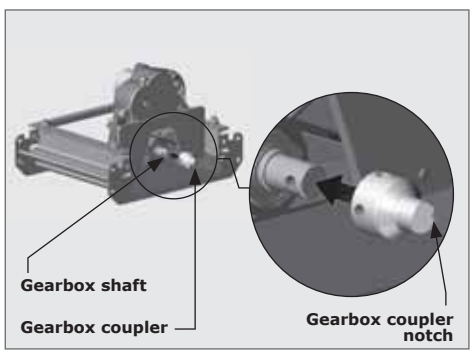
STEP 2 FIGURE 2



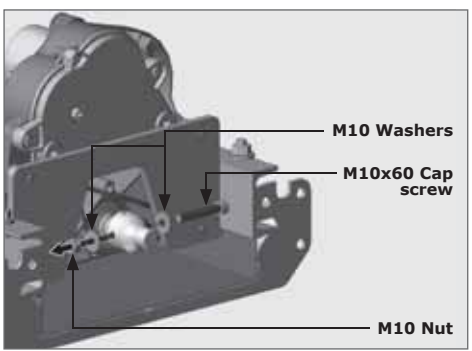
STEP 3 FIGURE 3



STEP 4 FIGURE 4



STEP 5 FIGURE 5



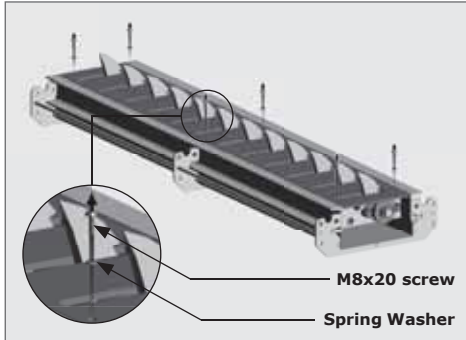
STEP 6 FIGURE 6



Note the orientation of the gearbox coupler notch is at the 3 o'clock position and that the gearbox drive arm is down as shown in Section 14, Figure 5.

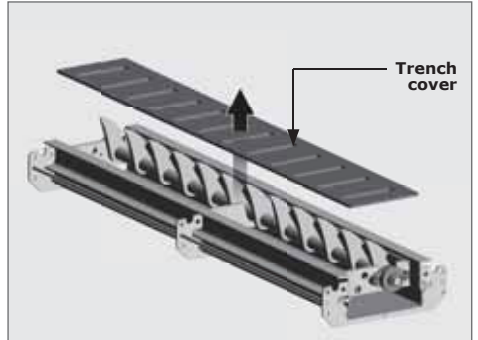
14.2. Spike Module Assembly

14.2.1. Preparing the Spike Module assembly(ies) for installation



STEP 1

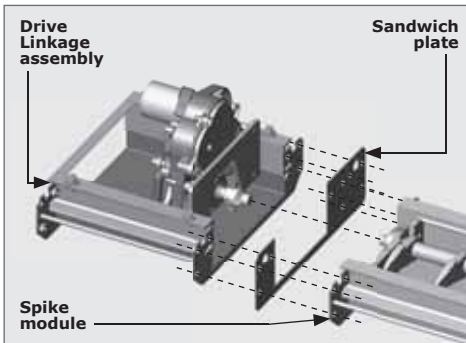
FIGURE 7



STEP 2

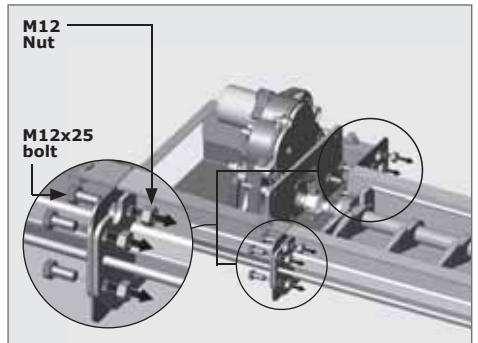
FIGURE 8

14.2.2. Attaching the drive linkage assembly to the spike module



STEP 1

FIGURE 9



STEP 2

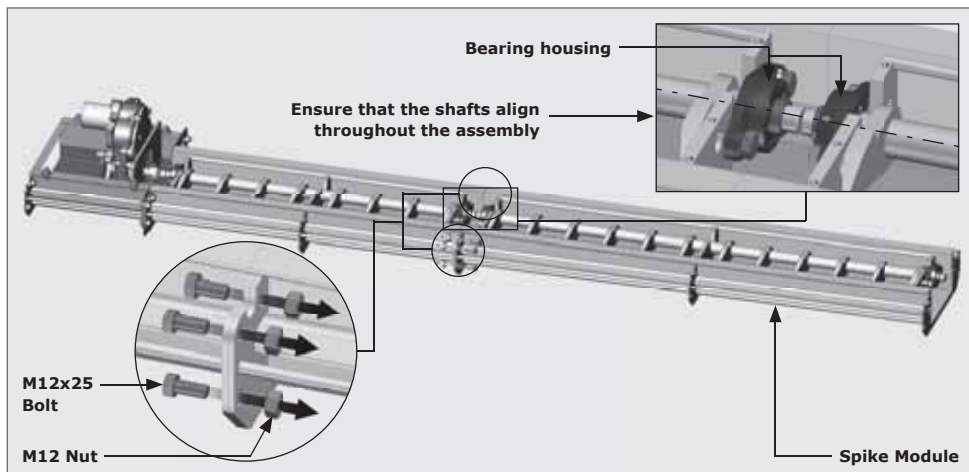
FIGURE 10



Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly.

STEP 3

Using six M12x25 bolts, fix one spike module to another (Section 14, Figure 11).

**FIGURE 11**

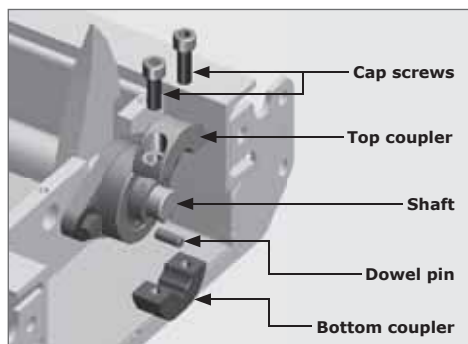
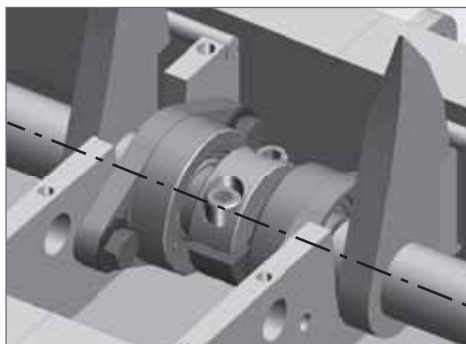
To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

14.2.3. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

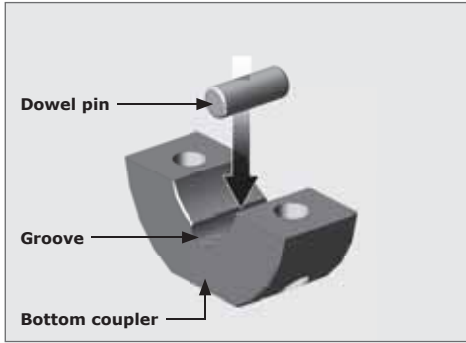


It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.

**FIGURE 12. SHAFT COUPLER****FIGURE 13**

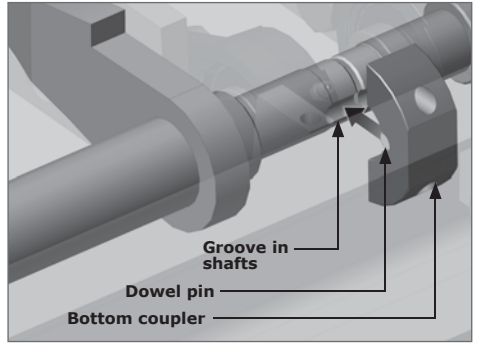


Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.



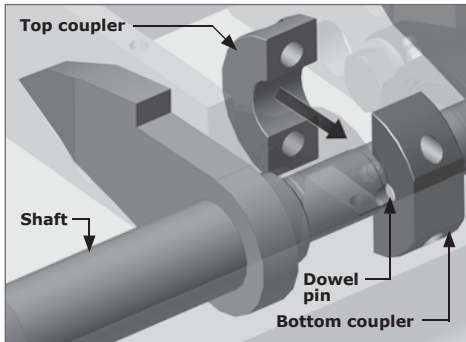
STEP 1

FIGURE 14



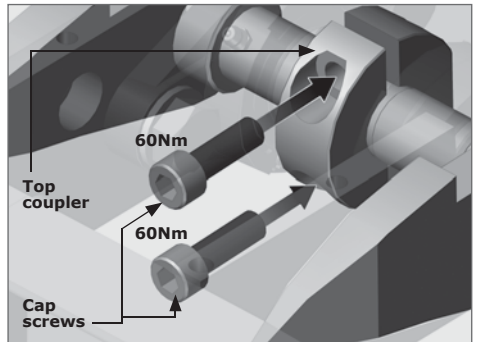
STEP 2

FIGURE 15



STEP 3

FIGURE 16



STEP 4

FIGURE 17

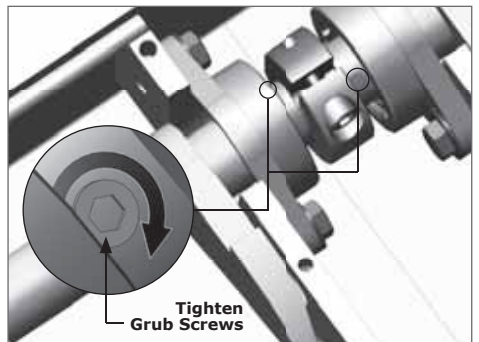
STEP 5

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.



STEP 6

FIGURE 18



STEP 7

FIGURE 19

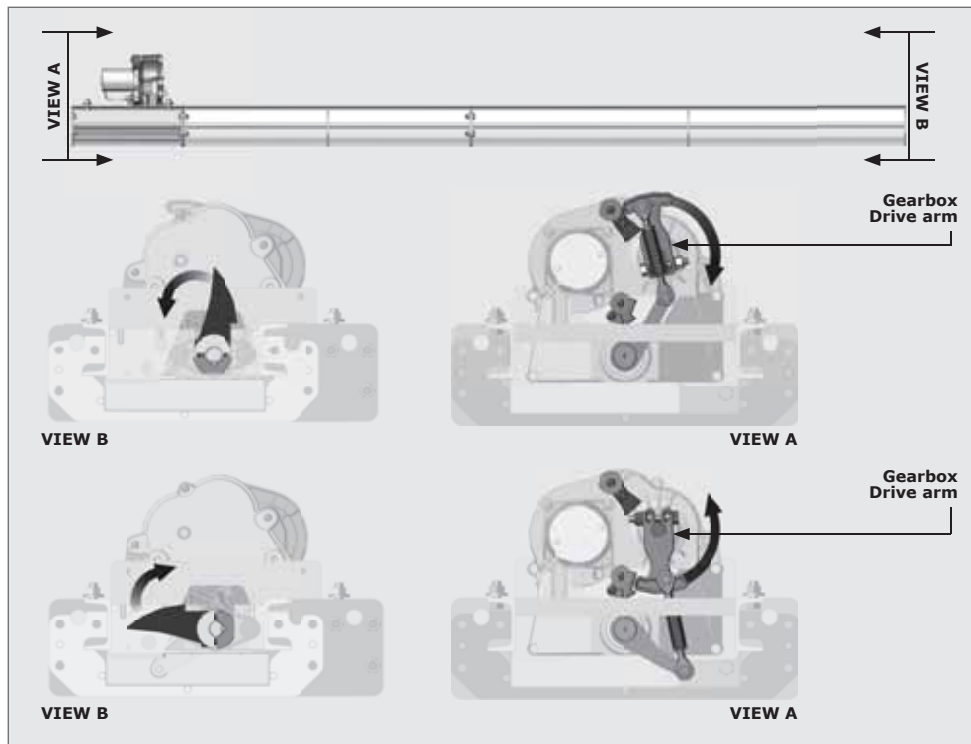
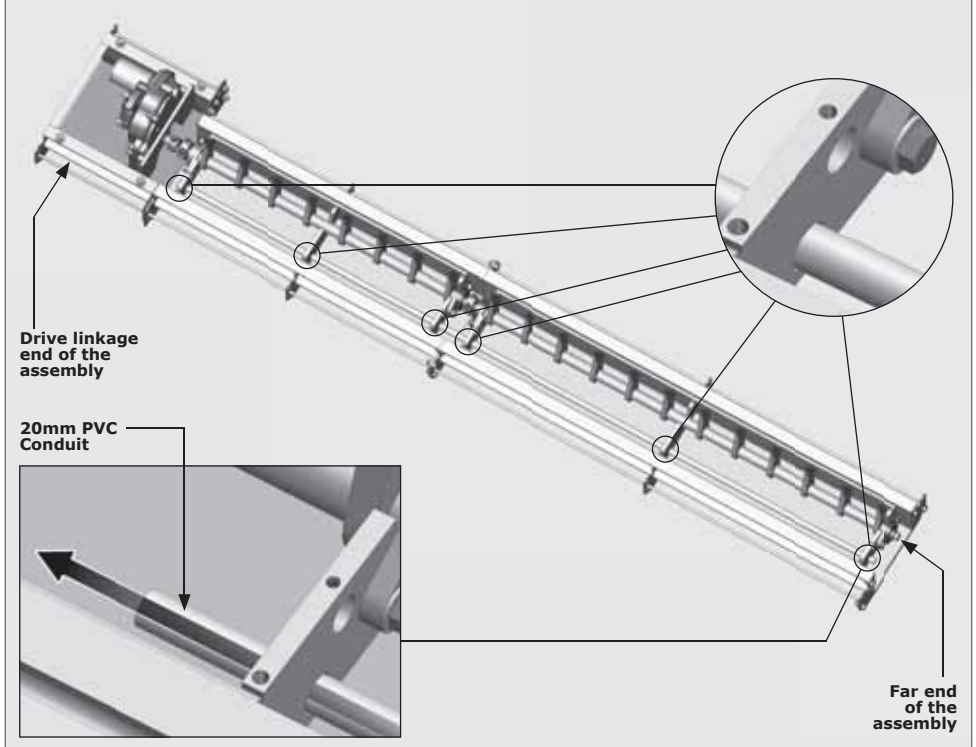



FIGURE 20. CORRECTLY ALIGNED SPIKE AND DRIVE MODULES

14.2.4. Proximity sensor installation



STEP 1

FIGURE 21

 The length of the PVC conduit will be relative to the length of the spike modules combined. Ensure that a further 38mm is added to this to account for the modules and coupling (Refer to Section 14, Figure 22).

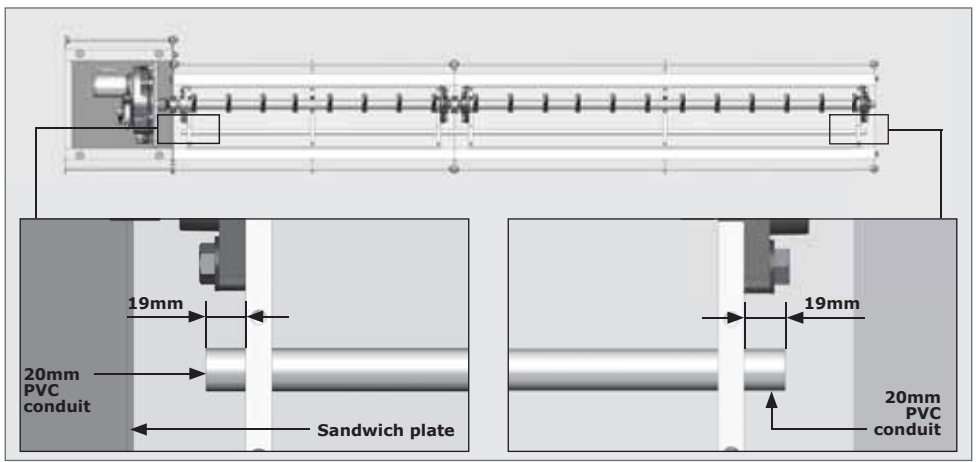
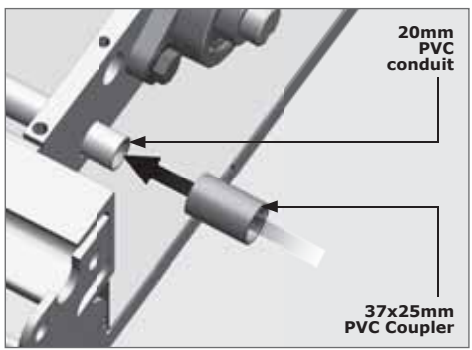


FIGURE 22

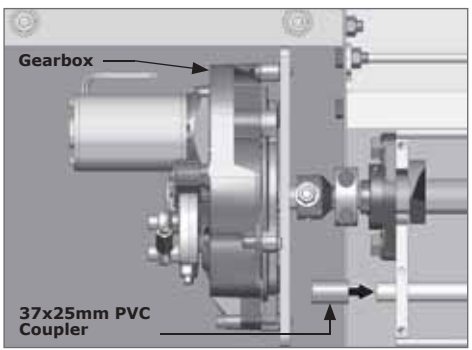


Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.



