## CLAWS - INDEPENDENT DRIVE INSTALLATION MANUAL



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## Icons used in this manual

?
This icon indicates tips and other information that could be useful during the installation.


This icon denotes variations and other aspects that should be considered during installation.

This icon indicates warning, caution or attention! Please take special note of critical aspects that MUST be adhered to in order to prevent injury.

## IMPORTANT SAFETY INSTRUCTIONS

## ATTENTION

To ensure the safety of people and possessions, it is important that you read all the following instructions.

Incorrect installation or incorrect use of the product may cause serious harm to people and / or property.

The installer, being either professional or DIY, is the last person on the site who can ensure that the operator is safely installed, and that the whole system can be operated safely.

## Warnings for the installer

## CAREFULLY READ AND FOLLOW ALL INSTRUCTIONS before beginning to install the product.

- All installation, repair, and service work to this product must be done by a suitably qualified person
- Do not activate the CLAWS unless you can see them and can determine that the CLAWS are clear of people, pets, vehicles or any obstructions
- Nothing must be placed, and nobody must be near the trench covers at any time. Always keep people and objects away from the spikes' area of travel
- Children should be supervised to ensure that they do not play with or around the spikes and trench cover
- This device is not intended for use by persons (including children) with reduced physical, sensory or mental capabilities, or lack of experience and knowledge, unless they have been given supervision or instruction concerning use of the appliance by a person responsible for their safety
- Secure all easily-accessed CLAWS controls in order to prevent unauthorised use
- Do not in any way modify the components of the automated system
- Do not install the equipment in an explosive atmosphere. The presence of flammable gas or fumes is a serious danger to safety
- Before attempting any work on the system, cut electrical power and disconnect the batteries
- The mains power supply of the automated system must be fitted with an all-pole switch with contact opening distance of 3 mm or greater. Use of a 5 A thermal breaker with all-pole circuit break is recommended
- Make sure that an earth leakage circuit breaker with a threshold of 30 mA is fitted upstream of the system
- Never short-circuit the battery and do not try to recharge the batteries with power supply units other than that supplied with the product, or manufactured by Centurion Systems (Pty) Ltd
- Make sure that the earthing system is correctly constructed, and that all metal parts of the system are suitably earthed
- Safety devices must be fitted to the installation to guard against mechanical movement risks such as crushing, dragging and shearing
- It is recommended that at least one warning indicator light be fitted to every system
- Always fit a warning sign visibly to the inside and outside of the entrance and exit
- The installer must explain and demonstrate the manual operation of the system in case of an emergency, and must hand the User Guide and Safety Instructions over to the end-user
- Explain these safety instructions to all persons authorised to use the system, and be sure that they understand the hazards associated with the system
- Do not leave packing materials (plastic, polystyrene, etc.) within reach of children as such materials are potential sources of danger
- Dispose of all waste products like packaging materials, worn-out batteries, etc. according to local regulations
- Always check the obstruction detection system and safety devices for correct operation
- Neither Centurion Systems (Pty) Ltd, nor its subsidiaries, accepts any liability caused by improper use of the product, or for use other than that for which the automated system was intended
- This product was designed and built strictly for the use indicated in this documentation. Any other use, not expressly indicated here, could compromise the service life/operation of the product and/or be a source of danger
- Everything not expressly specified in these instructions is not permitted


## warnived warniwed warninc! warniwed warniwed



MOVING PARTS CAN CAUSE SERIOUS INJURY, AMPUTATION OR DEATH. KEEP CLEAR! CLAWS SPIKES MAY MOVE AT ANY TIME. DO NOT ALLOW CHILDREN TO PLAY IN AREA OR OPERATE THE SYSTEM.

## ATTENTION

For the detection of vehicles, we recommend installing
Inductive Loop Detectors in preference to infrared beams. When installing the Loop detectors, positioning is very important for the safety of the vehicle

- X refers to the distance required between the loops and CLAWS for free-exit
- Free-exit for uni-directional traffic, X must be greater than 500 mm from the CLAWS
- For bi-directional traffic, X must also be greater than 500 mm from the CLAWS



## 1. General Description

CLAWS barrier spikes are designed to enhance the security at the entrance to highvolume application. They provide a formidable deterrent to would-be criminals and due to their robust construction they are very difficult to defeat.

Clever modular design allows the CLAWS to be ordered ex-stock and can be configured into a variety of different lengths. The orientation of the spikes can also be easily changed depending on the direction of the traffic flow. Their external limit switches allow for safe operation of the system.

CLAWS are easy to install and use a standard SECTOR controller and a standard SECTOR gearbox, saving you time and reducing your spares inventory. They boast all-weather construction and have been designed to allow for all moving parts to be removed easily for quick and easy maintenance.

CLAWS also provide onboard support for a traffic light interface, and the Independent Drive CLAWS models have variable speed control and multiple Modes of Operation. The CLAWS Independent Drive system has its own drive mechanism and controller, and can work independently of traffic barriers, etc. It is available in both Flush Mount and Surface Mount variants.

The Flush Mount models are ideal for installations that require seamless access control for smooth-flowing traffic, whereas the Surface Mount models are mounted above the general surface of the roadway and create a traffic-calming bump for a safer access control point.

## 2. Product Specifications

### 2.1. Technical Specifications

| Input Voltage | 220 V AC +/-10\% @ 50Hz ${ }^{1}$ |
| :---: | :---: |
| Motor Voltage | 12 V DC |
| Current Draw |  |
| Wiring Requirements | Battery-driven ${ }^{2}-2 \mathrm{~A}$ charger |
| Spike Modules - Available lengths | 1 metre and 1.5 metre |
| Spikes raise / lower time | 1.2 sec |
| Daily operations - Max | As per co-installed SECTOR II |
| Daily Operations - Mains present | As per co-installed SECTOR II |
| Anti-corrosion - Main chassis | Hot dip galvanised Mild Steel |
| Spike material | 85 mm Mild Steel, electroplated and powder-coated |
| Maximum allowable axel weight | 4000 kg |
| Onboard receiver specifications | CENTURION code-hopping, multichannel, 433 MHz with 500 remote control button storage capacity |

### 2.2. Product Dimensions

2.2.1. Surface Mount

2.2.2. Flush Mount


## INDEPENDENT DRIVE SURFACE MOUNT INSTALLATIONS

## CㅁWS



## 3. Product Identification



FIGURE 1. PRODUCT IDENTIFICATION

1. Boom pole
2. Spikes module assembly
3. Ramp plates
4. Trench cover plate
5. Spikes
6. Drive linkage assembly
7. SECTOR II

| Module Frame |
| :--- |
| Sinkage Frame |
| Top Coupler |
| Bottom Coupler |
| $8 \times 20$ Dowel Pin Plate |

Drive Linkage Arm
Driven Linkage Arm
Bearing Housing Down Bracket
Binkage End Cover
Blanking Plate
Module End Cover
Gearbox Cover

## 4. Tools Required

- $13 \mathrm{~mm}, 17 \mathrm{~mm}$, and 19 mm Spanners
- Ratchet
- 19 mm , and 24 mm Sockets
- Allen Key Set
- Mallet
- Tape Measure
- Spirit Level
- Torque Wrench


## 5. Introduction

This document describes the basic steps to follow when installing the surface-mountable CLAWS Spikes driven by an independently-powered gearbox. The installation described in this document is a 2.5 meter installation. For other installations, modules of 1.5 or 1.0 meters can be combined to achieve different widths.


The installation of the CLAWS Spikes requires a minimum of two persons.

### 5.1. Installation Configurations

The surface-mountable CLAWS Spikes can be installed in four different configurations. The configuration is dependent on two factors:

- Orientation of installation
- Direction of spike impact


### 5.1.1. Orientation of Installation

The orientation of installation is described as the side at which the drive linkage is installed when approaching the CLAWS Spikes. In other words, when driving up to the CLAWS Spikes, in the correct direction for traffic flow, and the drive is installed on the right-hand side of the vehicle, it's deemed a right-hand installation. And when driving up to the CLAWS Spikes, in the correct direction for traffic flow, and the drive is installed on the left-hand side of the vehicle, it's deemed a left-hand installation.