STEP 2

FIGURE 23

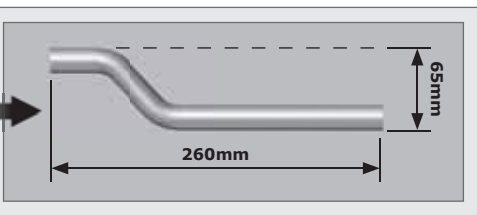
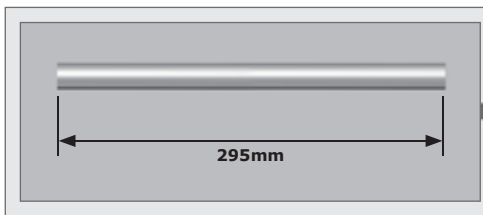


STEP 3

FIGURE 24



It is necessary to bend PVC conduit to circumvent the gearbox bulkhead to continue. The use of a conduit spring is recommended to avoid collapsing the pipe. Section 14, Figure 25 below is a guideline that can be used to achieve this.



STEP 4

FIGURE 25

STEP 5

Connect the bent piece of conduit to the PVC coupler installed in Section 14, Figure 24 Step 3. After it is connected, it should resemble Section 14, Figure 26.

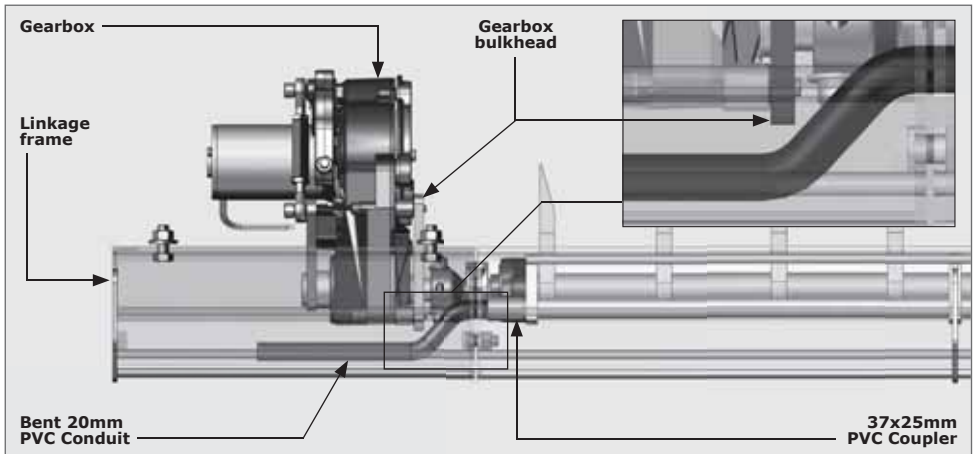
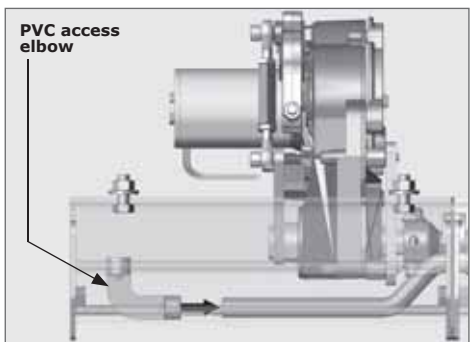


FIGURE 26

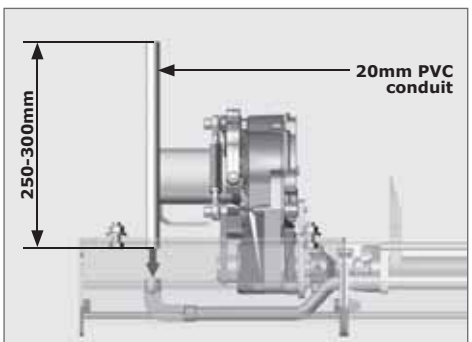


Steps 6-7 is only applicable if the SECTOR II will be mounted directly onto the **CLAWS** Gearbox. If they are going to be mounted separately, a trench for the conduit and cables will need to be dug (Refer to Section 14.5.2.).



STEP 6

FIGURE 27



STEP 7

FIGURE 28



Please ensure that the moving mechanical parts do not rub against the conduit or cables.

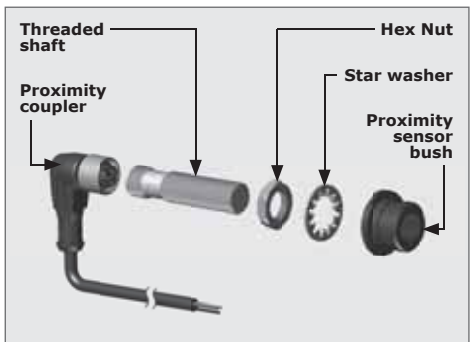


FIGURE 29. PROXIMITY SENSOR

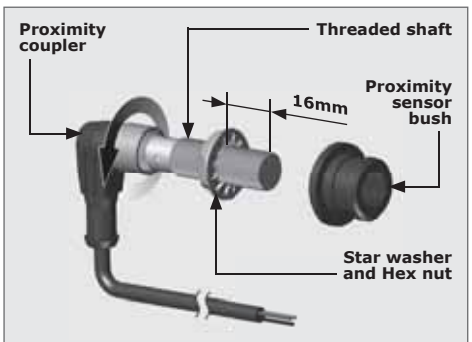


FIGURE 30. PROXIMITY SENSOR

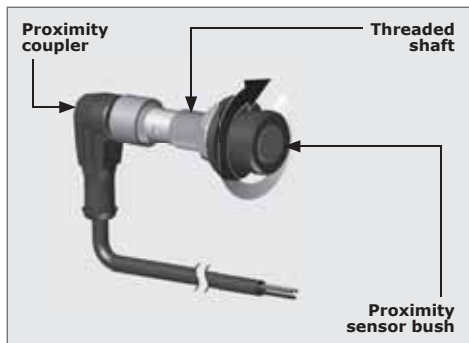
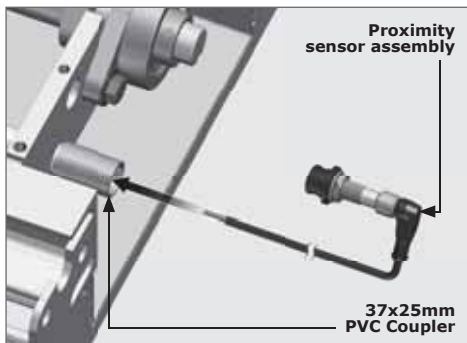


FIGURE 31. PROXIMITY SENSOR



STEP 6

FIGURE 32

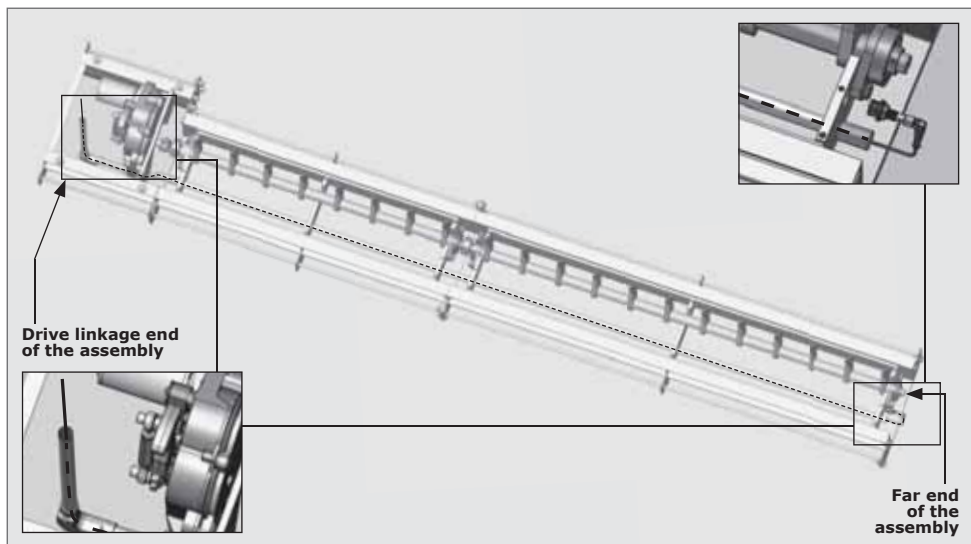
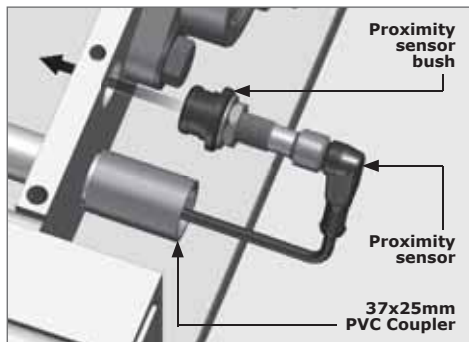


FIGURE 33

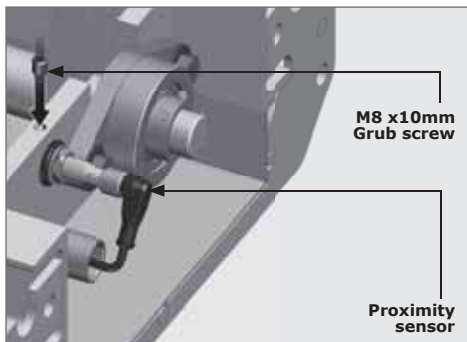


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed up the SECTOR II at a later stage.



STEP 7

FIGURE 34

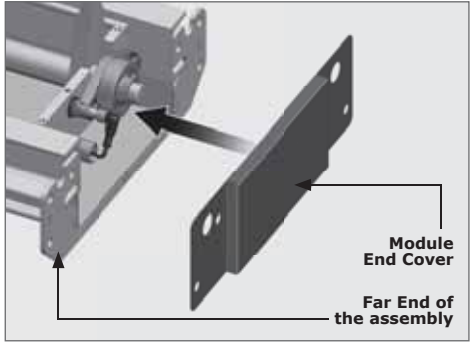


STEP 8

FIGURE 35

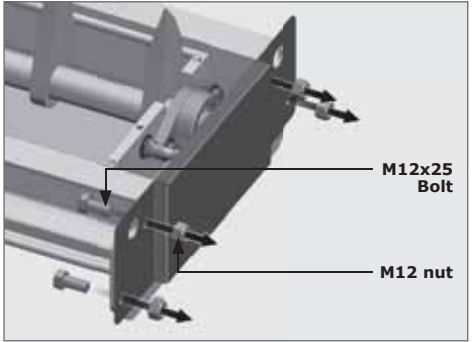
14.2.5. Attaching the End Covers to the Assembly

14.2.5.1. Attaching the Module End cover



STEP 1

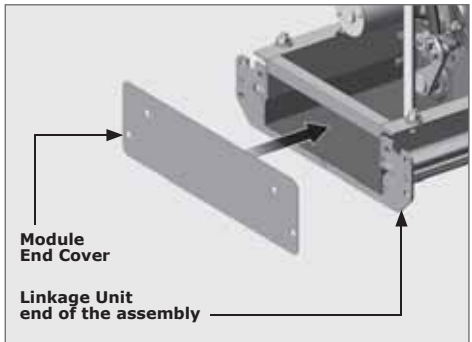
FIGURE 36



STEP 2

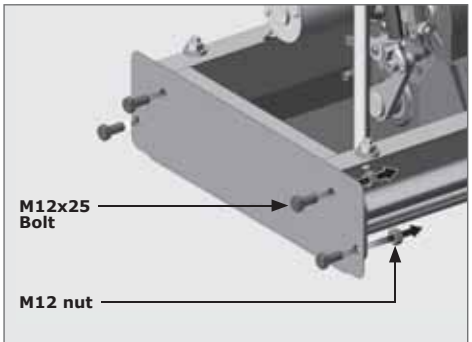
FIGURE 37

14.2.5.2. Attaching the Linkage Unit End cover



STEP 1

FIGURE 38

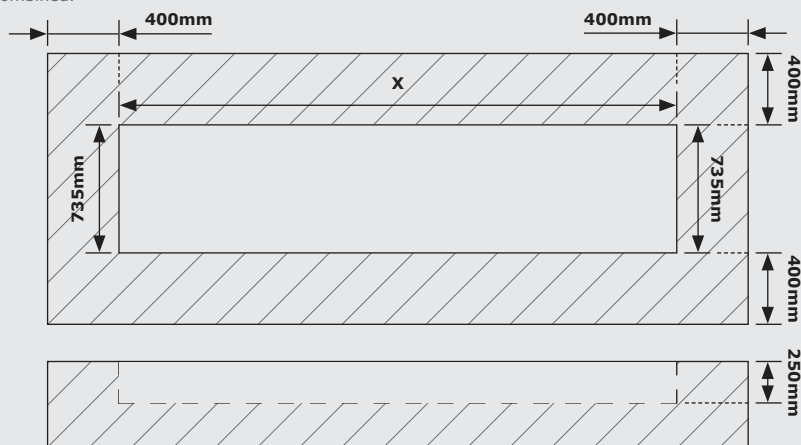


STEP 2

FIGURE 39

14.3. Preparing the trench and drainage system

Dig a hole following the dimensions below. Dimension 'X' is relative to the total length of the linkage unit and spike models combined.



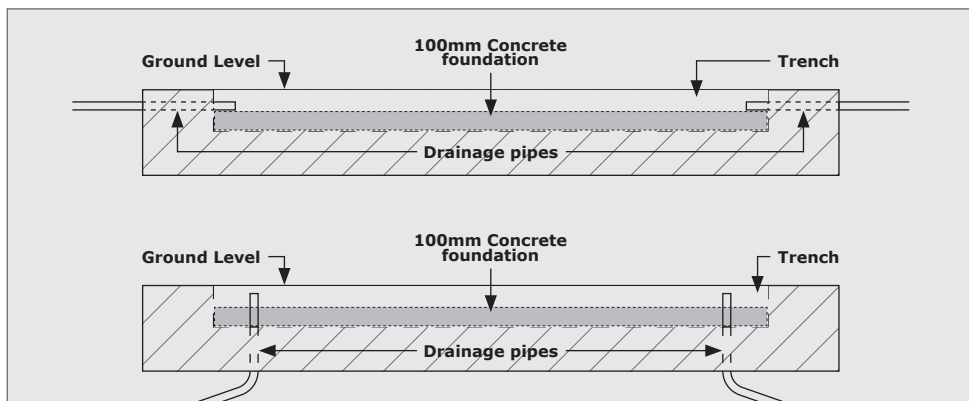
STEP 1

FIGURE 40

Drainage pipes must be laid at one or both ends of the trench to allow water to flow either into storm water drains or into any other area away from the installation. Section 14, Figure 41 shows two recommended drainage configurations. Once complete, hold them in place by pouring a 100mm concrete foundation and level off.



If the **SECTOR II** and **CLAWS** are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and **SECTOR II**. This must be done before any concrete is poured (Section 14.5.2.).



STEP 2

FIGURE 41



Make sure the drain pipes do not interfere with the structure when it will be placed in the trench.

14.3.1. Concreting the assembly into the trench.

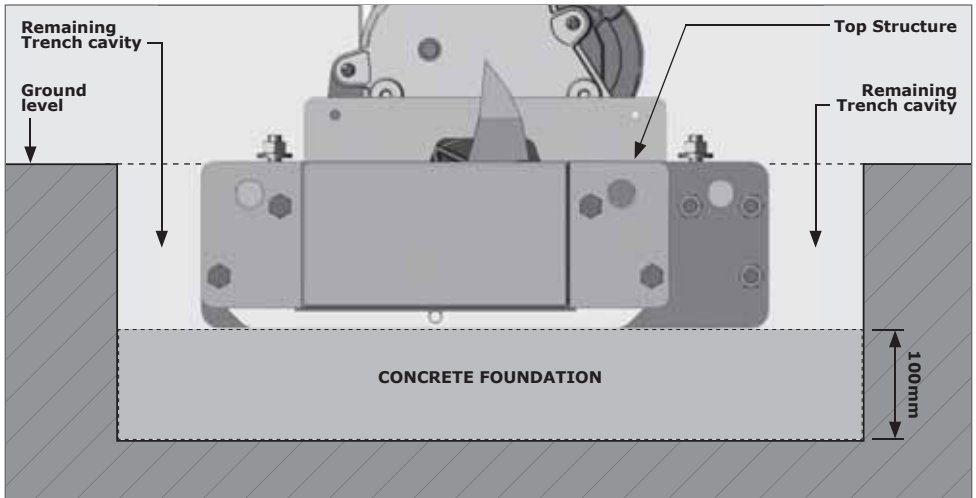


Ensure that the drain pipes will not interfere with the structure when it is placed in the trench.

Place the assembly in the trench and level the assembly using any type of propping or jacking method. Make sure that the top of the assembly is either in line with or a little higher than the ground level and pour concrete (minimum 45MPa after 28 days) into the cavity that remains.



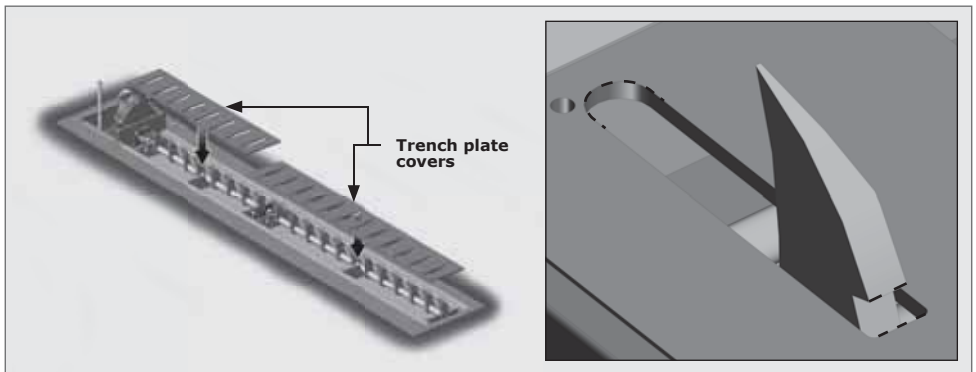
Do not pour any concrete into the gutter of the spikes module or drive link assembly.



STEP 3

FIGURE 42

14.4. Re-assembling the trench plates

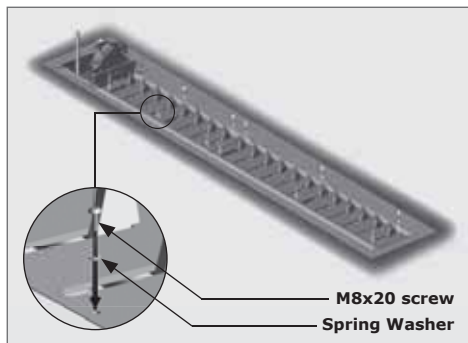


STEP 1

FIGURE 43



Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.



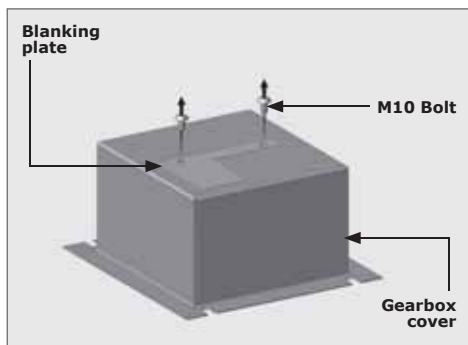
STEP 2

FIGURE 44

14.5. Integrating the SECTOR II with the CLAWS

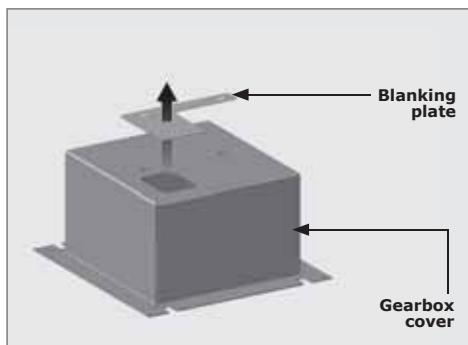
14.5.1. Directly mount THE SECTOR II onto the Independent Drive

14.5.1.1. Placing the gearbox cover into position



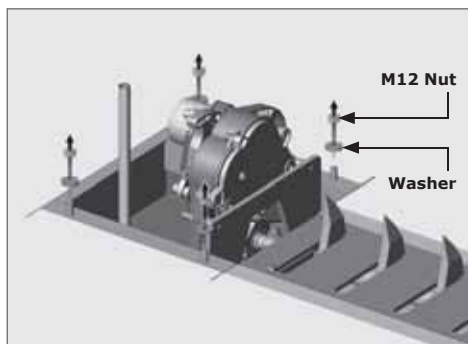
STEP 1

FIGURE 45



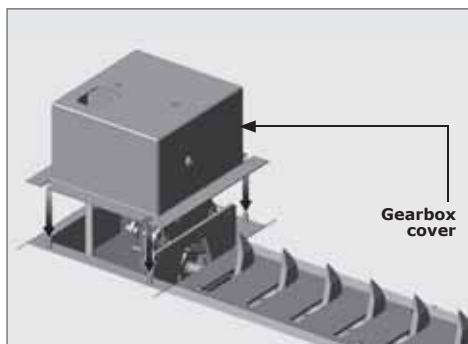
STEP 2

FIGURE 46



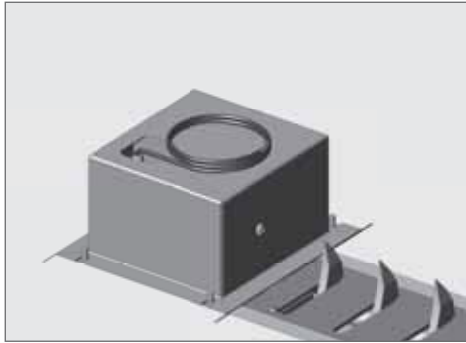
STEP 3

FIGURE 47



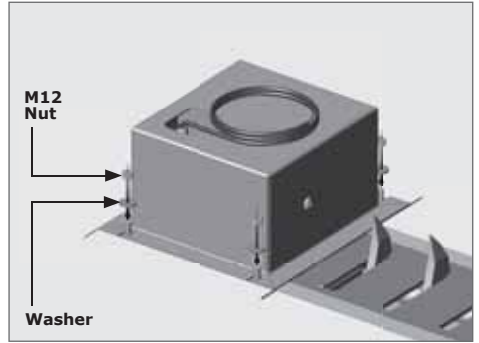
STEP 4

FIGURE 48



STEP 5

FIGURE 49



STEP 6

FIGURE 50

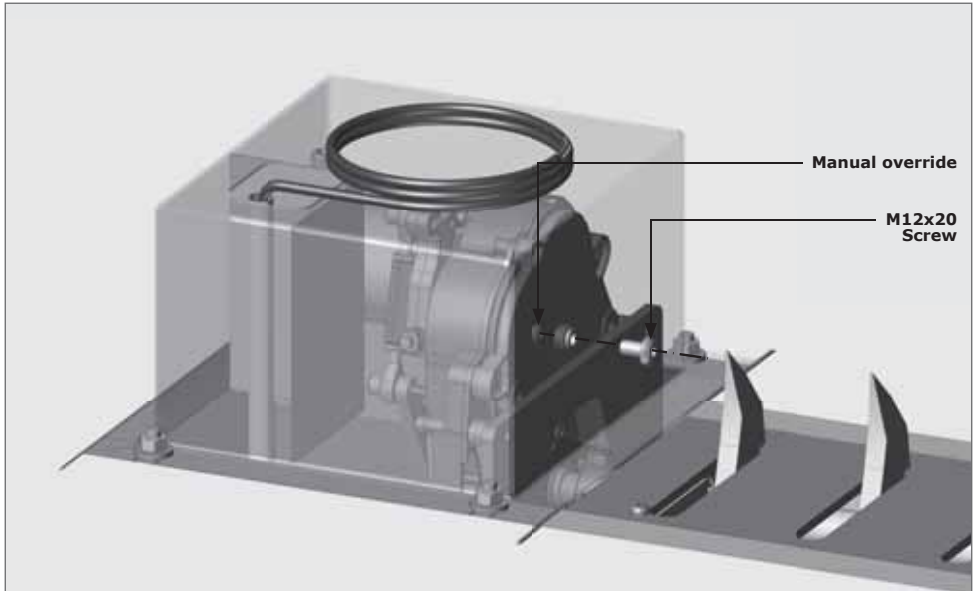
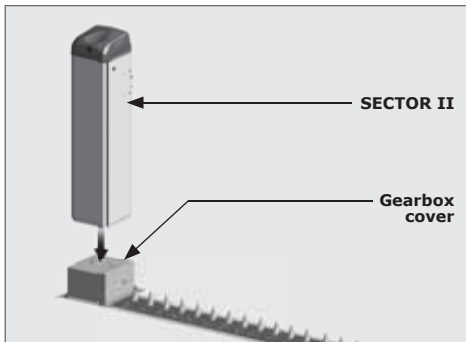


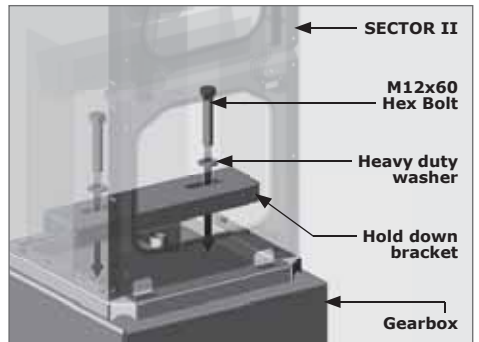
FIGURE 51. MANUAL OVERRIDE

14.5.1.2. Placing the SECTOR II into position



STEP 1

FIGURE 52



STEP 2

FIGURE 53

14.5.2. Separately-placed CLAWS and SECTOR II

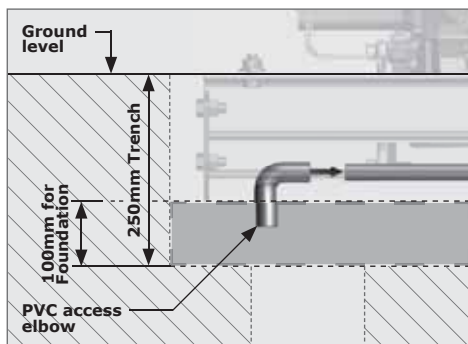
14.5.2.1. Running the conduit from the gearbox to the SECTOR II

STEP 1

Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.

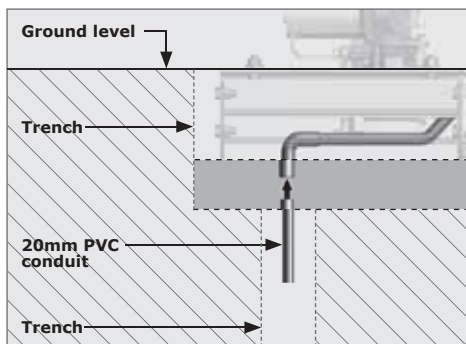


Drill a 20mm hole through the gutter plate using a 20mm hole saw for the proximity sensor conduit



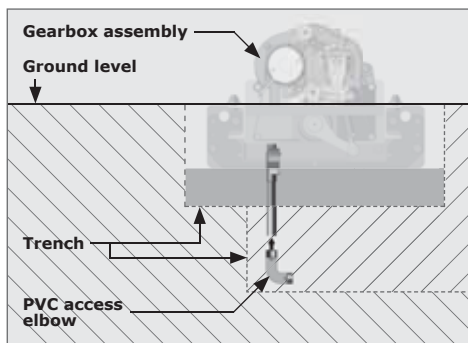
STEP 2

FIGURE 54



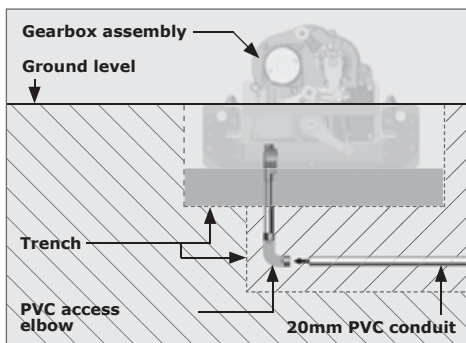
STEP 3

FIGURE 55



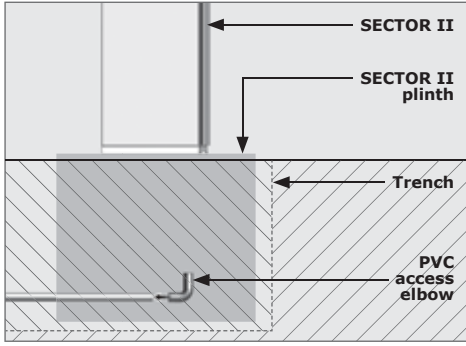
STEP 4

FIGURE 56



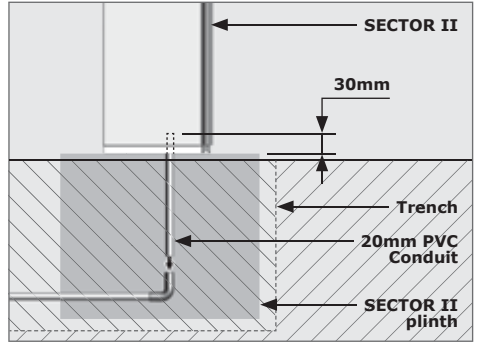
STEP 5

FIGURE 57



STEP 6

FIGURE 58



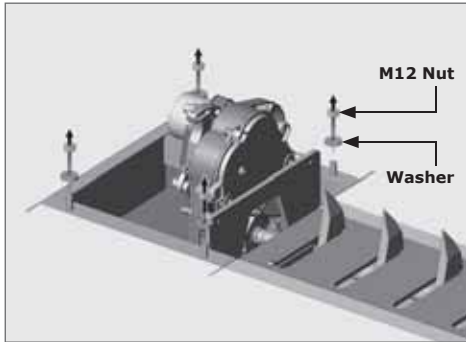
STEP 7

FIGURE 59

STEP 8
Route the **CLAWS** and Proximity sensor cables in the conduit to the SECTOR II.

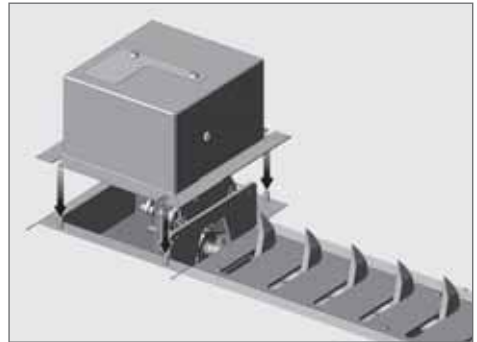
STEP 9
Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

14.5.2.2. Placing the gearbox cover into position



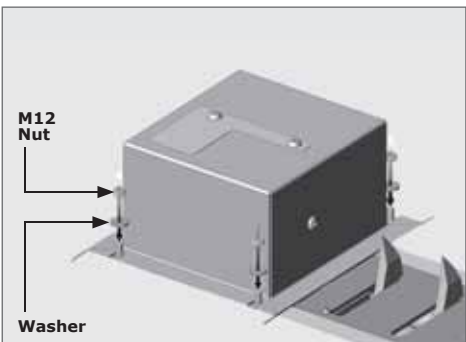
STEP 1

FIGURE 60



STEP 2

FIGURE 61



STEP 3

FIGURE 62

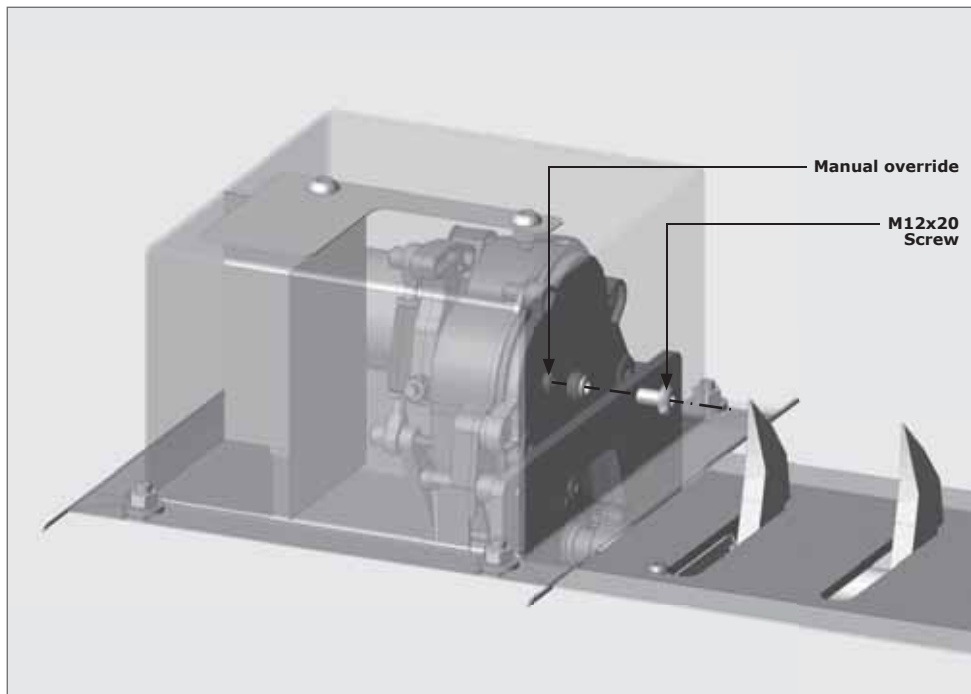
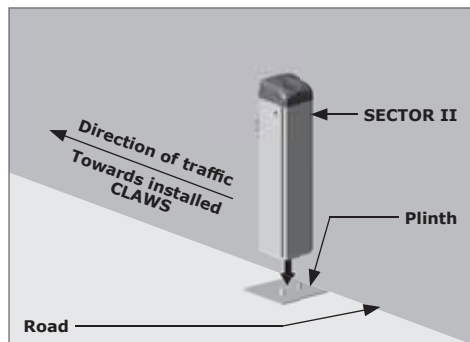


FIGURE 63. MANUAL OVERRIDE



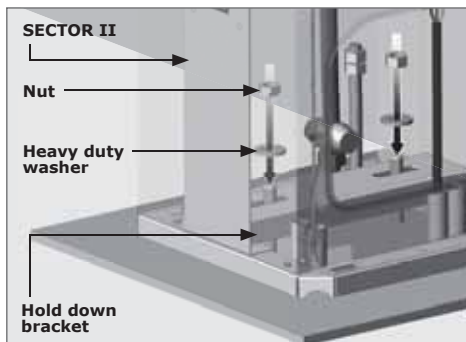
By removing the M12x20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.