FIGURE 2. RHS CONFIGURATION


FIGURE 3. LHS CONFIGURATION

### 5.1.2. Spike Impact Direction

The CLAWS Spikes are designed to take a much larger impact in one direction. Thus, the CLAWS Spikes can be installed to take larger or more frequent impact in one direction. In other words, the spikes can be installed to face either towards oncoming traffic (similar) or face towards traffic (opposing) trying to enter from the wrong direction or lane (Section 3, Figure 1).


FIGURE 4. SPIKE IMPACT DIRECTION - SIMILAR


FIGURE 5. SPIKE IMPACT DIRECTION - OPPOSING
There are four types of typical installations. Refer to Section 5, Figures 2 and 3 to determine if the installation is left- or right-hand orientated.
Secondly; pay attention to the spike impact direction:

- Similar direction of travel prevents vehicles from exiting whilst the boom pole is still down (Normal direction of traffic)
- Opposing direction of travel prevents vehicles entering against the flow of traffic whilst the boom pole is down



FIGURE 7. RHS OPPOSED DIRECTION OF TRAVEL


FIGURE 8. LHS SIMILAR DIRECTION OF TRAVEL


FIGURE 9. LHS OPPOSED DIRECTION OF TRAVEL

## 6. RHS Surface Mount - Similar Direction of Travel

### 6.1. Preparing the Drive Linkage Assembly




STEP 7
FIGURE 16


STEP 8
FIGURE 17

ㅁ
The drive linkage arm should point to a 5 o'clock position and the holes of the gearbox shaft and the linkage arm must line up as shown above.


STEP 9
FIGURE 18


FIGURE 19


Tighten the Countersunk M8x40 screw to 20Nm (Section 6, Figure 18).

### 6.2. Spike Module Assembly

6.2.1. Preparing the Spike Model assembly(ies) for installation


STEP 1


STEP 2


STEP 3
FIGURE 22


STEP 4
FIGURE 23

### 6.2.2. Attaching the Driven Link to the first spike module

[
Place the spikes into the down position to aid in the fitment of all the shaft couplings.


STEP 1
FIGURE 24


STEP 2
FIGURE 25
$\square$ Ensure the Driven Link and the spikes are pointing in the same direction. (Section 6, Figures 25 to 28).


STEP 3


STEP 4


FIGURE 28
6.2.3. Aligning the Driven Linkage Arm to the Drive Linkage Arm.

6.2.4. Attaching the drive linkage assembly to the spike module

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the

ㅁspike module assembly. Ensure that the Sandwich Plate is lifted over the Driven Linkage Arm, so that the Driven Linkage Arm sits flush with the Drive Linkage Arm (Section 6, Figure 30).


STEP 1
FIGURE 30


STEP 2


STEP 3

FIGURE 32

Using six M12x25 bolts, fix one spike module to another (Section 6, Figure 33).


D
To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

### 6.2.5. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

ㅁIt is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.


FIGURE 34. SHAFT COUPLER


FIGURE 35

a
Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.


STEP 1
FIGURE 36


STEP 3


STEP 2
FIGURE 37


STEP 4
FIGURE 39

## STEP 5

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they rotate freely.


### 6.2.6. Bolting down the assembly to the ground

If the SECTOR II and CLAWS are to be seperated, a trench for the conduit and
 cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. (Section 6.4.2.) These must be done before bolting the assembly to the ground. Once this preparation work has been completed, proceed with the installation below.


FIGURE 42

1
It is crucial that the surface it's mounted on is a reasonably even surface as an uneven surface could result in an uneven binding of the spike shafts. This will result in premature failure.

### 6.2.7. Proximity sensor installation



STEP 1
FIGURE 43


The length of the PVC conduit will be relative to the length of the spike modules and drive linkage unit combined. Ensure that a further 38 mm is added to this to account for the modules and coupling (Refer to Section 6, Figure 44).


Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.


STEP 2


STEP 3

FIGURE 46

日
Steps 4-7 is only applicable if the SECTOR II will be mounted directly onto the CLAWS Gearbox. If they are going to be mounted seperately, a trench for the conduit and proximity sensor cable will need to be dug (Section 6.4.2.).


STEP 4


STEP 6
FIGURE 47

Please ensure that the moving mechanical parts do not rub against the conduit or cables.


FIGURE 51. PROXIMITY SENSOR


FIGURE 53. PROXIMITY SENSOR


FIGURE 52. PROXIMITY SENSOR


STEP 8
FIGURE 54


FIGURE 55
There should be ample cable left over on the drive linkage end, as the wiring will need to be routed to the SECTOR II at a later stage.


STEP 9


STEP 10
FIGURE 57

### 6.3. Re-assembling the ramp plates and linkage cover



STEP 1


STEP 2
FIGURE 59

ㅁ
Leave out the four M8 screws and Spring Washers on the far end of the assembly as the module end cover will be assembled later.


STEP 3
FIGURE 60


Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.


### 6.4. Integrating the SECTOR II with the CLAWS

6.4.1. Directly mount THE SECTOR II onto the Independent Drive

### 6.4.1.1. Placing the gearbox cover into position



STEP 1


STEP 3
FIGURE 68


STEP 5
FIGURE 66

FIGURE 70


STEP 2
FIGURE 67



FIGURE 72. MANUAL OVERRIDE

### 6.4.1.2. Placing the SECTOR II into position



STEP 1


STEP 2

FIGURE 74

### 6.4.2. Seperately-placed CLAWS and SECTOR II

### 6.4.2.1. Running the conduit from the gearbox to the SECTOR II

STEP 1
Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.


STEP 2


STEP 3


STEP 4

STEP 6
FIGURE 77



STEP 5
FIGURE 78


STEP 7

FIGURE 80

## STEP 8

Route the CLAWS and Proximity sensor cables in the conduit to the SECTOR II.

## STEP 9

Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

### 6.4.2.2. Placing the gearbox cover into position



STEP 1


STEP 2
FIGURE 82


STEP 3


FIGURE 84. MANUAL OVERRIDE


By removing the $\mathrm{M} 12 \times 20$ screw and placing an allen key through the hole, the gearbox release screw can be loosened.

### 6.4.2.3. Placing the SECTOR II into position



STEP 1


STEP 2
FIGURE 86

### 6.4.3. Fitting the relay enclosure and its bracket



STEP 1


STEP 2


## $\square$

Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 17).

Complete the installation of the SECTOR II as per its full installation manual.
6.4.5. Fitting the CLAWS controller to the SECTOR II


STEP 1

STEP 2
Keeping the CLAWS Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.


FIGURE 91


FIGURE 92
The bracket can be moved into a set angle of $70^{\circ}$ by pivoting it upward from the bottom for better viewing of the LCD screen (Section 6, Figure 93).

It can also be moved lower down for optimum space when working on the gearbox (Section 6, Figure 94).

Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 6, Figure 91).


FIGURE 93. CLAWS CONTROLLER AND BRACKET AT FIXED $70^{\circ}$ POSITION


FIGURE 94. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION


FIGURE 95. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET
STEP 3
Connect harness and power supply. Refer to the wiring diagrams and controller settings.

## 7. RHS Surface Mount - Opposing Direction of Travel

### 7.1. Preparing the Drive Linkage Assembly



STEP 1
FIGURE 1


STEP 3
FIGURE 3


STEP 5
FIGURE 5


STEP 2
FIGURE 2


STEP 4
FIGURE 4


STEP 6
FIGURE 6


STEP 7
FIGURE 7


STEP 8

FIGURE 8

■
The drive linkage arm should point to a 7 o'clock position and the holes of the gearbox shaft and the linkage arm must line up as shown above.


STEP 9
FIGURE 9


FIGURE 10


Tighten the Countersunk M8x40 screw to 20Nm (Section 7, Figure 9).

### 7.2. Spike Module Assembly

7.2.1. Preparing the Spike Model assembly(ies) for installation


STEP 1


STEP 2
FIGURE 12


STEP 3
FIGURE 13


STEP 4
FIGURE 14

### 7.2.2. Attaching the Driven Link to the first spike module

A
Place the spikes into the down position to aid in the fitment of all the shaft couplings.


STEP 1
FIGURE 15


STEP 2

FIGURE 16

ㅁ
Ensure the Driven Link and the spikes are pointing in the same direction. (Section 7, Figures 16 to 19).


STEP 3

FIGURE 17


STEP 4


FIGURE 19
7.2.3. Aligning the Driven Linkage Arm to the Drive Linkage Arm.