14.5.2.3. Placing the SECTOR II into position



STEP 1

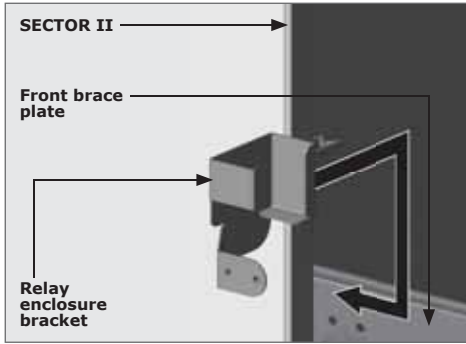
FIGURE 64



STEP 2

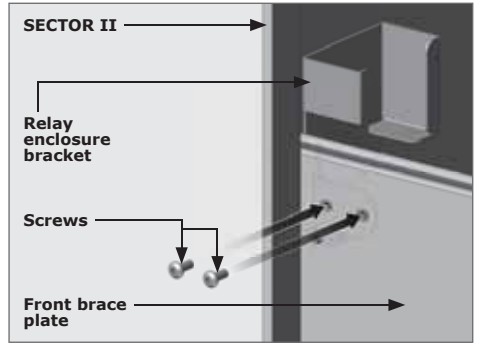
FIGURE 65

14.5.3. Fitting the relay enclosure and its bracket



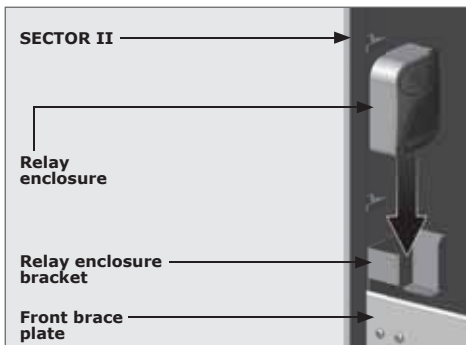
STEP 1

FIGURE 66



STEP 2

FIGURE 67



STEP 3

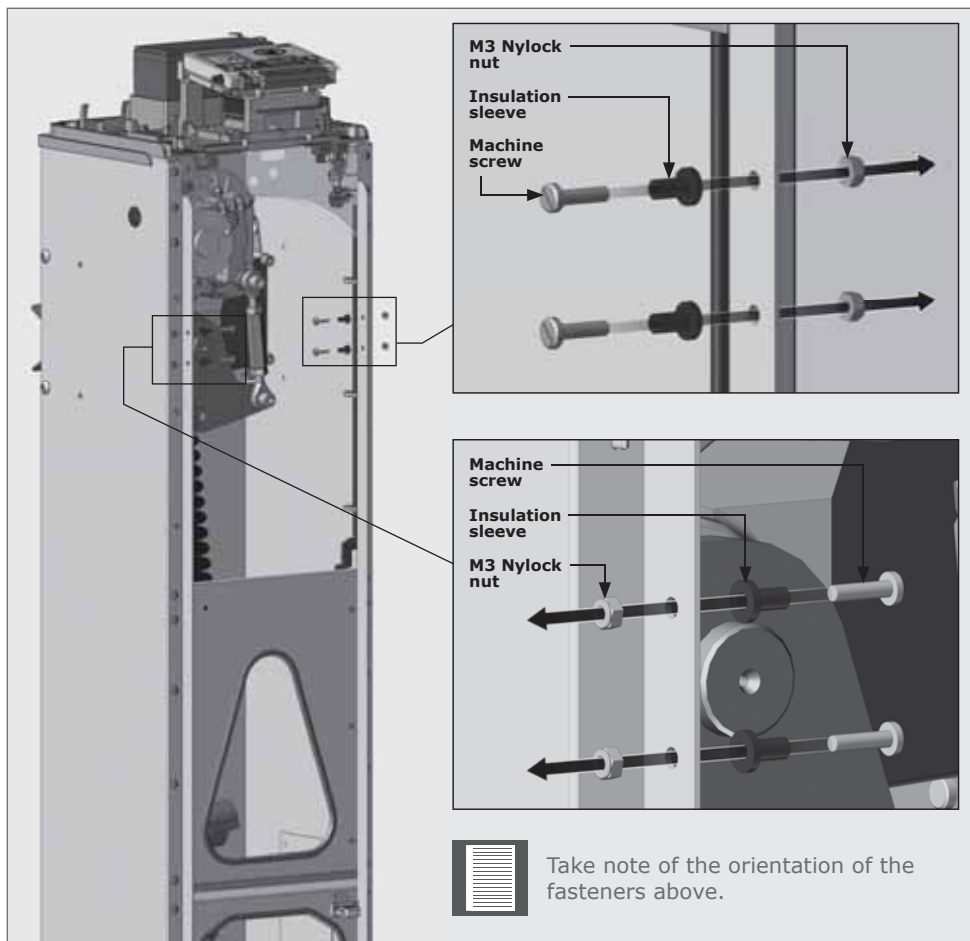
FIGURE 68



Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 16).

Complete the installation of the SECTOR II as per its full installation manual.

14.5.5. Fitting the CLAWS controller to the SECTOR II

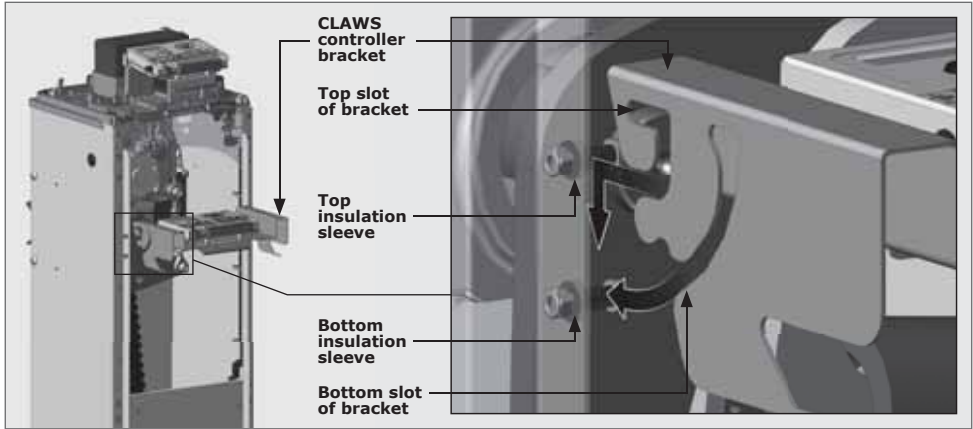
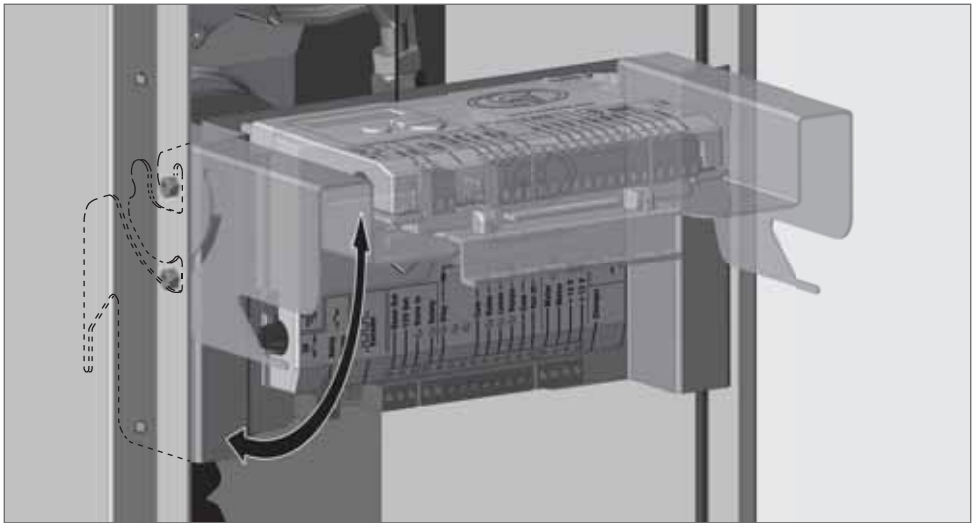


STEP 1

FIGURE 69

STEP 2

Keeping the **CLAWS** Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.

**FIGURE 70****FIGURE 71**

The bracket can be moved into a set angle of 70° by pivoting it upward from the bottom for better viewing of the LCD screen (Section 14, Figure 72).

It can also be moved lower down for optimum space when working on the gearbox (Section 14, Figure 73).



Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 14, Figure 70).

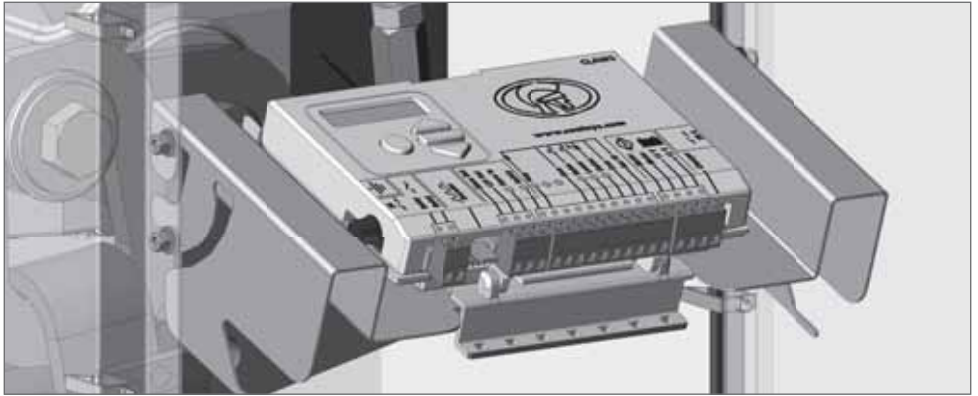


FIGURE 72. CLAWS CONTROLLER AND BRACKET AT FIXED 70° POSITION

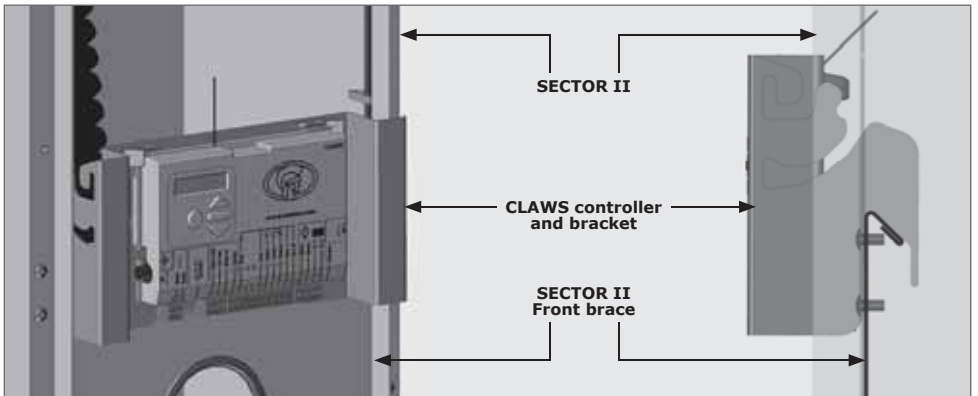


FIGURE 73. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION

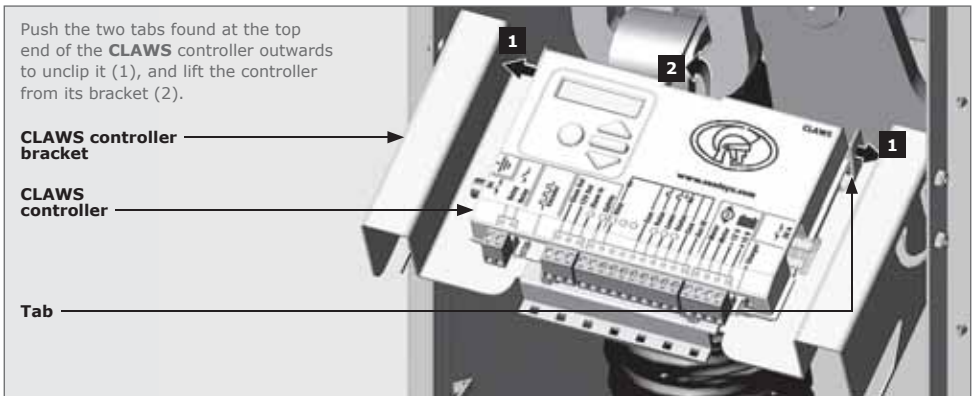


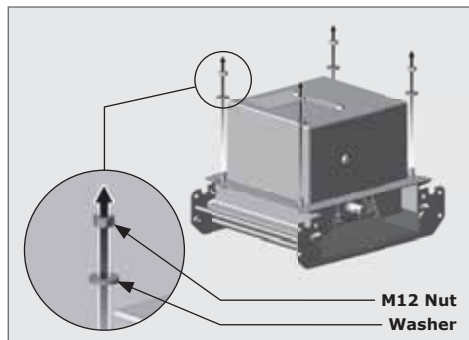
FIGURE 74. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET

STEP 3

Connect harness and power supply. Refer to the wiring diagrams and controller settings.

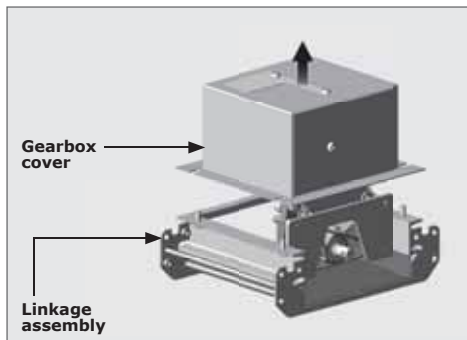
15. LHS Independent Drive Flush Mount - Opposing Direction of Travel

15.1. Preparing the Drive Linkage Assembly



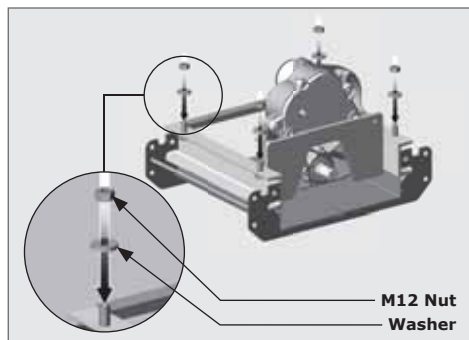
STEP 1

FIGURE 1



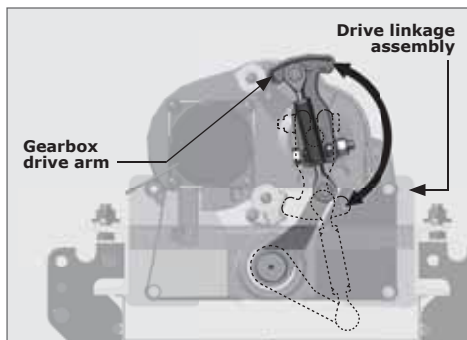
STEP 2

FIGURE 2



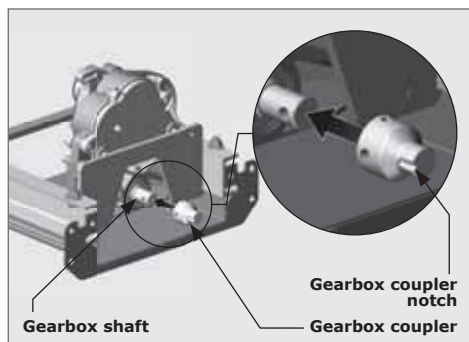
STEP 3

FIGURE 3



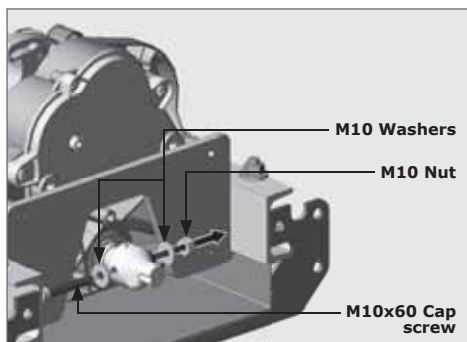
STEP 4

FIGURE 4



STEP 5

FIGURE 5



STEP 6

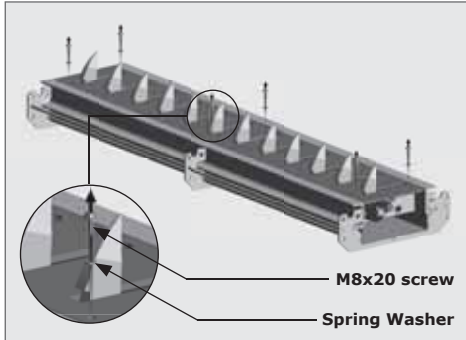
FIGURE 6



Note the orientation of the gearbox coupler notch is at the 9 o'clock position and that the gearbox drive arm is up as shown in Section 15, Figure 5.

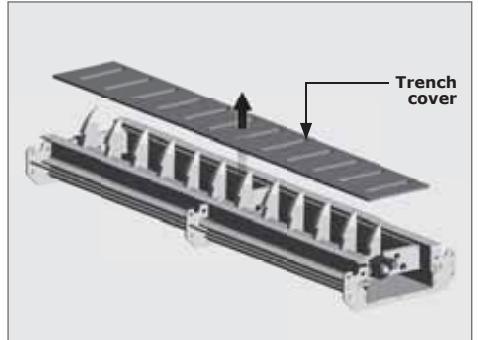
15.2. Spike Module Assembly

15.2.1. Preparing the Spike Module assembly(ies) for installation



STEP 1

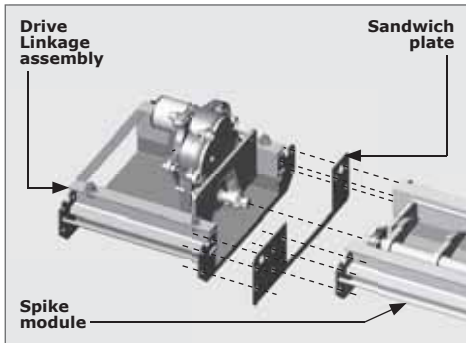
FIGURE 7



STEP 2

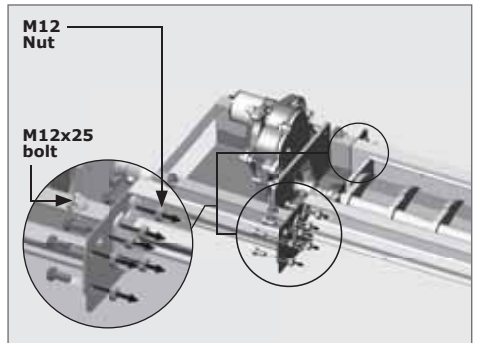
FIGURE 8

15.2.2. Attaching the drive linkage assembly to the spike module



STEP 1

FIGURE 9



STEP 2

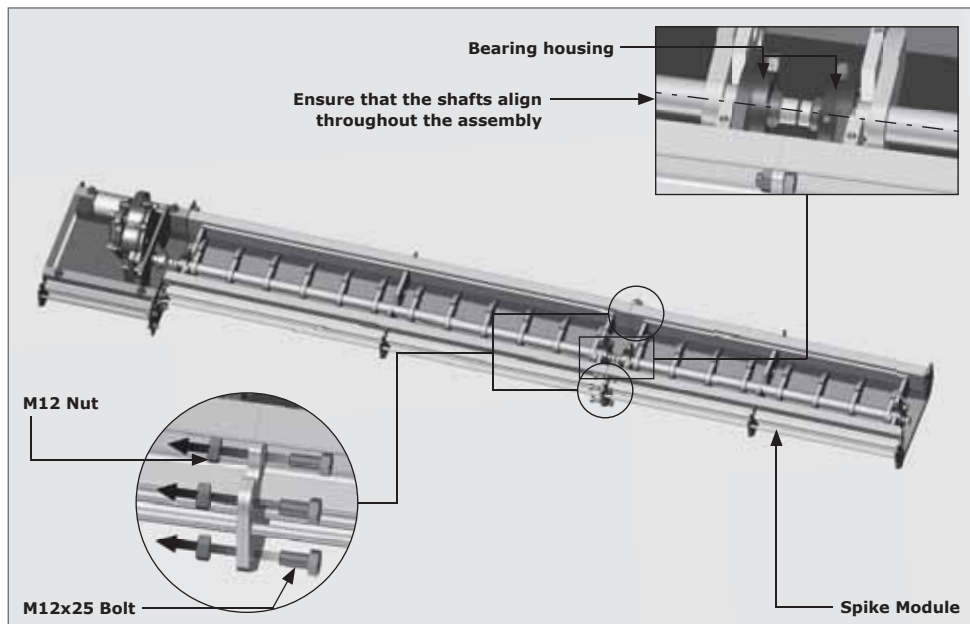
FIGURE 10



Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly.

STEP 3

Using six M12x25 bolts, fix one spike module to another (Section 15, Figure 11).

**FIGURE 11**

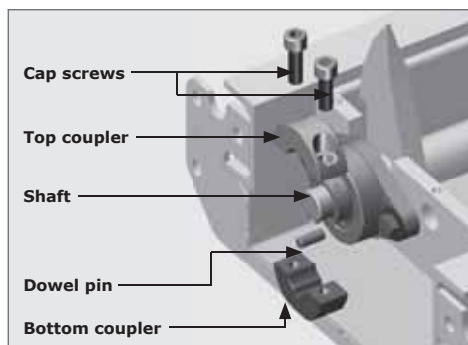
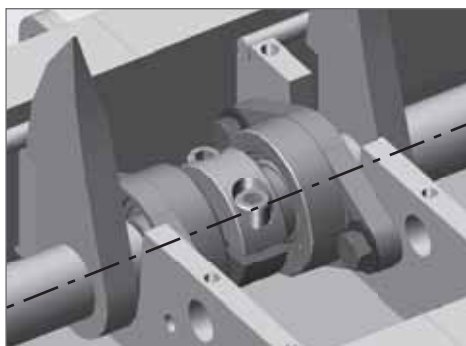
To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

15.2.3. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

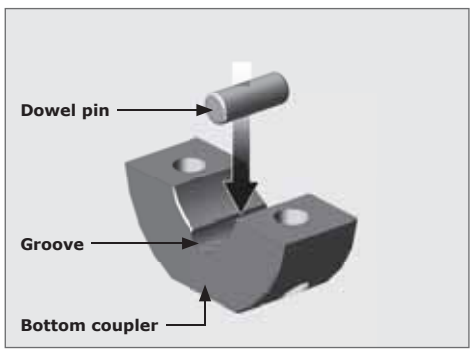


It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.

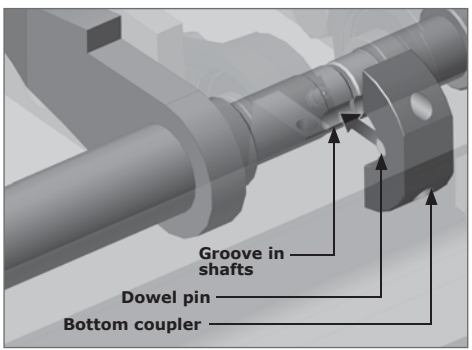
**FIGURE 12. SHAFT COUPLER****FIGURE 13**



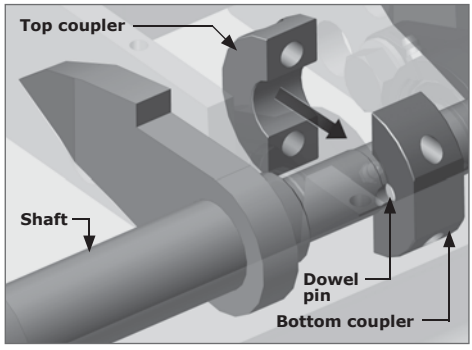
Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.



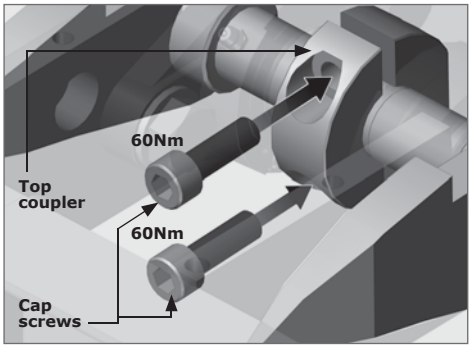
STEP 1 FIGURE 14



STEP 2 FIGURE 15

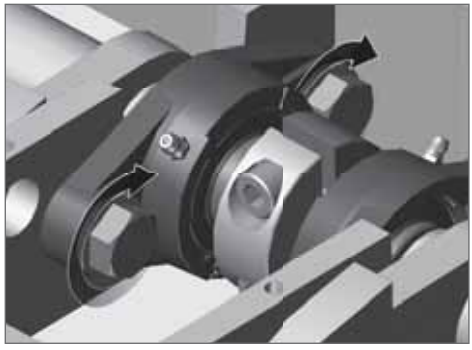


STEP 3 FIGURE 16

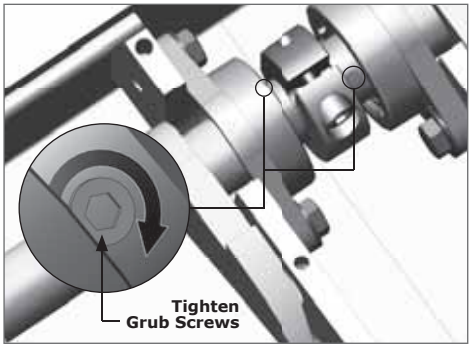


STEP 4 FIGURE 17

STEP 5
Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.



STEP 6 FIGURE 18



STEP 7 FIGURE 19

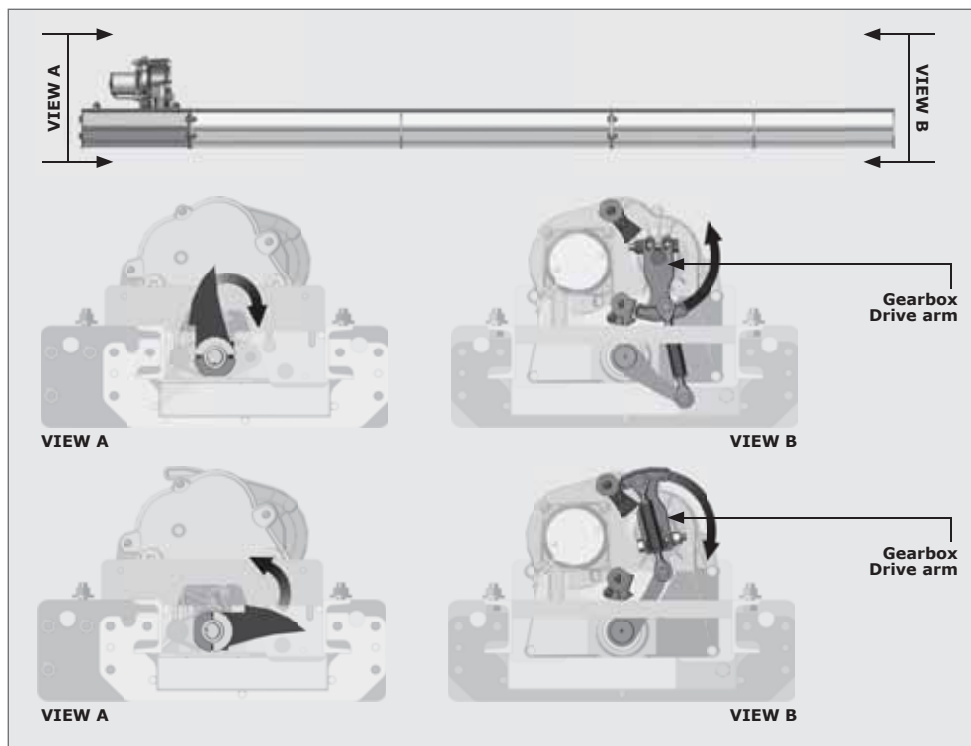
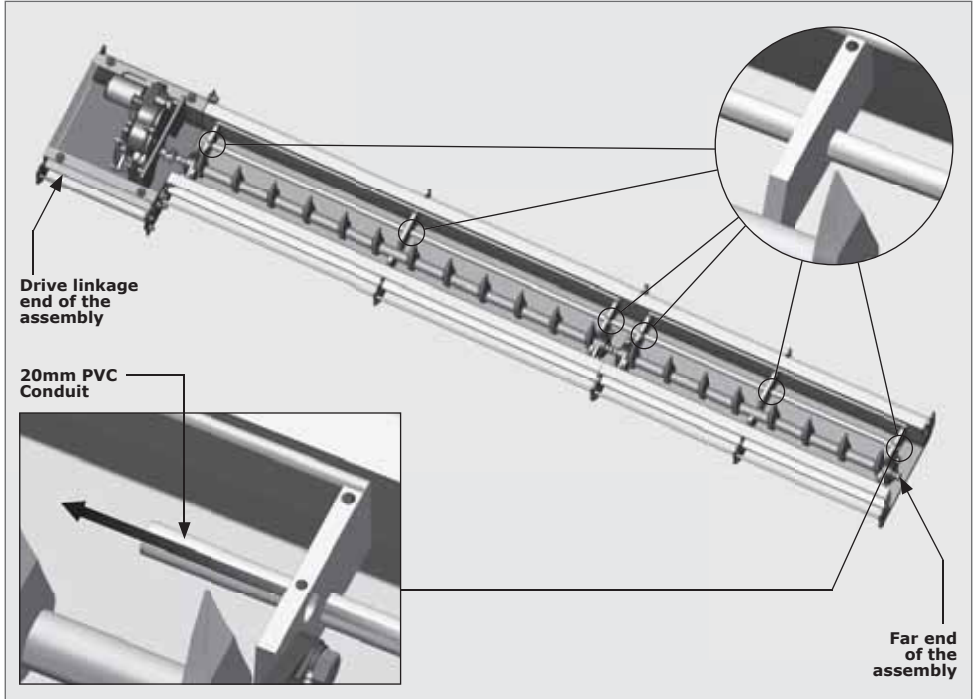


FIGURE 20. CORRECTLY ALIGNED SPIKE AND DRIVE MODULES

STEP 7

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.

15.2.4. Proximity sensor installation



STEP 1

FIGURE 21



The length of the PVC conduit will be relative to the length of the spike modules combined. Ensure that a further 38mm is added to this to account for the modules and coupling (Refer to Section 15, Figure 22).

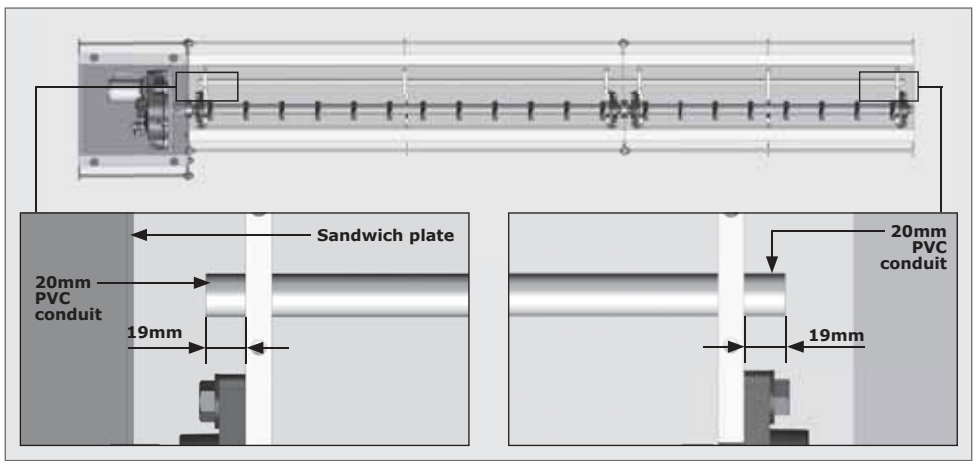
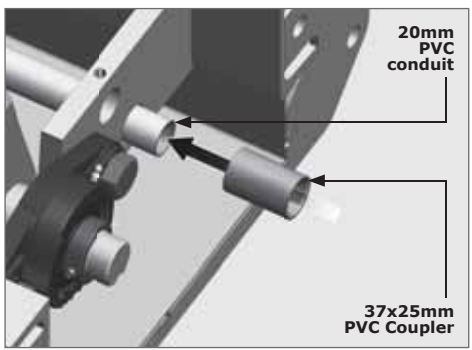


FIGURE 22

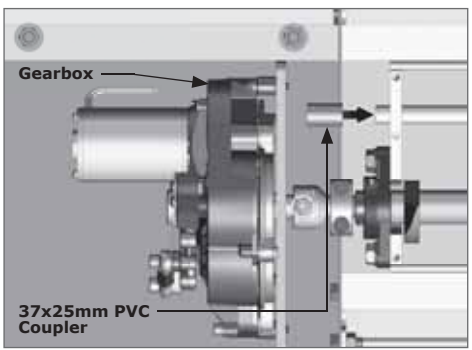


Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.



STEP 2

FIGURE 23

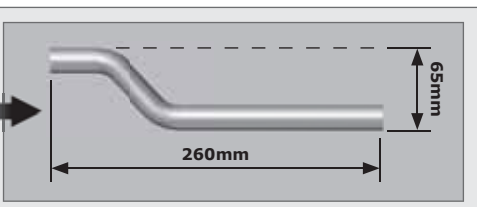
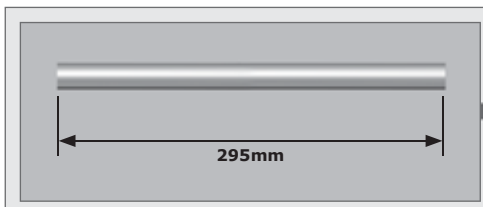


STEP 3

FIGURE 24



It is necessary to bend PVC conduit to circumvent the gearbox bulkhead to continue. The use of a conduit spring is recommended to avoid collapsing the pipe. Section 15, Figure 25 below is a guideline that can be used to achieve this.



STEP 4

FIGURE 25

STEP 5

Connect the bent piece of conduit to the PVC coupler installed in Section 15, Figure 24 Step 3. After it is connected, it should resemble Section 15, Figure 26.

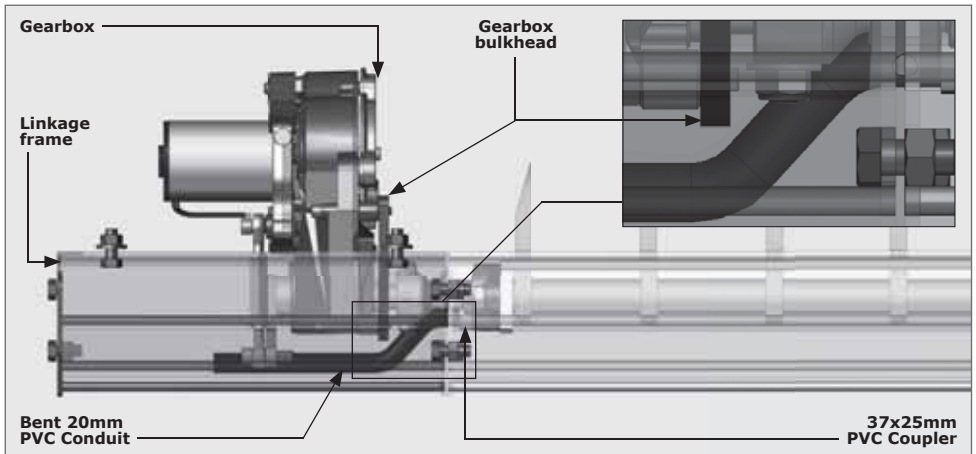
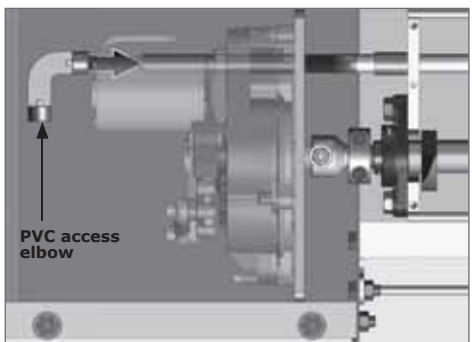


FIGURE 26

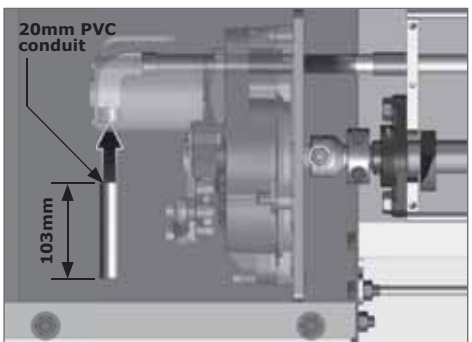


Steps 6-9 is only applicable if the SECTOR II will be mounted directly onto the **CLAWS** Gearbox. If they are going to be mounted separately, a trench for the conduit and cables will need to be dug (Refer to Section 15.5.2.).