### 7.2.4. Attaching the drive linkage assembly to the spike module

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the

ㅁspike module assembly. Ensure that the Sandwich Plate is lifted over the Driven Linkage Arm, so that the Driven Linkage Arm sits flush with the Drive Linkage Arm (Section 7, Figure 21).


STEP 1
FIGURE 21


STEP 3

Using six M12x25 bolts, fix one spike module to another (Section 7, Figure 24).


STEP 4
FIGURE 24

D
To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

### 7.2.5. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

ㅁ
It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.


FIGURE 25. SHAFT COUPLER


FIGURE 26

a
Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.


STEP 1
FIGURE 27


STEP 3


STEP 2
FIGURE 28


STEP 4
FIGURE 30

## STEP 5

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.


### 7.2.6. Bolting down the assembly to the ground

If the SECTOR II and CLAWS are to be seperated, a trench for the conduit and
 cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. (Section 7.4.2.) These must be done before bolting the assembly to the ground. Once this preparation work has been completed, proceed with the installation below.


FIGURE 33

!
It is crucial that the surface it's mounted on is a reasonably even surface as an uneven surface could result in an uneven binding of the spike shafts. This will result in premature failure.

### 7.2.7. Proximity sensor installation



STEP 1
FIGURE 34

ㅁThe length of the PVC conduit will be relative to the length of the spike modules and drive linkage unit combined. Ensure that a further 38 mm is added to this to account for the modules and coupling (Refer to Section 7, Figure 35).


I
Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.


STEP 2
FIGURE 36


STEP 3

FIGURE 37

■
Steps 4-5 is only applicable if the SECTOR II will be mounted directly onto the CLAWS Gearbox. If they are going to be mounted seperately, a trench for the conduit and proximity sensor cable will need to be dug (Section 7.4.2.).


STEP 4
FIGURE 38


STEP 5
FIGURE 39

$\square$
Please ensure that the moving mechanical parts do not rub against the conduit or cables.


FIGURE 40. PROXIMITY SENSOR


FIGURE 41. PROXIMITY SENSOR


FIGURE 42. PROXIMITY SENSOR


STEP 8
FIGURE 43


FIGURE 44
There should be ample cable left over on the drive linkage end, as the wiring will need to be routed to the SECTOR II at a later stage.


STEP 9


STEP 10

### 7.3. Re-assembling the ramp plates and linkage cover



STEP 1


STEP 2
FIGURE 48

ㅁ
Leave out the four M8 screws and Spring Washers on the far end of the assembly as the module end cover will be assembled later.


STEP 3
FIGURE 49


Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.


STEP 4


STEP 6


STEP 8
FIGURE 54


FIGURE 51


STEP 7
FIGURE 53

### 7.4. Integrating the SECTOR II with the CLAWS

### 7.4.1. Directly mount the SECTOR II onto the Independent Drive

### 7.4.1.1. Placing the gearbox cover into position



STEP 1
FIGURE 55


STEP 3
FIGURE 57


STEP 5

FIGURE 59


STEP 2
FIGURE 56


STEP 4
FIGURE 58



FIGURE 61. MANUAL OVERRIDE

### 7.4.1.2. Placing the SECTOR II into position



### 7.4.2. Seperately-placed CLAWS and SECTOR II

### 7.4.2.1. Running the conduit from the gearbox to the SECTOR II

STEP 1
Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.


STEP 2

FIGURE 64


STEP 3


STEP 4
FIGURE 66


STEP 6


STEP 5
FIGURE 67


STEP 7

FIGURE 69

## STEP 8

Route the CLAWS and Proximity sensor cables in the conduit to the SECTOR II.

## STEP 9

Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

### 7.4.2.2. Placing the gearbox cover into position



STEP 1


STEP 2

FIGURE 71


STEP 3


FIGURE 73. MANUAL OVERRIDE
$\square$ By removing the $\mathrm{M} 12 \times 20$ screw and placing an allen key through the hole, the gearbox release screw can be loosened.

### 7.4.2.3. Placing the SECTOR II into position



STEP 1


STEP 2
FIGURE 75

### 7.4.3. Fitting the relay enclosure and its bracket



STEP 1


STEP 2
FIGURE 77


Route the excess wire from the proximity sensor, and wire it
 to the relay by referring to the wiring diagram (Section 17).

Complete the installation of the SECTOR II as per its full installation manual.
7.4.5. Fitting the CLAWS controller to the SECTOR II


STEP 1

## STEP 2

Keeping the CLAWS Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.


FIGURE 80


FIGURE 81
The bracket can be moved into a set angle of $70^{\circ}$ by pivoting it upward from the
 bottom for better viewing of the LCD screen (Section 7, Figure 82).

It can also be moved lower down for optimum space when working on the gearbox (Section 7, Figure 83).

Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 7, Figure 80).


FIGURE 82. CLAWS CONTROLLER AND BRACKET AT FIXED $70^{\circ}$ POSITION


FIGURE 83. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION


FIGURE 84. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET
STEP 3
Connect harness and power supply. Refer to the wiring diagrams and controller settings.

## 8. LHS Surface Mount - Similar Direction of Travel

### 8.1. Preparing the Drive Linkage Assembly



STEP 1


STEP 3
FIGURE 3


STEP 5


STEP 2
FIGURE 2


STEP 4
FIGURE 4


STEP 6
FIGURE 6


STEP 7
FIGURE 7


STEP 8
FIGURE 8
$\square$ The drive linkage arm should point to a 7 o'clock position and the holes of the gearbox shaft and the linkage arm must line up as shown above.


STEP 9
FIGURE 9



Tighten the Countersunk M8x40 screw to 20Nm (Section 8, Figure 9).

### 8.2. Spike Module Assembly

8.2.1. Preparing the Spike Model assembly(ies) for installation


STEP 1


STEP 3
FIGURE 13


STEP 4

### 8.2.2. Attaching the Driven Link to the first spike module

B
Place the spikes into the down position to aid in the fitment of all the shaft couplings.


STEP 1
FIGURE 15


STEP 2
FIGURE 16
$\square$ Ensure the Driven Link and the spikes are pointing in the same direction. (Section 8, Figures 16 to 19).


STEP 3

FIGURE 17


STEP 4


FIGURE 19
8.2.3. Aligning the Driven Linkage Arm to the Drive Linkage Arm.

8.2.4. Attaching the drive linkage assembly to the spike module

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly. Ensure that the Sandwich Plate is lifted over the Driven Linkage Arm, so that the Driven Linkage Arm sits flush with the Drive Linkage Arm (Section 8, Figure 21).


STEP 1


STEP 2

FIGURE 22


STEP 3
FIGURE 23

Using six M12x25 bolts, fix one spike module to another (Section 8, Figure 24).


STEP 4
FIGURE 24

S
To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

### 8.2.5. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

ㅁIt is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.


FIGURE 25. SHAFT COUPLER


FIGURE 26

a
Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.


STEP 1
FIGURE 27



STEP 2
FIGURE 28


STEP 4
FIGURE 30

## STEP 5

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.


### 8.2.6. Bolting down the assembly to the ground

If the SECTOR II and CLAWS are to be seperated, a trench for the conduit and
 cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. (Section 8.4.2.) These must be done before bolting the assembly to the ground. Once this preparation work has been completed, proceed with the installation below.


FIGURE 33


It is crucial that the surface it's mounted on is a reasonably even surface as an uneven surface could result in an uneven binding of the spike shafts. This will result in premature failure.

### 8.2.7. Proximity sensor installation



STEP 1
FIGURE 34

目The length of the PVC conduit will be relative to the length of the spike modules and drive linkage unit combined. Ensure that a further 38 mm is added to this to account for the modules and coupling (Refer to Section 8, Figure 35).


FIGURE 35

Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.


STEP 2
FIGURE 36


STEP 3


Steps 4-7 is only applicable if the SECTOR II will be mounted directly onto the CLAWS Gearbox. If they are going to be mounted seperately, a trench for the conduit and proximity sensor cable will need to be dug (Section 8.4.2.).


STEP 4


STEP 5
FIGURE 39

ㅁ
Please ensure that the moving mechanical parts do not rub against the conduit or cables.


FIGURE 40. PROXIMITY SENSOR


FIGURE 41. PROXIMITY SENSOR


FIGURE 42. PROXIMITY SENSOR


STEP 8
FIGURE 43


FIGURE 44
There should be ample cable left over on the drive linkage end, as the wiring will need to be routed to the SECTOR II at a later stage.


FIGURE 48

### 8.3. Re-assembling the ramp plates and linkage cover



STEP 1

FIGURE 49


STEP 2
FIGURE 50

ㅁ
Leave out the four M8 screws and Spring Washers on the far end of the assembly as the module end cover will be assembled later.


STEP 3
FIGURE 51


Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.


STEP 4
FIGURE 52


STEP 6


FIGURE 56


STEP 5
FIGURE 53


STEP 7
FIGURE 55

### 8.4. Integrating the SECTOR II with the CLAWS

8.4.1. Directly mount THE SECTOR II onto the Independent Drive

### 8.4.1.1. Placing the gearbox cover into position



STEP 1


STEP 3
FIGURE 59


STEP 5

FIGURE 61


STEP 2
FIGURE 58


STEP 4
FIGURE 60


STEP 6
FIGURE 62


FIGURE 63. MANUAL OVERRIDE

### 8.4.1.2. Placing the SECTOR II into position



STEP 1

FIGURE 64


STEP 2
FIGURE 65

### 8.4.2. Seperately-placed CLAWS and SECTOR II

### 8.4.2.1. Running the conduit from the gearbox to the SECTOR II

## STEP 1

Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.


STEP 2


STEP 3


STEP 4


STEP 6
FIGURE 70


STEP 5
FIGURE 69


STEP 7

## STEP 8

Route the CLAWS and Proximity sensor cables in the conduit to the SECTOR II.

## STEP 9

Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

### 8.4.2.2. Placing the gearbox cover into position



STEP 1


STEP 2

FIGURE 73


STEP 3


FIGURE 75. MANUAL OVERRIDE

П
By removing the M12x20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.

### 8.4.2.3. Placing the SECTOR II into position



STEP 1


STEP 2
FIGURE 77
8.4.3. Fitting the relay enclosure and its bracket


STEP 1


STEP 2
FIGURE 79


STEP 1

FIGURE 80

Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 17).

Complete the installation of the SECTOR II as per its full installation manual.
8.4.5. Fitting the CLAWS controller to the SECTOR II


STEP 1

STEP 2
Keeping the CLAWS Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.


FIGURE 82


FIGURE 83
The bracket can be moved into a set angle of $70^{\circ}$ by pivoting it upward from the
 bottom for better viewing of the LCD screen (Section 8, Figure 84).

It can also be moved lower down for optimum space when working on the gearbox (Section 8, Figure 85).

Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 8, Figure 82).


FIGURE 84. CLAWS CONTROLLER AND BRACKET AT FIXED $70^{\circ}$ POSITION


FIGURE 85. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION


FIGURE 86. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET
STEP 3
Connect harness and power supply. Refer to the wiring diagrams and controller settings.

## 9. RHS Surface Mount - Opposing Direction of Travel

### 9.1. Preparing the Drive Linkage Assembly



STEP 1


STEP 3


STEP 5

FIGURE 3

## STEP 4



FIGURE 6


STEP 7
FIGURE 7


STEP 8
FIGURE 8

$\square$
The drive linkage arm should point to a 5 o'clock position and the holes of the gearbox shaft and the linkage arm must line up as shown above.


STEP 9


FIGURE 10


Tighten the Countersunk M8x40 screw to 20Nm (Section 9, Figure 9).

### 9.2. Spike Module Assembly

9.2.1. Preparing the Spike Model assembly(ies) for installation


STEP 1


STEP 3
FIGURE 13


STEP 4
FIGURE 14

### 9.2.2. Attaching the Driven Link to the first spike module

D
Place the spikes into the down position to aid in the fitment of all the shaft couplings.


STEP 1
FIGURE 15


STEP 2
FIGURE 16
$\square$ Ensure the Driven Link and the spikes are pointing in the same direction. (Section 9, Figures 16 to 19).


STEP 3


STEP 4


FIGURE 19
9.2.3. Aligning the Driven Linkage Arm to the Drive Linkage Arm.


### 9.2.4. Attaching the drive linkage assembly to the spike module

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the

ㅁspike module assembly. Ensure that the Sandwich Plate is lifted over the Driven Linkage Arm, so that the Driven Linkage Arm sits flush with the Drive Linkage Arm (Section 9, Figure 21).


STEP 1

STEP 2
FIGURE 22


STEP 3
FIGURE 23

Using six M12x25 bolts, fix one spike module to another (Section 9, Figure 24).


I
To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

### 9.2.5. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

ㅁ
It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.


FIGURE 25. SHAFT COUPLER


FIGURE 26

a
Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.


STEP 1
FIGURE 27



STEP 2
FIGURE 28


STEP 4
FIGURE 30

## STEP 7

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.


### 9.2.6. Bolting down the assembly to the ground

If the SECTOR II and CLAWS are to be seperated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. (Section 9.4.2.) These must be done before bolting the assembly to the ground. Once this preparation work has been completed, proceed with the installation below.


FIGURE 33

A
It is crucial that the surface it's mounted on is a reasonably even surface as an uneven surface could result in an uneven binding of the spike shafts. This will result in premature failure.

### 9.2.5. Proximity sensor installation



STEP 1
FIGURE 34

$\square$The length of the PVC conduit will be relative to the length of the spike modules and drive linkage unit combined. Ensure that a further 38 mm is added to this to account for the modules and coupling (Refer to Section 9, Figure 35).


FIGURE 35

a
Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.


STEP 2


STEP 3

FIGURE 37

日
Steps 4-7 is only applicable if the SECTOR II will be mounted directly onto the CLAWS Gearbox. If they are going to be mounted seperately, a trench for the conduit and proximity sensor cable will need to be dug (Section 9.4.2.).


STEP 4


STEP 6


STEP 5
FIGURE 39


STEP 7
FIGURE 41

Please ensure that the moving mechanical parts do not rub against the conduit or cables.


FIGURE 42. PROXIMITY SENSOR


FIGURE 44. PROXIMITY SENSOR


FIGURE 43. PROXIMITY SENSOR


STEP 8
FIGURE 45


FIGURE 46
There should be ample cable left over on the drive linkage end, as the wiring will need to be routed to the SECTOR II at a later stage.


STEP 9


STEP 10
FIGURE 48

### 8.3. Re-assembling the ramp plates and linkage cover



STEP 1

FIGURE 49


STEP 2
FIGURE 50

ㅁ
Leave out the four M8 screws and Spring Washers on the far end of the assembly as the module end cover will be assembled later.


STEP 3
FIGURE 51


Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.


STEP 4
FIGURE 52


STEP 6


STEP 8
FIGURE 56


STEP 5
FIGURE 53


STEP 7
FIGURE 55

### 9.4. Integrating the SECTOR II with the CLAWS

9.4.1. Directly mount THE SECTOR II onto the Independent Drive

### 9.4.1.1. Placing the gearbox cover into position



STEP 1


STEP 3
FIGURE 59


STEP 5
FIGURE 57

FIGURE 61


STEP 2
FIGURE 58


STEP 4
FIGURE 60


STEP 6

FIGURE 62


FIGURE 63. MANUAL OVERRIDE

### 9.4.1.2. Placing the SECTOR II into position



STEP 1

FIGURE 64

### 9.4.2. Seperately-placed CLAWS and SECTOR II

### 9.4.2.1. Running the conduit from the gearbox to the SECTOR II

## STEP 1

Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.


STEP 2

FIGURE 66


STEP 3


STEP 6
FIGURE 70


STEP 5
FIGURE 69


STEP 7

## STEP 8

Route the CLAWS and Proximity sensor cables in the conduit to the SECTOR II.

## STEP 9

Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

### 9.4.2.2. Placing the gearbox cover into position



STEP 1

FIGURE 72


STEP 2

FIGURE 73


STEP 3


FIGURE 75. MANUAL OVERRIDE


By removing the $M 12 \times 20$ screw and placing an allen key through the hole, the gearbox release screw can be loosened.

### 9.4.2.3. Placing the SECTOR II into position



STEP 1
FIGURE 76


STEP 2
FIGURE 77
9.4.3. Fitting the relay enclosure and its bracket


STEP 1


STEP 2
FIGURE 79


Route the excess wire from the proximity sensor, and wire it
to the relay by referring to the wiring diagram (Section 17).

Complete the installation of the SECTOR II as per its full installation manual.