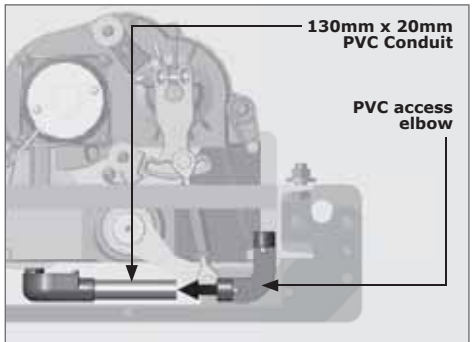
STEP 6

FIGURE 27



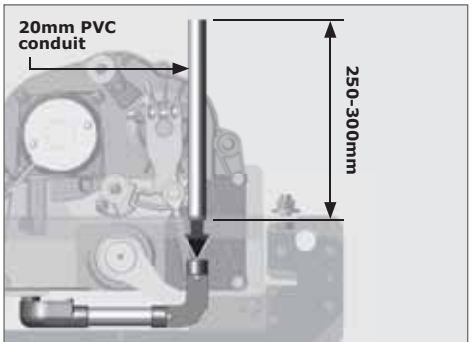
STEP 7

FIGURE 28



STEP 8

FIGURE 29



STEP 9

FIGURE 30



Please ensure that the moving mechanical parts do not rub against the conduit or cables.

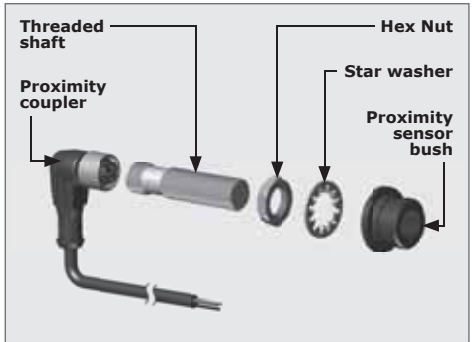


FIGURE 31. PROXIMITY SENSOR

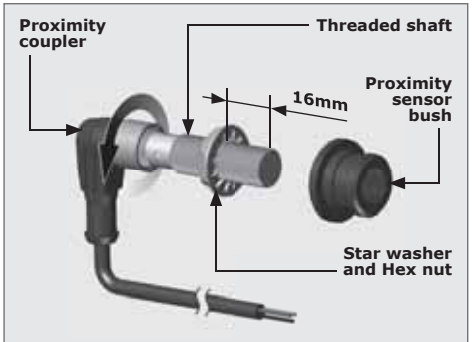


FIGURE 32. PROXIMITY SENSOR

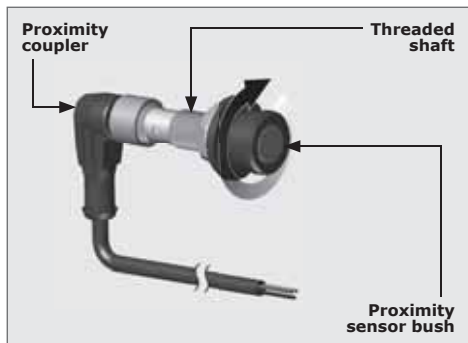
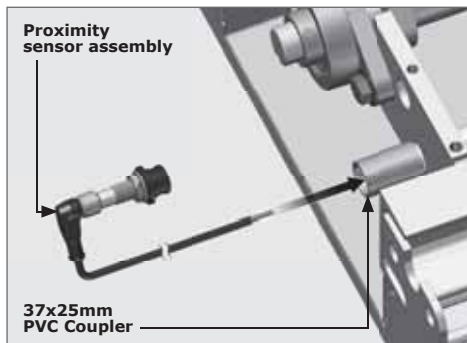


FIGURE 33. PROXIMITY SENSOR



STEP 6

FIGURE 34

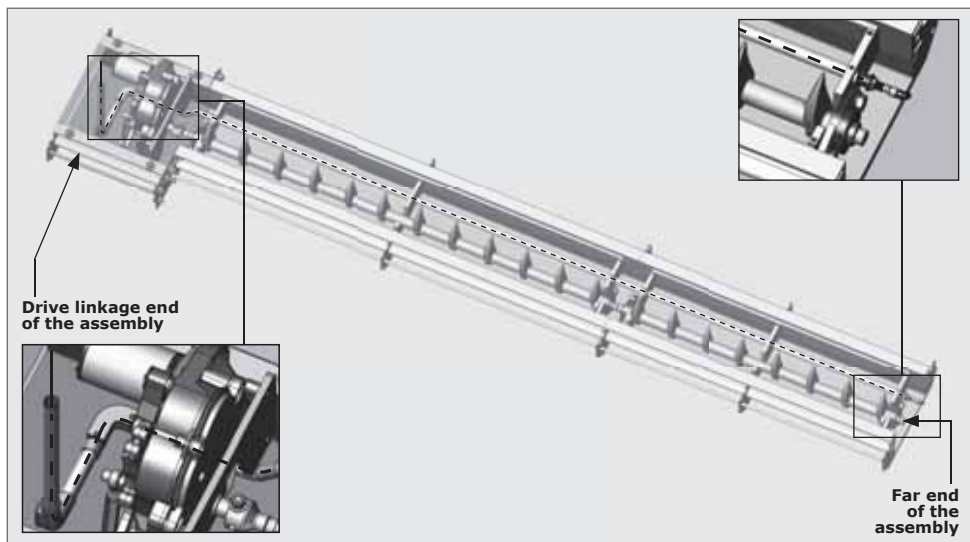
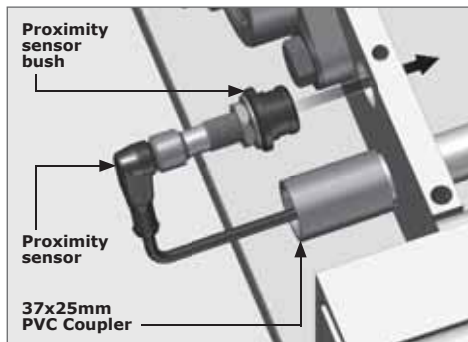


FIGURE 35

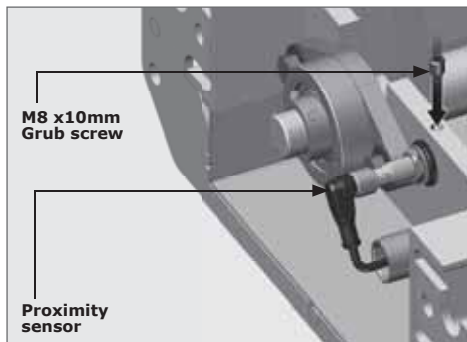


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed up the SECTOR II at a later stage.



STEP 7

FIGURE 36

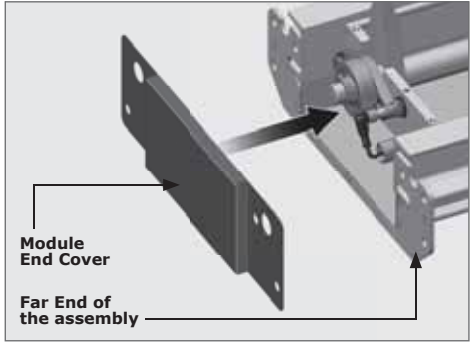


STEP 8

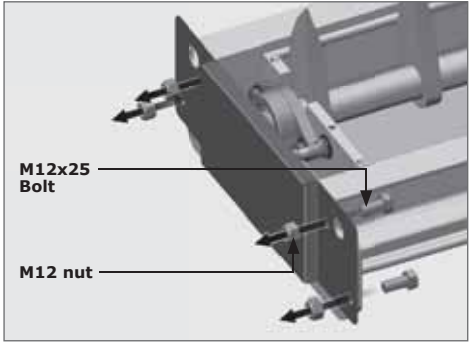
FIGURE 37

15.2.5. Attaching the End Covers to the Assembly

15.2.5.1. Attaching the Module End cover

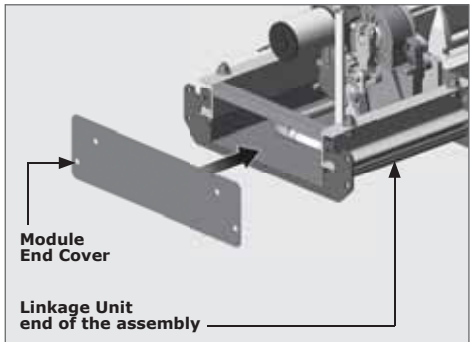


STEP 1 FIGURE 38

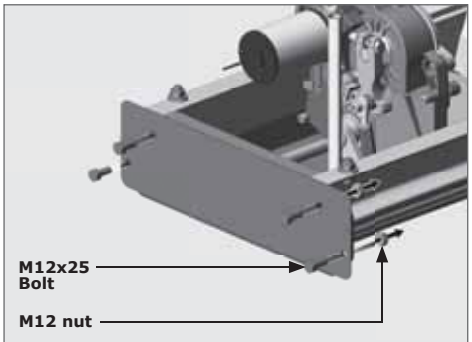


STEP 2 FIGURE 39

15.2.5.2. Attaching the Linkage Unit End cover



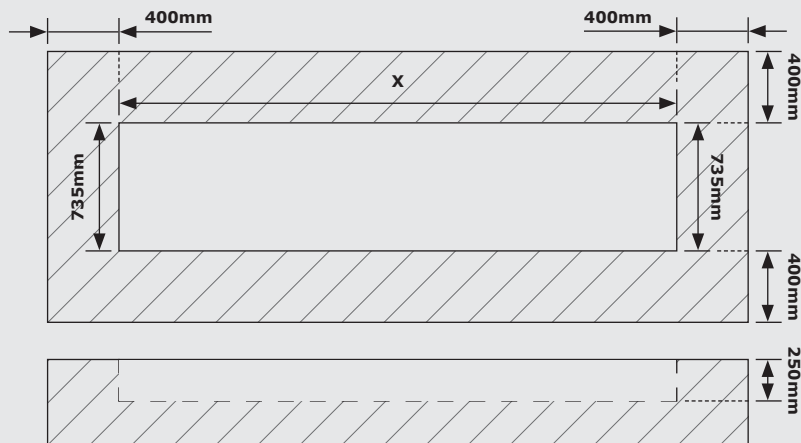
STEP 1 FIGURE 40



STEP 2 FIGURE 41

15.3. Preparing the trench and drainage system

Dig a hole following the dimensions below. Dimension 'X' is relative to the total length of the linkage unit and spike models combined.



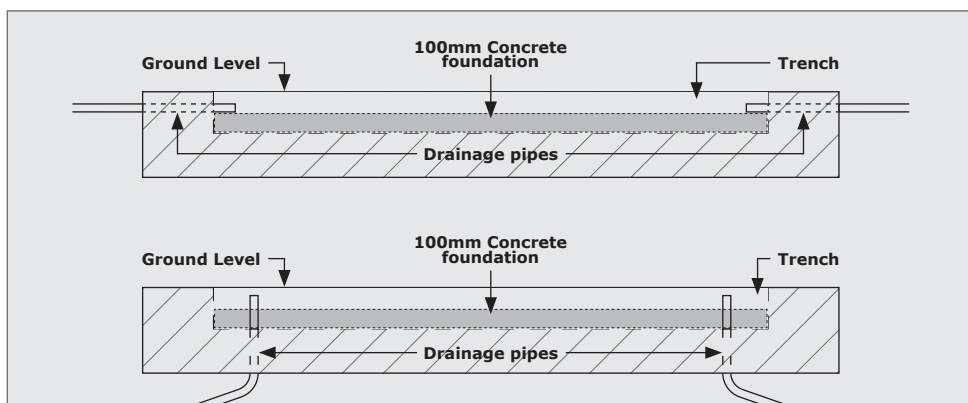
STEP 1

FIGURE 42

Drainage pipes must be laid at one or both ends of the trench to allow water to flow either into storm water drains or into any other area away from the installation. Section 15, Figure 43 shows two recommended drainage configurations. Once complete, hold them in place by pouring a 100mm concrete foundation and level off.



If the SECTOR II and **CLAWS** are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. This must be done before any concrete is poured (Section 15.5.2.).



STEP 2

FIGURE 43



Make sure the drain pipes do not interfere with the structure when it will be placed in the trench.

15.3.1. Concreting the assembly into the trench.

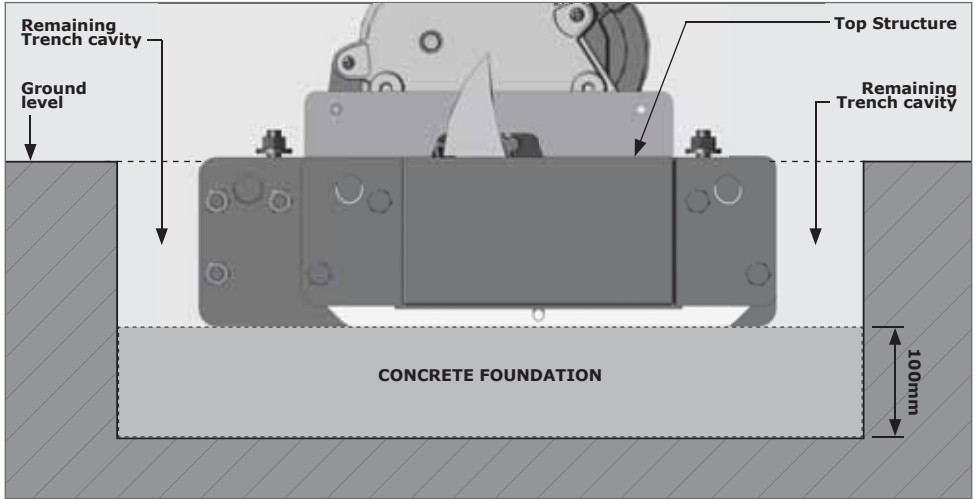


Ensure that the drain pipes will not interfere with the structure when it is placed in the trench.

Place the assembly in the trench and level the assembly using any type of propping or jacking method. Make sure that the top of the assembly is either in line with or a little higher than the ground level and pour concrete (minimum 45MPa after 28 days) into the cavity that remains.



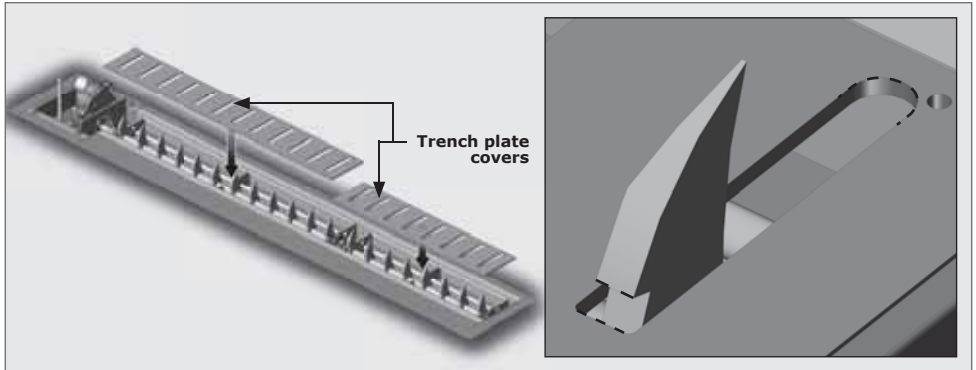
Do not pour any concrete into the gutter of the spikes module or drive link assembly.



STEP 3

FIGURE 44

15.4. Re-assembling the trench plates

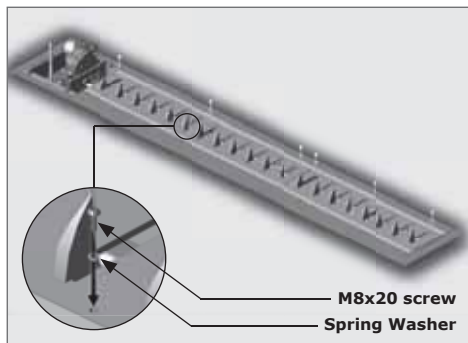


STEP 1

FIGURE 45



Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.



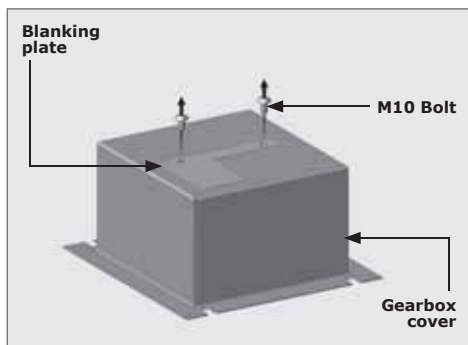
STEP 2

FIGURE 46

15.5. Integrating the SECTOR II with the CLAWS

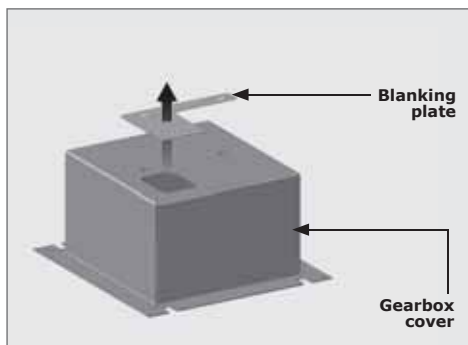
15.5.1. Directly mount THE SECTOR II onto the Independent Drive

15.5.1.1. Placing the gearbox cover into position



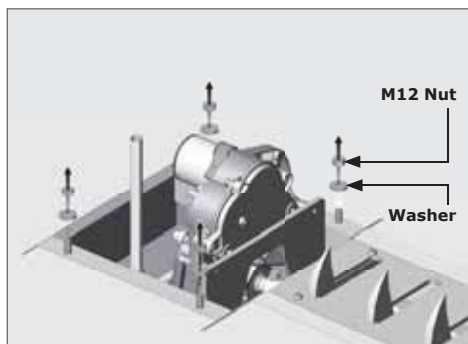
STEP 1

FIGURE 47



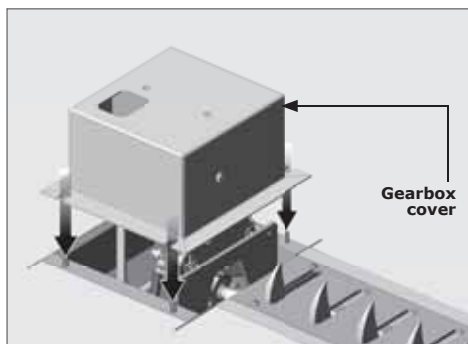
STEP 2

FIGURE 48



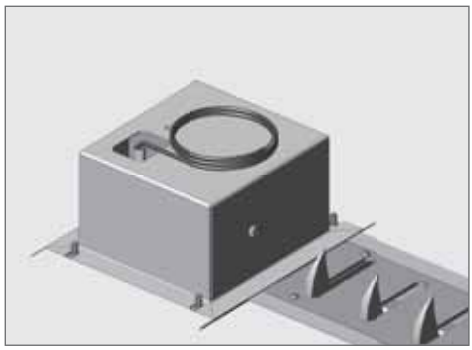
STEP 3

FIGURE 49



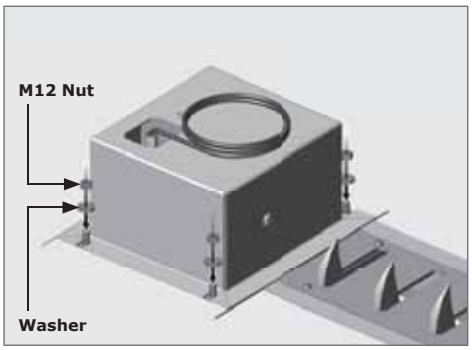
STEP 4

FIGURE 50



STEP 5

FIGURE 51



STEP 6

FIGURE 52

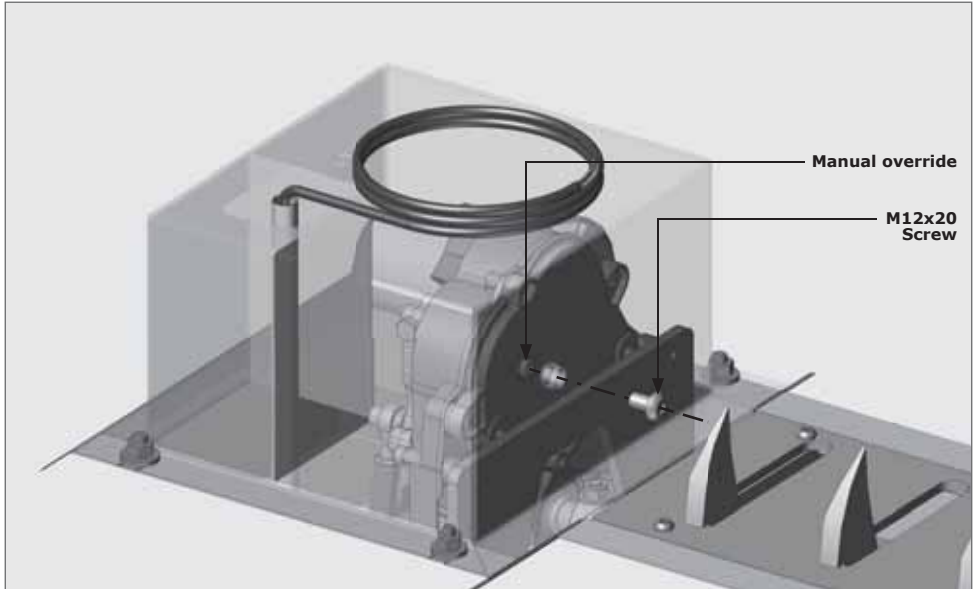
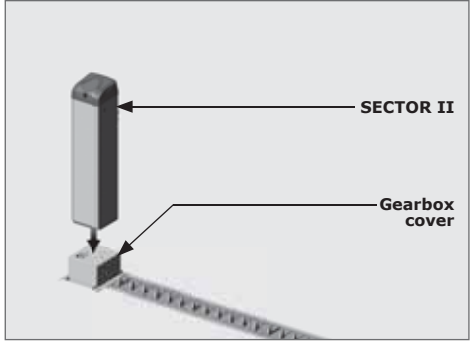


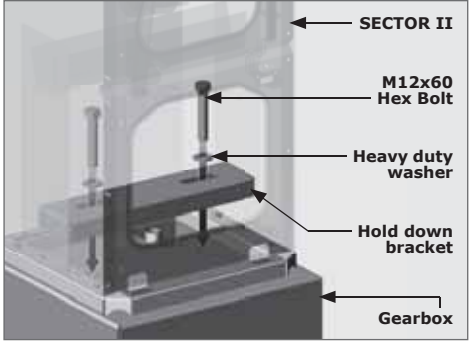
FIGURE 53. MANUAL OVERRIDE

15.5.1.2. Placing the SECTOR II into position



STEP 1

FIGURE 54



STEP 2

FIGURE 55

15.5.2. Separately-placed CLAWS and SECTOR II

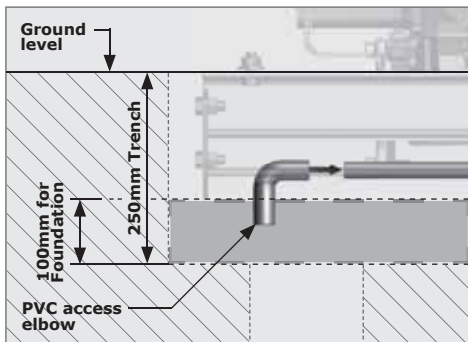
15.5.2.1. Running the conduit from the gearbox to the SECTOR II

STEP 1

Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.

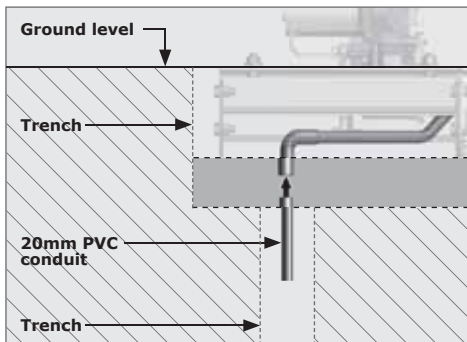


Drill a 20mm hole through the gutter plate using a 20mm hole saw for the proximity sensor conduit



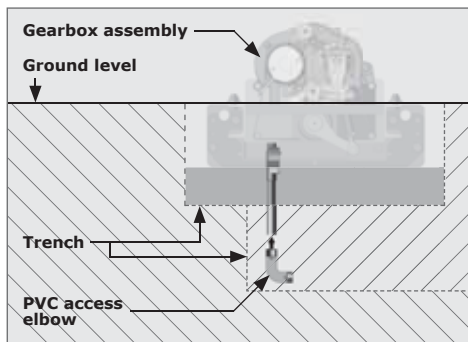
STEP 2

FIGURE 56



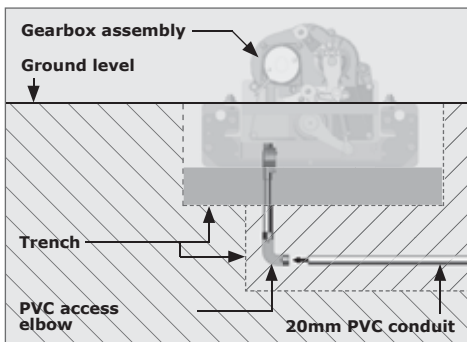
STEP 3

FIGURE 57



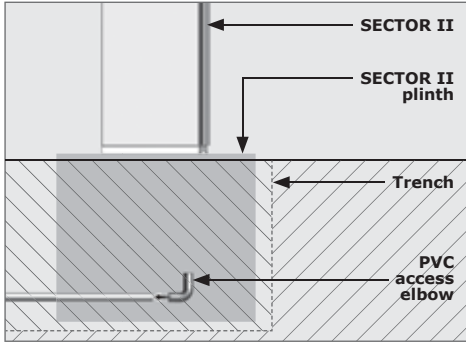
STEP 4

FIGURE 58



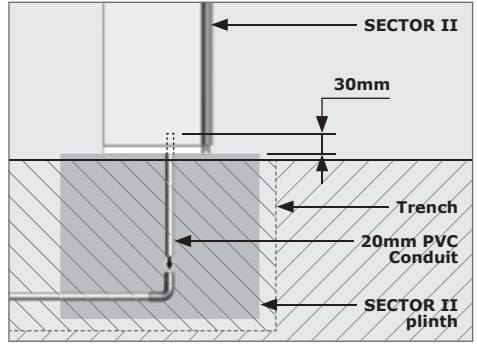
STEP 5

FIGURE 59



STEP 6

FIGURE 60



STEP 7

FIGURE 61

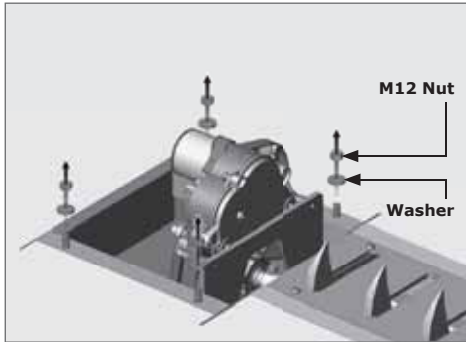
STEP 8

Route the **CLAWS** and Proximity sensor cables in the conduit to the SECTOR II.

STEP 9

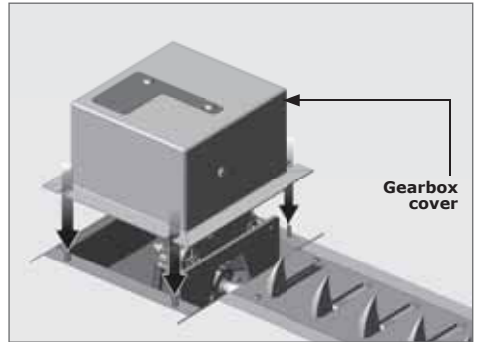
Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

13.5.2.2. Placing the gearbox cover into position



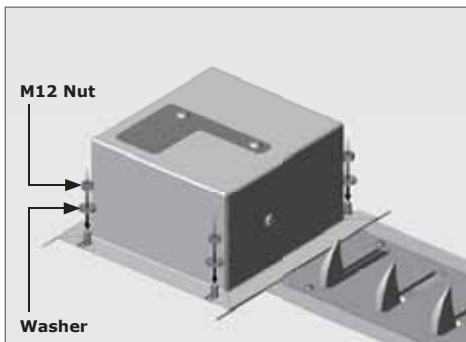
STEP 1

FIGURE 62



STEP 2

FIGURE 63



STEP 3

FIGURE 64

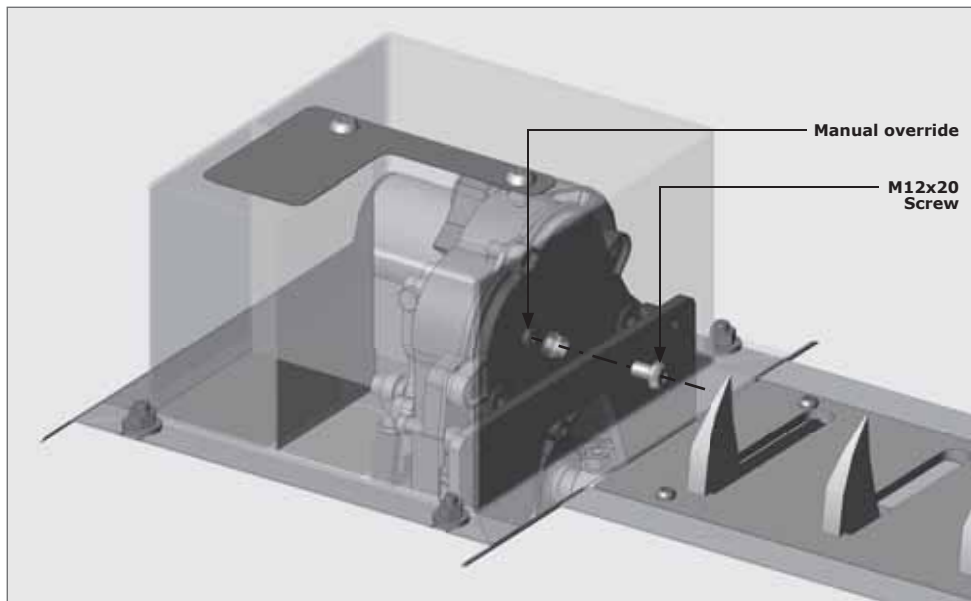
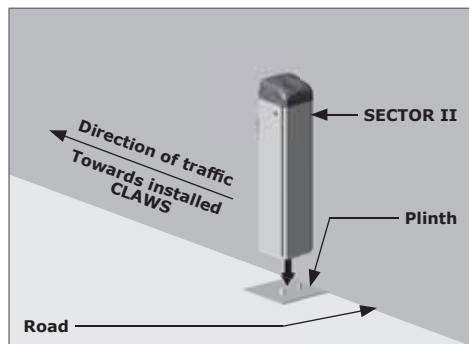


FIGURE 65. MANUAL OVERRIDE



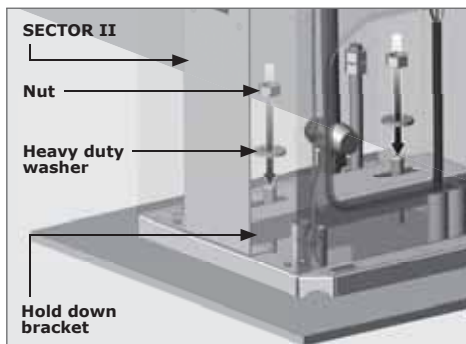
By removing the M12x20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.