### 8.4.5. Fitting the CLAWS controller to the SECTOR II



STEP 1

## STEP 2

Keeping the CLAWS Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.


FIGURE 82


FIGURE 83
The bracket can be moved into a set angle of $70^{\circ}$ by pivoting it upward from the
 bottom for better viewing of the LCD screen (Section 9, Figure 84).

It can also be moved lower down for optimum space when working on the gearbox (Section 9, Figure 85).

Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 9, Figure 82).


FIGURE 84. CLAWS CONTROLLER AND BRACKET AT FIXED $70^{\circ}$ POSITION


FIGURE 85. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION


FIGURE 86. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET
STEP 3
Connect harness and power supply. Refer to the wiring diagrams and controller settings.

# INDEPENDENT DRIVE FLUSH MOUNT INSTALLATIONS 

## cabws



## 10. Product Identification



FIGURE 1. PRODUCT IDENTIFICATION

1. Boom pole
2. Spikes module assembly
3. Trench cover plate
4. Spikes
5. Drive linkage assembly
6. SECTOR II
Module Frame
Linkage Frame
Top Coupler
Bottom Coupler
$8 \times 20$ Dowel Pin

| Bearing Housing |
| :--- |
| Hold Down Bracket Coupler |
| Blanking Plate |
| Gearbox Cover |

## 11. Tools Required

- $13 \mathrm{~mm}, 17 \mathrm{~mm}$, and 19 mm Spanners
- Ratchet
- 19 mm , and 24 mm Sockets
- Allen Key Set
- 20mm and 50mm Hole Saw
- Mallet
- Tape Measure
- Spirit Level
- Torque Wrench
- Conduit Spring for 20 mm conduit


## 12. Introduction

This document describes the basic steps to follow when installing the flush-mountable CLAWS Spikes driven directly from a SECTOR II Barrier by a "push-pull" linkage system. The installation described in this document is a 2.5 meter installation which utilises modules of 1.5 and 1.0 meters.


The installation of the CLAWS Spikes requires a minimum of two persons.

### 12.1. Installation Configurations

The flush-mountable CLAWS Spikes can be installed in four different configurations. The configuration is dependent on two factors:

- Orientation of installation
- Direction of spike impact


### 12.1.1. Orientation of Installation

The orientation of installation is described as the side at which the drive linkage is installed when approaching the CLAWS Spikes. In other words, when driving up to the CLAWS Spikes, in the correct direction for traffic flow, and the drive is installed on the right-hand side of the vehicle, it's deemed a right-hand installation. And when driving up to the CLAWS Spikes, in the correct direction for traffic flow, and the drive is installed on the left-hand side of the vehicle, it's deemed a left-hand installation.


FIGURE 2. RHS CONFIGURATION


FIGURE 3. LHS CONFIGURATION

### 12.1.2. Spike Impact Direction

The CLAWS Spikes are designed to take a much larger or more frequent impact in one direction. The spikes can be installed to face either towards oncoming traffic (similar) or face towards traffic (opposing) trying to enter from the wrong direction or lane.


FIGURE 4. SPIKE IMPACT DIRECTION - SIMILAR


FIGURE 5. SPIKE IMPACT DIRECTION - OPPOSING

There are four types of typical installations. Refer to Section 11, Figures 2 and 3 to determine if the installation is left- or right-hand orientated.
Secondly; pay attention to the spike impact direction:

- Similar direction of travel prevents vehicles from exiting whilst the boom pole is still down (Normal direction of traffic)
- Opposing direction of travel prevents vehicles entering against the flow of traffic whilst the boom pole is down


FIGURE 6. RHS SIMILAR DIRECTION OF TRAVEL


FIGURE 7. RHS OPPOSED DIRECTION OF TRAVEL


FIGURE 8. LHS SIMILAR DIRECTION OF TRAVEL


FIGURE 9. LHS OPPOSED DIRECTION OF TRAVEL

## 13. RHS Flush Mount - Similar Direction of Travel

### 13.1. Preparing the Drive Linkage Assembly



Note the orientation of the gearbox coupler notch is at the 9 o'clock position and that the gearbox drive arm is up as shown in Section 13, Figure 14.

### 13.2. Spike Module Assembly

### 13.2.1. Preparing the Spike Module assembly(ies) for installation


13.2.2. Attaching the drive linkage assembly to the spike module


STEP 1


STEP 2

FIGURE 19

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly.

## STEP 3

Using six M12x25 bolts, fix one spike module to another (Section 13, Figure 20).


FIGURE 20

S
To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

### 13.2.3. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

ㅁ
It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.


FIGURE 21. SHAFT COUPLER
FIGURE 22

a
Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.


## STEP 1

FIGURE 23


STEP 3
FIGURE 25


STEP 2
FIGURE 24


STEP 4

FIGURE 26

## STEP 5

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.


STEP 6
FIGURE 27


STEP 7
FIGURE 28


FIGURE 29. CORRECTLY ALIGNED SPIKE AND DRIVE MODULES

### 13.2.4. Proximity sensor installation



STEP 1
FIGURE 30

ㅁ
The length of the PVC conduit will be relative to the length of the spike modules combined. Ensure that a further 38 mm is added to this to account for the modules and coupling (Refer to Section 13, Figure 31).


FIGURE 31

D
Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.


STEP 2


STEP 3

FIGURE 33

■
It is necessary to bend PVC conduit to circumvent the gearbox bulkhead to continue. The use of a conduit spring is recommended to avoid collapsing the pipe. Section 13, Figure 34 below is a guideline that can be used to achieve this.


STEP 4
FIGURE 34
STEP 5
Connect the bent piece of conduit to the PVC coupler installed in Section 13, Figure 33 Step 3. After it is connected, it should resemble Section 13, Figure 35.


FIGURE 35

$\square$
Steps 6-9 is only applicable if the SECTOR II will be mounted directly onto the CLAWS Gearbox. If they are going to be mounted seperately, a trench for the conduit and cables will need to be dug (Refer to Section 13.5.2.).


STEP 6


STEP 8
FIGURE 38


STEP 7
FIGURE 37


STEP 9

FIGURE 39


Please ensure that the moving mechanical parts do not rub against the conduit or cables.


FIGURE 40. PROXIMITY SENSOR


FIGURE 41. PROXIMITY SENSOR


FIGURE 42. PROXIMITY SENSOR


STEP 6
FIGURE 43


FIGURE 44


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed up the SECTOR II at a later stage.


STEP 7


STEP 8
FIGURE 46

### 13.2.5. Attaching the End Covers to the Assembly

### 13.2.5.1. Attaching the Module End cover



STEP 1

### 13.2.5.2. Attaching the Linkage Unit End cover



STEP 1

FIGURE 49


STEP 2

### 13.3. Preparing the Trench and Drainage System



STEP 1
FIGURE 51
Drainage pipes must be laid at one or both ends of the trench to allow water
 to flow either into storm water drains or into any other area away from the installation. Section 13, Figure 52 shows two recommended drainage configurations. Once complete, hold the draining pipes in place by pouring a 100 mm concrete foundation and level off.

If the SECTOR II and CLAWS are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. This must be done before any concrete is poured (Section 13.5.2.).


STEP 2
FIGURE 52
Make sure the drain pipes do not interfere with the structure when it is in the trench.

### 13.3.1. Concreting the Assembly into the Trench.

官
Ensure that the drain pipes will not interfere with the structure when it is placed in the trench.

Place the assembly in the trench and level the assembly using any type of propping or jacking method. Make sure that the top of the assembly is either in line with or a little higher than the ground level and pour concrete (minimum 45MPa after 28 days) into the cavity that remains.

A
Do not pour any concrete into the gutter of the spikes module or drive link assembly.


STEP 3
FIGURE 53


### 13.4. Re-assembling the trench plates



STEP 1
FIGURE 55
Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.


STEP 2
FIGURE 56

### 13.5. Integrating the SECTOR II with the CLAWS

13.5.1. Directly mount THE SECTOR II onto the Independent Drive
13.5.1.1. Placing the gearbox cover into position



FIGURE 63. MANUAL OVERRIDE
13.5.1.2. Placing the SECTOR II into position


STEP 1
FIGURE 65

### 13.5.2. Seperately-placed CLAWS and SECTOR II

### 13.5.2.1. Running the conduit from the gearbox to the SECTOR II

## STEP 1

Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.