15.5.2.3. Placing the SECTOR II into position



STEP 1

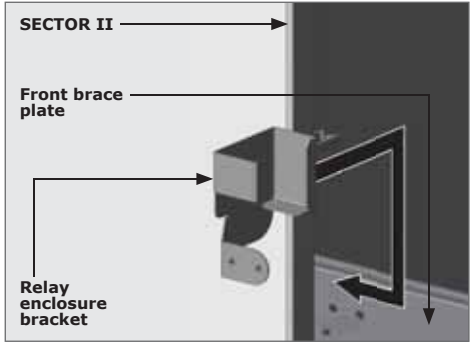
FIGURE 66



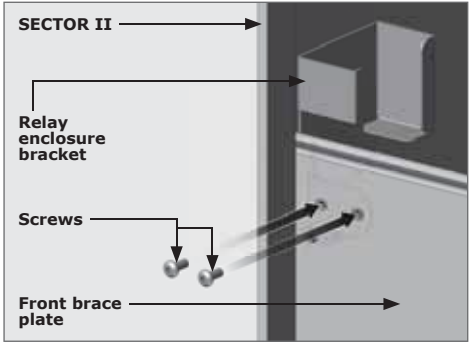
STEP 2

FIGURE 67

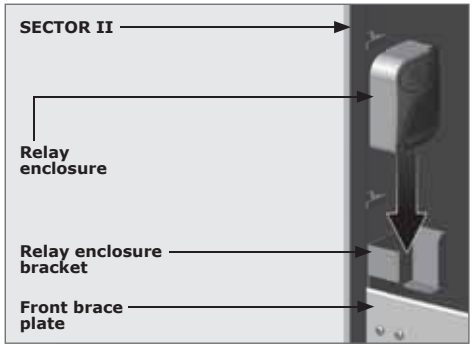
15.5.3. Fitting the relay enclosure and its bracket



STEP 1 FIGURE 68



STEP 2 FIGURE 69



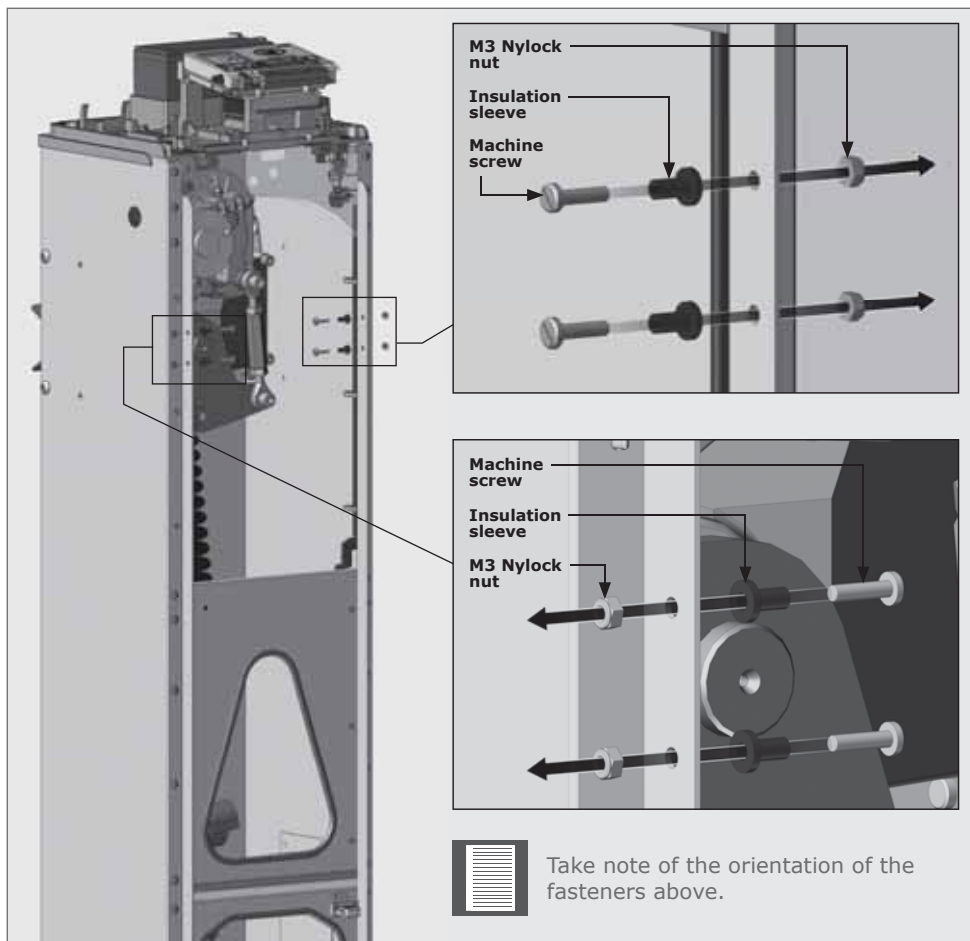
STEP 3 FIGURE 70



Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 16).

Complete the installation of the SECTOR II as per its full installation manual.

15.5.5. Fitting the CLAWS controller to the SECTOR II



STEP 1

FIGURE 71

STEP 2

Keeping the **CLAWS** Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.

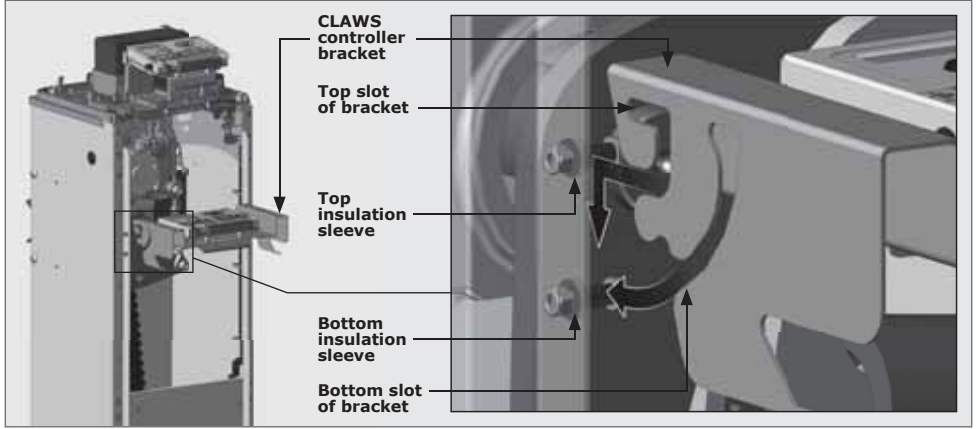


FIGURE 72

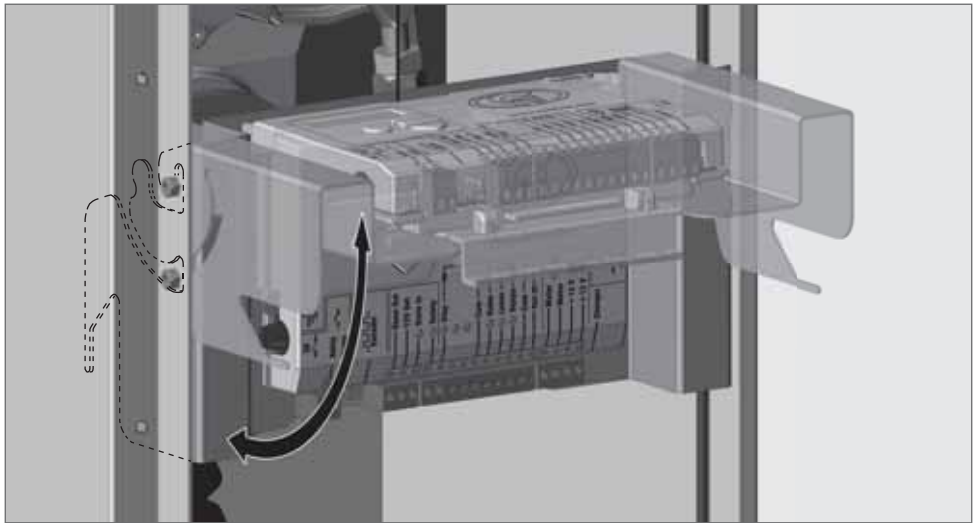


FIGURE 73



The bracket can be moved into a set angle of 70° by pivoting it upward from the bottom for better viewing of the LCD screen (Section 15, Figure 74).

It can also be moved lower down for optimum space when working on the gearbox (Section 15, Figure 75).



Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 15, Figure 72).

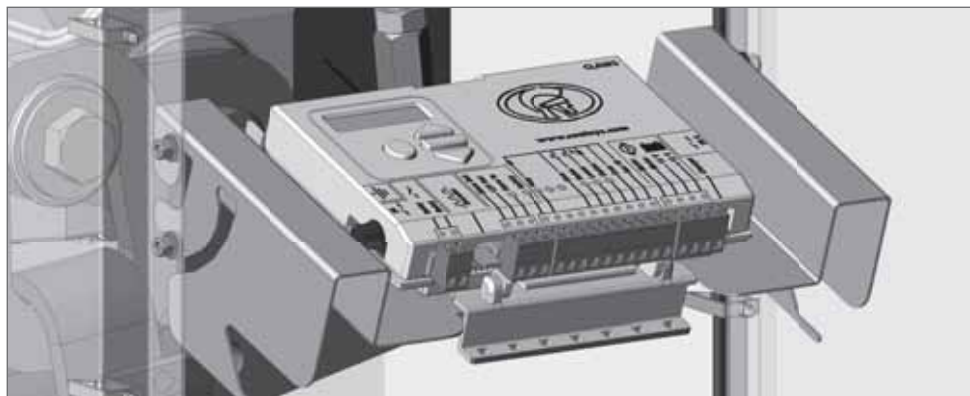


FIGURE 74. CLAWS CONTROLLER AND BRACKET AT FIXED 70° POSITION

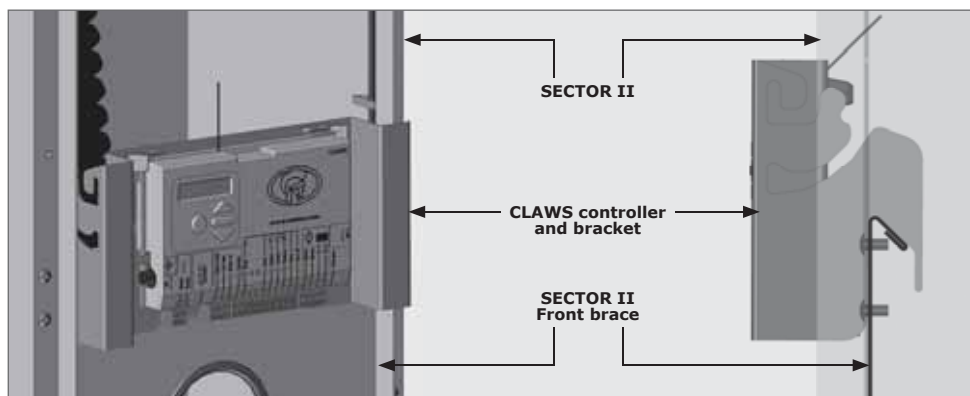


FIGURE 75. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION

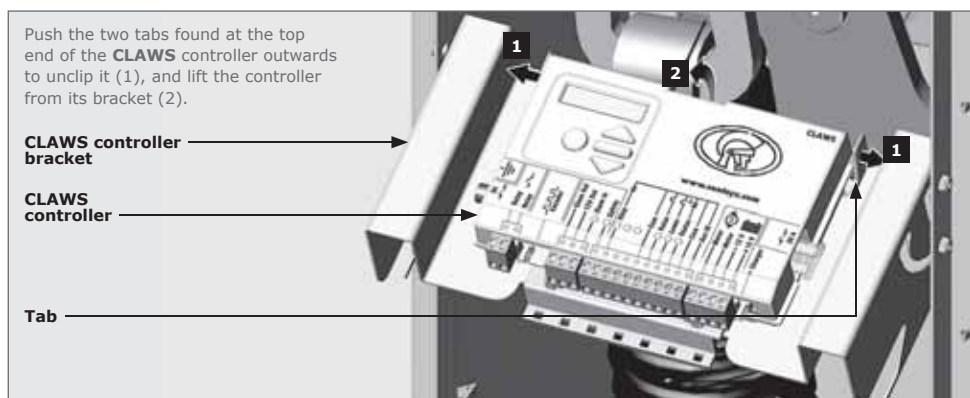


FIGURE 76. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET

STEP 3

Connect harness and power supply. Refer to the wiring diagrams and controller settings.

16. Wiring Diagram

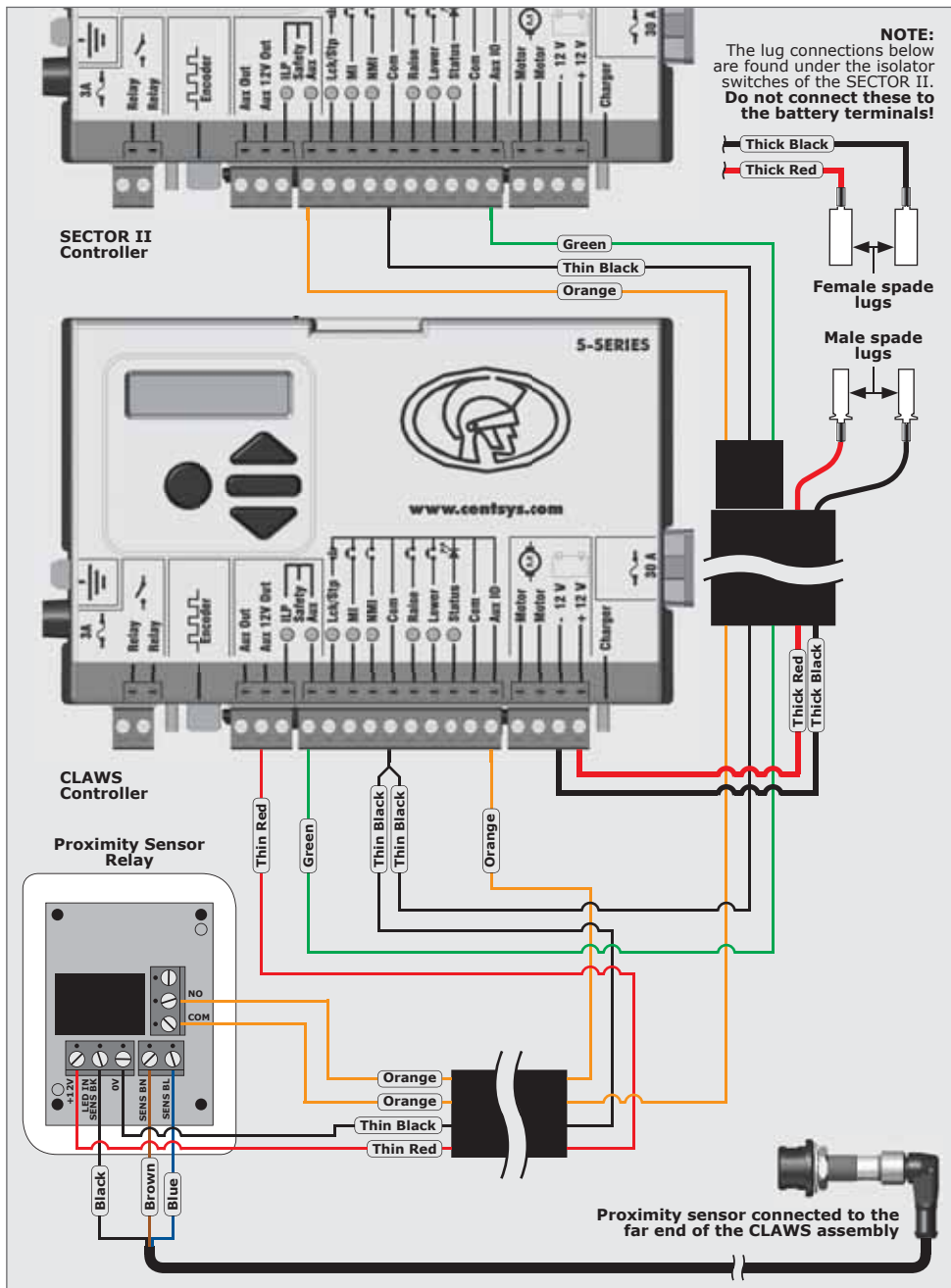


FIGURE 77. CONNECTING THE TWO CONTROLLERS

17. SECTOR II & CLAWS Controller Settings

17.1. SECTOR II Controller settings



4. Modes of Operation

4.1. Operating mode

(Set to any mode applicable, *Simplex (SMX)*, *Complex (CMX)* or *PLC (PLC)*)



11. Spikes Mode

11.1. Spike interface

(Set to any mode applicable, *Safe (SAF)*, or *Secure (SEC)*)

TABLE 1

17.2. CLAWS Controller settings



4. Modes of Operation

4.1. Operating mode

(Set to *Spike Mode (SPK)*)

TABLE 2

18. Installation Handover

Once the installation has been successfully completed and tested, it is important to explain the operation and safety requirements of the system to the end-user.

NEVER ASSUME THE USER KNOWS HOW TO SAFELY OPERATE AUTOMATED ROADWAY SPIKES!

Even if the user has used such a system before, it does not mean he knows how to SAFELY operate it. Make sure that the user fully understands the following safety requirements before finally handing over the site.

The following needs to be understood by the user:

- How to operate the manual override mechanism
(Show them how by demonstration)
- How co-installed safety loops and all other safety features work
(Show them how by demonstration)
- All the features and benefits of the spikes
- **All the safety considerations associated with operating automated roadway spikes.**
The user should be able to pass this knowledge on to all other users of the automated system and must be made aware of this responsibility

- Do not activate the **CLAWS** unless you can see it and can determine that its area of travel is clear of people, pets, or other obstructions
- **NO ONE MAY PASS OVER RAISING SPIKES.** Always keep people and objects away from the spikes
- **NEVER LET CHILDREN OPERATE OR PLAY WITH THE SPIKE CONTROLS,** and do not allow children or pets near the spike area
- Be careful with moving parts and avoid close proximity to areas where fingers or hands could be pinched
- Secure all easily-accessed spike controls in order to prevent its unauthorised use
- Keep the automated spikes system properly maintained, and ensure that all working areas are free of objects that could affect its operation and safety
- On a monthly basis, check the obstruction detection system and safety devices for correct operation
- All repair and service work to this product must be done by a suitably qualified person
- This product was designed and built strictly for the use indicated in this documentation. Any other use, not expressly indicated here, could compromise the good condition/operation of the product and/or be a source of danger!



Neither Centurion Systems (Pty) Ltd, nor its subsidiaries, accepts any liability caused by improper use of the product, or for use other than that for which the automated system was intended.

Ensure that the customer is in possession of the user guide and that you have completed the installation details in the back of the manual.



Connect with us on:

 facebook.com/centurionsystems

 YouTube.com/centurionsystems

 [@askcenturion](https://twitter.com/askcenturion)

Subscribe to the newsletter: www.centsys.com/subscribe

Call Centurion Systems (Pty) Ltd · South Africa
Head Office: +27 11 699 2400

Call Technical Support: +27 11 699 2481
Monday to Friday: from 07h00 to 18h00 (GMT+2)
Saturday: from 08h00 to 16h30 (GMT+2)

E&OE Centurion Systems (Pty) Ltd reserves the right to change any product without prior notice

All product and brand names in this document that are accompanied by the ® symbol are registered trademarks in South Africa and/or other countries, in favour of Centurion Systems (Pty) Ltd, South Africa.

The CENTURION and CENTSYS logos, all product and brand names in this document that are accompanied by the TM symbol are trademarks of Centurion Systems (Pty) Ltd, in South Africa and other territories; all rights are reserved.

We invite you to contact us for further details.



Doc number: 1307.D.01.0005_1
SAP code: DOC1307D05

www.centsys.com