$\square$
Drill a 20 mm hole through the gutter plate using a 20 mm hole saw for the proximity sensor conduit


STEP 2
FIGURE 66


FIGURE 68


STEP 3
FIGURE 67



STEP 6

FIGURE 70


STEP 7

FIGURE 71

## STEP 8

Route the CLAWS and Proximity sensor cables in the conduit to the SECTOR II.

## STEP 9

Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

### 13.5.2.2. Placing the gearbox cover into position



STEP 3



FIGURE 75. MANUAL OVERRIDE
By removing the M12×20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.
13.5.2.3. Placing the SECTOR II into position


STEP 1


STEP 2
FIGURE 77

### 13.5.3. Fitting the relay enclosure and its bracket



STEP 1

FIGURE 78


13.5.4. Fitting the CLAWS controller to the SECTOR II


STEP 1
FIGURE 81

## STEP 2

Keeping the CLAWS Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.


FIGURE 82


FIGURE 83
The bracket can be moved into a set angle of $70^{\circ}$ by pivoting it upward from the
 bottom for better viewing of the LCD screen (Section 13, Figure 84).

It can also be moved lower down for optimum space when working on the gearbox (Section 13, Figure 85).

Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 13, Figure 82).


FIGURE 84. CLAWS CONTROLLER AND BRACKET AT FIXED $70^{\circ}$ POSITION


FIGURE 85. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION


FIGURE 86. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET
STEP 3
Connect harness and power supply. Refer to the wiring diagrams and controller settings.

## 14. RHS Flush Mount - Opposing Direction of Travel

### 14.1. Preparing the Drive Linkage Assembly



STEP 1


STEP 3


STEP 5
FIGURE 5


STEP 2
FIGURE 2


STEP 4
FIGURE 4


STEP 6

FIGURE 6

Note the orientation of the gearbox coupler notch is at the 3 o'clock position and that the gearbox drive arm is down as shown in Section 14, Figure 5.

### 14.2. Spike Module Assembly

### 14.2.1. Preparing the Spike Module assembly(ies) for installation



STEP 1


STEP 2
14.2.2. Attaching the drive linkage assembly to the spike module


STEP 1


STEP 2
FIGURE 10

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly.

## STEP 3

Using six M12x25 bolts, fix one spike module to another (Section 14, Figure 11).


FIGURE 11

S
To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

### 14.2.3. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

$\square$
It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.


FIGURE 12. SHAFT COUPLER
FIGURE 13

a
Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.


## STEP 1

FIGURE 14


STEP 3
FIGURE 16


STEP 2
FIGURE 15


STEP 4
FIGURE 17

## STEP 5

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.


STEP 6
FIGURE 18


STEP 7
FIGURE 19


FIGURE 20. CORRECTLY ALIGNED SPIKE AND DRIVE MODULES

### 14.2.4. Proximity sensor installation



STEP 1
FIGURE 21

口
The length of the PVC conduit will be relative to the length of the spike modules combined. Ensure that a further 38 mm is added to this to account for the modules and coupling (Refer to Section 14, Figure 22).


I
Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.


## STEP 2

FIGURE 23
$\square$ It is necessary to bend PVC conduit to circumvent the gearbox bulkhead to continue. The use of a conduit spring is recommended to avoid collapsing the pipe. Section 14, Figure 25 below is a guideline that can be used to achieve this.


STEP 4
FIGURE 25

## STEP 5

Connect the bent piece of conduit to the PVC coupler installed in Section 14, Figure 24 Step 3. After it is connected, it should resemble Section 14, Figure 26.


■
Steps 6-9 is only applicable if the SECTOR II will be mounted directly onto the CLAWS Gearbox. If they are going to be mounted seperately, a trench for the conduit and cables will need to be dug (Refer to Section 14.5.2.).


STEP 6
FIGURE 27


STEP 7


Please ensure that the moving mechanical parts do not rub against the conduit or cables.


FIGURE 29. PROXIMITY SENSOR


FIGURE 31. PROXIMITY SENSOR


FIGURE 30. PROXIMITY SENSOR


STEP 6


FIGURE 33


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed up the SECTOR II at a later stage.


STEP 7
FIGURE 34


STEP 8
FIGURE 35

### 14.2.5. Attaching the End Covers to the Assembly

### 14.2.5.1. Attaching the Module End cover


14.2.5.2. Attaching the Linkage Unit End cover


STEP 1

FIGURE 38


STEP 2

### 14.3. Preparing the Trench and Drainage System



STEP 1
FIGURE 40
Drainage pipes must be laid at one or both ends of the trench to allow water

ㅁto flow either into storm water drains or into any other area away from the installation. Section 14, Figure 41 shows two recommended drainage configurations. Once complete, hold the drainage pipes in place by pouring a 100 mm concrete foundation and level off.


If the SECTOR II and CLAWS are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. This must be done before any concrete is poured (Section 14.5.2.).


STEP 2
FIGURE 41

Make sure the drain pipes do not interfere with the structure when it is in the trench.

### 14.3.1. Concreting the Assembly into the Trench.

$\square$
Ensure that the drain pipes will not interfere with the structure when it is placed in the trench.

Place the assembly in the trench and level the assembly using any type of propping or jacking method. Make sure that the top of the assembly is either in line with or a little higher than the ground level and pour concrete (minimum 45MPa after 28 days) into the cavity that remains.

A
Do not pour any concrete into the gutter of the spikes module or drive link assembly.


STEP 3
FIGURE 42


### 14.4. Re-assembling the trench plates



STEP 1
FIGURE 44

ㅁ
Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.


STEP 2
FIGURE 45

### 14.5. Integrating the SECTOR II with the CLAWS

14.5.1. Directly mount THE SECTOR II onto the Independent Drive
14.5.1.1. Placing the gearbox cover into position


STEP 1



STEP 2
FIGURE 47



STEP 5


STEP 6
FIGURE 51


FIGURE 52. MANUAL OVERRIDE

### 14.5.1.2. Placing the SECTOR II into position



### 14.5.2. Seperately-placed CLAWS and SECTOR II

### 14.5.2.1. Running the conduit from the gearbox to the SECTOR II

## STEP 1

Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.
$\square$ Drill a 20 mm hole through the gutter plate using a 20 mm hole saw for the proximity sensor conduit


STEP 2
FIGURE 55


STEP 4

FIGURE 57


STEP 3
FIGURE 56


STEP 5
FIGURE 58


STEP 6

FIGURE 59


STEP 7

FIGURE 60

## STEP 8

Route the CLAWS and Proximity sensor cables in the conduit to the SECTOR II.

## STEP 9

Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

### 14.5.2.2. Placing the gearbox cover into position





FIGURE 64. MANUAL OVERRIDE
By removing the M12×20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.
14.5.2.3. Placing the SECTOR II into position


STEP 1
FIGURE 65


STEP 2

### 14.5.3. Fitting the relay enclosure and its bracket



STEP 1

FIGURE 67



Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 17).

Complete the installation of the SECTOR II as per its full installation manual.
14.5.4. Fitting the CLAWS controller to the SECTOR II


STEP 1
FIGURE 69

## STEP 2

Keeping the CLAWS Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.


FIGURE 70


FIGURE 71
The bracket can be moved into a set angle of $70^{\circ}$ by pivoting it upward from the
 bottom for better viewing of the LCD screen (Section 14, Figure 72).

It can also be moved lower down for optimum space when working on the gearbox (Section 14, Figure 73).

Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 14, Figure 70).


FIGURE 72. CLAWS CONTROLLER AND BRACKET AT FIXED $70^{\circ}$ POSITION


FIGURE 73. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION


FIGURE 74. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET
STEP 3
Connect harness and power supply. Refer to the wiring diagrams and controller settings.

## 15. LHS Flush Mount - Similar Direction of Travel

### 15.1. Preparing the Drive Linkage Assembly



STEP 1


STEP 3
FIGURE 3


STEP 5


STEP 2
FIGURE 2


STEP 4
FIGURE 4


STEP 6

FIGURE 6

Note the orientation of the gearbox coupler notch is at the 3 o'clock position and that the gearbox drive arm is down as shown in Section 15, Figure 5.

### 15.2. Spike Module Assembly

15.2.1. Preparing the Spike Module assembly(ies) for installation


STEP 1


STEP 2
15.2.2. Attaching the drive linkage assembly to the spike module


STEP 1
FIGURE 9


STEP 2

FIGURE 10

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly.

## STEP 3

Using six M12x25 bolts, fix one spike module to another (Section 15, Figure 11).


FIGURE 11

ロ
To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

### 15.2.3. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

ㅁ
It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.


FIGURE 12. SHAFT COUPLER


FIGURE 13

a
Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.


## STEP 1

FIGURE 14


STEP 3
FIGURE 16


STEP 2
FIGURE 15


STEP 4
FIGURE 17

## STEP 5

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.


STEP 6
FIGURE 18


STEP 7
FIGURE 19


FIGURE 20. CORRECTLY ALIGNED SPIKE AND DRIVE MODULES
15.2.4. Proximity sensor installation


STEP 1

ㅁ
The length of the PVC conduit will be relative to the length of the spike modules combined. Ensure that a further 38 mm is added to this to account for the modules and coupling (Refer to Section 15, Figure 22).


FIGURE 22

D
Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.


STEP 2


STEP 3

ㅁ
It is necessary to bend PVC conduit to circumvent the gearbox bulkhead to continue. The use of a conduit spring is recommended to avoid collapsing the pipe. Section 15, Figure 25 below is a guideline that can be used to achieve this.


STEP 4
FIGURE 25

## STEP 5

Connect the bent piece of conduit to the PVC coupler installed in Section 14, Figure 24 Step 3. After it is connected, it should resemble Section 15, Figure 26.


FIGURE 26

Steps 6-7 is only applicable if the SECTOR II will be mounted directly onto the CLAWS Gearbox. If they are going to be mounted seperately, a trench for the conduit and cables will need to be dug (Refer to Section 15.5.2.).


STEP 6
FIGURE 27


STEP 7

FIGURE 28


Please ensure that the moving mechanical parts do not rub against the conduit or cables.


FIGURE 29. PROXIMITY SENSOR


FIGURE 30. PROXIMITY SENSOR


FIGURE 31. PROXIMITY SENSOR


STEP 6
FIGURE 32


FIGURE 33


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed up the SECTOR II at a later stage.


STEP 7


STEP 8

### 15.2.5. Attaching the End Covers to the Assembly

### 15.2.5.1. Attaching the Module End cover



STEP 1


STEP 2
FIGURE 37
15.2.5.2. Attaching the Linkage Unit End cover


STEP 1
FIGURE 38


STEP 2
FIGURE 39

### 15.3. Preparing the Trench and Drainage System



STEP 1
FIGURE 40
Drainage pipes must be laid at one or both ends of the trench to allow water
 to flow either into storm water drains or into any other area away from the installation. Section 15, Figure 41 shows two recommended drainage configurations. Once complete, hold thedrainage pipes in place by pouring a 100 mm concrete foundation and level off.


If the SECTOR II and CLAWS are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. This must be done before any concrete is poured (Section 15.5.2.).


STEP 2
FIGURE 41

Make sure the drain pipes do not interfere with the structure when it is in the trench.

### 14.3.1. Concreting the Assembly into the Trench.

$\square$
Ensure that the drain pipes will not interfere with the structure when it is placed in the trench.

Place the assembly in the trench and level the assembly using any type of propping or jacking method. Make sure that the top of the assembly is either in line with or a little higher than the ground level and pour concrete (minimum 45MPa after 28 days) into the cavity that remains.

A
Do not pour any concrete into the gutter of the spikes module or drive link assembly.


STEP 3


### 15.4. Re-assembling the trench plates



STEP 1
FIGURE 44

Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.


STEP 2
FIGURE 45

### 15.5. Integrating the SECTOR II with the CLAWS

15.5.1. Directly mount THE SECTOR II onto the Independent Drive
15.5.1.1. Placing the gearbox cover into position


STEP 1


STEP 3
FIGURE 48


STEP 5
FIGURE 46

FIGURE 50


STEP 2
FIGURE 47


STEP 4


STEP 6
FIGURE 51


FIGURE 52. MANUAL OVERRIDE

### 15.5.1.2. Placing the SECTOR II into position



STEP 1
FIGURE 53
STEP 2
FIGURE 54

### 15.5.2. Seperately-placed CLAWS and SECTOR II

### 15.5.2.1. Running the conduit from the gearbox to the SECTOR II

## STEP 1

Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.
$\square$ Drill a 20 mm hole through the gutter plate using a 20 mm hole saw for the proximity sensor conduit


STEP 2
FIGURE 55


FIGURE 57


STEP 3
FIGURE 56


STEP 5
FIGURE 58


STEP 6

FIGURE 59


STEP 7
FIGURE 60

## STEP 8

Route the CLAWS and Proximity sensor cables in the conduit to the SECTOR II.

## STEP 9

Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

### 15.5.2.2. Placing the gearbox cover into position



STEP 1
FIGURE 61



STEP 2


FIGURE 64. MANUAL OVERRIDE

$\square$By removing the M12×20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.
15.5.2.3. Placing the SECTOR II into position


STEP 1
FIGURE 65


STEP 2
FIGURE 66

### 15.5.3. Fitting the relay enclosure and its bracket



STEP 1

FIGURE 67



STEP 3

FIGURE 69

Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 17).

Complete the installation of the SECTOR II as per its full installation manual.
15.5.5. Fitting the CLAWS controller to the SECTOR II


STEP 1
FIGURE 70

## STEP 2

Keeping the CLAWS Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.


FIGURE 71


FIGURE 72
The bracket can be moved into a set angle of $70^{\circ}$ by pivoting it upward from the bottom for better viewing of the LCD screen (Section 15, Figure 73).

It can also be moved lower down for optimum space when working on the gearbox (Section 15, Figure 74).

Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 15, Figure 71).


FIGURE 73. CLAWS CONTROLLER AND BRACKET AT FIXED $70^{\circ}$ POSITION


FIGURE 74. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION


FIGURE 75. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET
STEP 3
Connect harness and power supply. Refer to the wiring diagrams and controller settings.

## 16. LHS Flush Mount - Opposing Direction of Travel

### 16.1. Preparing the Drive Linkage Assembly



STEP 1
FIGURE 1


STEP 3
FIGURE 3


STEP 5


STEP 2
FIGURE 2


STEP 4
FIGURE 4


STEP 6

FIGURE 6

Note the orientation of the gearbox coupler notch is at the 9 o'clock position and that the gearbox drive arm is up as shown in Section 16, Figure 5.

### 16.2. Spike Module Assembly

### 16.2.1. Preparing the Spike Module assembly(ies) for installation



STEP 1
FIGURE 7


STEP 2
16.2.2. Attaching the drive linkage assembly to the spike module


STEP 1
FIGURE 9


STEP 2

FIGURE 10

Take note of the orientation of the Sandwich Plate to the Linkage Assembly before fixing them to the spike module assembly.

## STEP 3

Using six M12x25 bolts, fix one spike module to another (Section 16, Figure 11).


FIGURE 11

- 

To assist with the alignment and adjustment of the shafts, loosen (but do not remove) the bolts on all of the bearing housings.

### 16.2.3. Assembling the shaft couplings

The coupler is used to connect and align the shafts together.

ㅁ
It is essential that the coupler is assembled correctly; failing to do so will result in slipping of the spikes which is undesirable.


FIGURE 12. SHAFT COUPLER
FIGURE 13

a
Place the spikes into the down position (and the drive arm pointing upwards) to aid in the fitment of all the shaft couplings.


## STEP 1

FIGURE 14


STEP 3
FIGURE 16


STEP 2
FIGURE 15


STEP 4
FIGURE 17

## STEP 5

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.


STEP 6
FIGURE 18


STEP 7
FIGURE 19


FIGURE 20. CORRECTLY ALIGNED SPIKE AND DRIVE MODULES

## STEP 7

Repeat this coupling process for additional spike modules. Once all shafts have been coupled, check that they move freely.
16.2.4. Proximity sensor installation


STEP 1
FIGURE 21

$\square$
The length of the PVC conduit will be relative to the length of the spike modules combined. Ensure that a further 38 mm is added to this to account for the modules and coupling (Refer to Section 16, Figure 22).


FIGURE 22

D
Use an appropriate PVC adhesive to bond all conduit lengths, access elbows and couplers to one another.


STEP 2


FIGURE 24

ㅁ
It is necessary to bend PVC conduit to circumvent the gearbox bulkhead to continue. The use of a conduit spring is recommended to avoid collapsing the pipe. Section 16, Figure 25 below is a guideline that can be used to achieve this.


STEP 4
FIGURE 25

## STEP 5

Connect the bent piece of conduit to the PVC coupler installed in Section 16, Figure 24 Step 3. After it is connected, it should resemble Section 16, Figure 26.


FIGURE 26

I
Steps 6-9 is only applicable if the SECTOR II will be mounted directly onto the CLAWS Gearbox. If they are going to be mounted seperately, a trench for the conduit and cables will need to be dug (Refer to Section 16.5.2.).


STEP 6


STEP 8
FIGURE 29


STEP 7


STEP 9

FIGURE 30


Please ensure that the moving mechanical parts do not rub against the conduit or cables.


FIGURE 31. PROXIMITY SENSOR


FIGURE 32. PROXIMITY SENSOR


FIGURE 33. PROXIMITY SENSOR


STEP 6
FIGURE 34


FIGURE 35


There should be ample cable left over on the drive linkage end, as the wiring will need to be routed up the SECTOR II at a later stage.


STEP 7


STEP 8
FIGURE 37

### 16.2.5. Attaching the End Covers to the Assembly

### 16.2.5.1. Attaching the Module End cover



STEP 1

FIGURE 38


STEP 2

### 16.2.5.2. Attaching the Linkage Unit End cover



STEP 1


STEP 2
FIGURE 41

### 16.3. Preparing the Trench and Drainage System



STEP 1
FIGURE 42
Drainage pipes must be laid at one or both ends of the trench to allow water
 to flow either into storm water drains or into any other area away from the installation. Section 16, Figure 43 shows two recommended drainage configurations. Once complete, hold the drainage pipes in place by pouring a 100 mm concrete foundation and level off.


If the SECTOR II and CLAWS are to be separated, a trench for the conduit and cables will need to be dug, and the wiring harnesses will need to be extended in relation to the distance between the gearbox and SECTOR II. This must be done before any concrete is poured (Section 16.5.2.).


STEP 2
FIGURE 43

Make sure the drain pipes do not interfere with the structure when it is in the trench.

### 16.3.1. Concreting the Assembly into the Trench.

官
Ensure that the drain pipes will not interfere with the structure when it is placed in the trench.

Place the assembly in the trench and level the assembly using any type of propping or jacking method. Make sure that the top of the assembly is either in line with or a little higher than the ground level and pour concrete (minimum 45MPa after 28 days) into the cavity that remains.


Do not pour any concrete into the gutter of the spikes module or drive link assembly.


STEP 3
FIGURE 44


### 16.4. Re-assembling the trench plates



STEP 1
FIGURE 46


Take note of the slot orientation in the trench cover plates before it is placed back into position. The spike must rest on the straight edge of the slot when it is in its upright position.


STEP 2
FIGURE 47

### 16.5. Integrating the SECTOR II with the CLAWS

16.5.1. Directly mount THE SECTOR II onto the Independent Drive
15.5.1.1. Placing the gearbox cover into position


STEP 1


STEP 3
FIGURE 50


STEP 5
FIGURE 48


STEP 2
FIGURE 49


STEP 4
FIGURE 51


STEP 6
FIGURE 53


FIGURE 54. MANUAL OVERRIDE

### 16.5.1.2. Placing the SECTOR II into position



STEP 1


STEP 2
FIGURE 56

### 16.5.2. Seperately-placed CLAWS and SECTOR II

### 16.5.2.1. Running the conduit from the gearbox to the SECTOR II

## STEP 1

Dig a trench for the conduit from the gearbox to the desired position of the SECTOR II.

ㅁ
Drill a 20 mm hole through the gutter plate using a 20 mm hole saw for the proximity sensor conduit


STEP 2

STEP 4
FIGURE 57


FIGURE 59


STEP 3
FIGURE 58


STEP 5
FIGURE 60


STEP 6
FIGURE 61


STEP 7
FIGURE 62

## STEP 8

Route the CLAWS and Proximity sensor cables in the conduit to the SECTOR II.

## STEP 9

Cast a plinth for the SECTOR II according to the SECTOR II installation manual.

### 16.5.2.2. Placing the gearbox cover into position




FIGURE 66. MANUAL OVERRIDE

■
By removing the M12x20 screw and placing an allen key through the hole, the gearbox release screw can be loosened.

### 16.5.2.3. Placing the SECTOR II into position



STEP 1


STEP 2
FIGURE 68

### 16.5.3. Fitting the relay enclosure and its bracket



STEP 1

FIGURE 69



Route the excess wire from the proximity sensor, and wire it to the relay by referring to the wiring diagram (Section 17).

Complete the installation of the SECTOR II as per its full installation manual.
16.5.4. Fitting the CLAWS controller to the SECTOR II


STEP 1
FIGURE 72

## STEP 2

Keeping the CLAWS Controller bracket horizontal, slide the top insulation sleeves into the top slot of the bracket. Ensure that the bottom insulation sleeves line up with the bottom slot of the bracket to follow the slot as the bracket drops to its resting place.


FIGURE 73


FIGURE 74
The bracket can be moved into a set angle of $70^{\circ}$ by pivoting it upward from the bottom for better viewing of the LCD screen (Section 16, Figure 75).

It can also be moved lower down for optimum space when working on the gearbox (Section 16, Figure 76).

Ensure that the bracket is placed in the standard vertical position when done to enable the SECTOR II access door to be closed (Section 16, Figure 73).


FIGURE 75. CLAWS CONTROLLER AND BRACKET AT FIXED $70^{\circ}$ POSITION


FIGURE 76. TEMPORARY CLAWS CONTROLLER AND BRACKET POSITION


FIGURE 77. UNCLIPPING THE CLAWS CONTROLLER FROM ITS BRACKET
STEP 3
Connect harness and power supply. Refer to the wiring diagrams and controller settings.

## 17. Wiring Diagram



FIGURE 78. CONNECTING THE TWO CONTROLLERS

## 18. SECTOR II \& CLAWS Controller Settings

### 18.1. SECTOR II Controller settings


4. Modes of Operation
4.1. Operating mode
(Set to any mode applicable, Simplex (SMX), Complex (CMX) or PLC (PLC))

11. Spikes Mode
11.1. Spike interface
(Set to any mode applicable, Safe (SAF), or Secure (SEC))

### 18.2. CLAWS Controller settings


4. Modes of Operation
4.1. Operating mode
(Set to Spike Mode (SPK))
TABLE 2

## 19. Installation Handover

Once the installation has been successfully completed and tested, it is important to explain the operation and safety requirements of the system to the end-user.

## NEVER ASSUME THE USER KNOWS HOW TO SAFELY OPERATE AUTOMATED ROADWAY SPIKES!

Even if the user has used such a system before, it does not mean he knows how to SAFELY operate it. Make sure that the user fully understands the following safety requirements before finally handing over the site.

The following needs to be understood by the user:

- How to operate the manual override mechanism
(Show them how by demonstration)
- How co-installed safety loops and all other safety features work (Show them how by demonstration)
- All the features and benefits of the spikes
- All the safety considerations associated with operating automated roadway spikes.
The user should be able to pass this knowledge on to all other users of the automated system and must be made aware of this responsibility
- Do not activate the CLAWS unless you can see it and can determine that its area of travel is clear of people, pets, or other obstructions
- NO ONE MAY PASS OVER RAISING SPIKES. Always keep people and objects away from the spikes
- NEVER LET CHILDREN OPERATE OR PLAY WITH THE SPIKE

CONTROLS, and do not allow children or pets near the spike area

- Be careful with moving parts and avoid close proximity to areas where fingers or hands could be pinched
- Secure all easily-accessed spike controls in order to prevent its unauthorised use
- Keep the automated spikes system properly maintained, and ensure that all working areas are free of objects that could affect its operation and safety
- On a monthly basis, check the obstruction detection system and safety devices for correct operation
- All repair and service work to this product must be done
 by a suitably qualified person
- This product was designed and built strictly for the use indicated in this documentation. Any other use, not expressly indicated here, could compromise the good condition/operation of the product and/or be a source of danger!

Neither Centurion Systems (Pty) Ltd, nor its subsidiaries, accepts any liability caused by improper use of the product, or for use other than that for which the automated system was intended.

Ensure that the customer is in possession of the user guide and that you have completed the installation details in the back of the manual.

Notes

Notes

Notes


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